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transposition

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# Quasiconvexity is not invariant under transposition

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### Abstract

An example is given of a quasiconvex  $f : M^{2 \times 3} \rightarrow \mathbb{R}$  such that the transposed function  $\tilde{f} : M^{3 \times 2} \rightarrow \mathbb{R}$  given by  $\tilde{f}(F) = f(F^T)$  is not quasiconvex. For  $\tilde{f}$  one can take Šverák's quartic polynomial that is rank-one convex but not quasiconvex. The proof is closely related to the observation that the map  $v \mapsto v^1 v^2 v^3$  is weakly continuous from  $L^3(\mathbb{R}^3; \mathbb{R}^3)$  into distributions provided that  $A(Pv) = (\partial_2 v^1, \partial_3 v^1, \partial_1 v^2, \partial_3 v^2, \partial_1 v^3, \partial_2 v^3)$  is compact in  $W^{-1,3}(\mathbb{R}^3; \mathbb{R}^6)$ .

## 1 Introduction

Quasiconvexity is the natural notion of convexity for variational problems for multiple integrals

$$I(u) = \int_{\Omega} f(Du) dx, \quad u : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m.$$

In his pioneering work Morrey ([Mo 52], [Mo 66]) showed that weak lower semicontinuity of  $I$  in Sobolev spaces is essentially equivalent to quasiconvexity of the integrand  $f$  (see [AF 84], [Ma 85] for technically nearly optimal statements). An integral  $f : M^{m \times n} \rightarrow \mathbb{R}$  is called quasiconvex if

$$\int_Q f(F + D\varphi) \geq f(F),$$

for all  $F \in M^{m \times n}$  and all Lipschitz functions  $\varphi : \mathbb{R}^m \rightarrow \mathbb{R}^n$  that are periodic with cell  $Q = (0, 1)^n$ . (For the equivalence with other definitions see e.g. [Sv 92]).

Quasiconvexity is still poorly understood, partly because it is a non-local condition. Therefore algebraic sufficient and necessary conditions were introduced. A function  $f$  is rank-1 convex if it is convex on rank-1 lines in  $M^{m \times n}$ , and it is called polyconvex if it can be written as a convex function of the minors. For  $n = 1$  or  $m = 1$  all these notions coincide with ordinary convexity. For  $n \geq 2$ ,  $m \geq 2$  one has the implications ([Mo 52], [Mo 66], [Da 89])

$$f \text{ convex} \not\Rightarrow f \text{ polyconvex} \not\Rightarrow \text{quasiconvex} \Rightarrow f \text{ rank-1 convex}.$$

Šverák [Sv 92] solved a long standing conjecture by showing that rank-1 convexity does not imply quasiconvexity if  $m \geq 3$ ,  $n \geq 2$ . The case  $m = 2$ ,  $n \geq 2$  is open. Šverák's example is reminiscent of a counterexample by Tartar [Ta 79], pp. 185–186, in trilinear compensated compactness.

Rank-1 convexity and polyconvexity are invariant under transposition, i.e. if  $f : M^{m \times n} \rightarrow \mathbb{R}$  does have one of these properties so does  $\tilde{f} : M^{n \times m} \rightarrow \mathbb{R}$  given by

$$\tilde{f}(F) = f(F^T).$$

Alberti thus raised the question whether quasiconvexity is also invariant under transposition. Using Šverák's counterexample Kružík [Kr 97] recently showed that this is not the case if one allows  $f$  to take the value  $\infty$ . Here we refine this analysis and show that Šverák's (finite-valued) functions provide already a counterexample.

**Theorem 1** *There exists a quasiconvex function  $f : M^{2 \times 3} \rightarrow \mathbb{R}$  such that  $\tilde{f}$  is not quasiconvex.*

## 2 Proofs

*Proof.* We will choose  $\tilde{f}$  as in Šverák's counterexample. Let

$$L = \left\{ \begin{pmatrix} r & 0 & t \\ 0 & s & t \end{pmatrix} : r, s, t \in \mathbb{R} \right\} \subset M^{2 \times 3}$$

and let

$$g(F) = -rst \text{ for } F \in L.$$

Denote by  $\pi$  the orthogonal projection onto  $L$  and consider the functions

$$f_{\varepsilon, k}(F) = g(\pi F) + \varepsilon(|F|^2 + |F|^4) + k|F - \pi F|^2, \quad \varepsilon \geq 0, \quad k \geq 0.$$

Šverák showed that for small enough  $\varepsilon > 0$  (and all  $k$ ) the function  $\tilde{f}_{\varepsilon, k}$  is not quasiconvex. Indeed it suffices to note that the periodic map

$$\psi(x) = \frac{1}{2\pi} \begin{pmatrix} \sin 2\pi x^1 \\ \sin 2\pi x^2 \\ \sin 2\pi(x^1 + x^2) \end{pmatrix}$$

satisfies  $(D\psi)^T \in L$  and

$$\int_{(0,1)^2} g(D\psi^T) dx = -\frac{1}{4} < g(0) = 0.$$

Šverák also showed that for any given  $\varepsilon > 0$  the function  $f_{\varepsilon, k}$  is rank-one convex for large enough  $k > k_0(\varepsilon)$ .

We claim that for each  $\varepsilon > 0$  there exists a  $k(\varepsilon)$  such that for  $k \geq k(\varepsilon)$  the function  $f_{\varepsilon, k}$  is quasiconvex. First note that it suffices to show that

$$\int_Q f_{\varepsilon, k}(F + D\varphi) - f_{\varepsilon, k}(F) - Df_{\varepsilon, k}(F)D\varphi \, dx \geq 0, \quad (1)$$

for all  $\varphi \in W^{1, \infty}(T^3; \mathbb{R}^2)$  and all  $F \in M^{2 \times 3}$ , since  $\int_Q D\varphi = 0$ . One easily checks that there exists  $c > 0$  such that

$$|F + G|^4 - |F|^4 - 4|F|^2 F : G \geq c(|F|^2 |G|^2 + |G|^4).$$

Here  $F : G = \sum F_{ij} G_{ij}$ . Indeed, by homogeneity we may assume  $|F| = 1$  (the case  $F = 0$  is trivial), and since the function  $F \mapsto |F|^4$  is strictly convex it suffices to consider the cases  $|G| \rightarrow 0$  or  $|G| \rightarrow \infty$ . The latter is obvious and for the former it suffices to compute the Hessian. Since  $g$  is a polynomial of degree three, expansion of  $g(\pi F + \pi D\varphi)$  yields

$$\begin{aligned} & f_{\varepsilon, k}(F + D\varphi) - f_{\varepsilon, k}(F) - Df_{\varepsilon, k}(F)D\varphi \\ & \geq \frac{1}{2} D^2 g(\pi F)(\pi D\varphi, \pi D\varphi) + g(\pi D\varphi) \\ & \quad + \varepsilon |D\varphi|^2 + c\varepsilon(|F|^2 |D\varphi|^2 + |D\varphi|^4) + k|D\varphi - \pi D\varphi|^2. \end{aligned} \quad (2)$$

Let

$$v^1 = \partial_1 \varphi^1, \quad v^2 = \partial_2 \varphi^2, \quad v^3 = \frac{1}{2} \partial_3 (\varphi^1 + \varphi^2),$$

$$w^1 = \partial_2 \varphi^1, \quad w^2 = \partial_1 \varphi^2, \quad w^3 = \frac{1}{2} \partial_3 (\varphi^1 - \varphi^2)$$

and  $h(v) = v^1 v^2 v^3$ . Then

$$\begin{aligned} \pi D\varphi &= \begin{pmatrix} v^1 & 0 & v^3 \\ 0 & v^2 & v^3 \end{pmatrix}, \quad D\varphi - \pi D\varphi = \begin{pmatrix} 0 & w^1 & w^3 \\ w^2 & 0 & -w^3 \end{pmatrix}, \\ g(\pi D\varphi) &= -h(v). \end{aligned}$$

If  $w = 0$  (i.e.  $D\varphi \in L$ ) then one easily deduces that  $v^1 = v^1(x^1)$ ,  $v^2 = v^2(x^2)$ ,  $v^3 = v^3(x^3)$  and thus  $\int_Q h(v) = 0$  since  $\int_Q v = 0$ . To obtain an estimate for  $\int_Q h(v)$  if  $w \neq 0$  let

$$A(Dv) = (\partial_2 v^1, \partial_3 v^1, \partial_1 v^2, \partial_3 v^2, \partial_1 v^3, \partial_2 v^3).$$

A short calculation shows that  $A(Dv)$  can be expressed as a linear combination of first derivatives of  $w$ . Hence

$$\|A(Dv)\|_{W^{-1,2}(Q)} \leq C \|D\varphi - \pi D\varphi\|_{L^2(Q)}.$$

Application of Lemma 2 below with  $p = q = 2$  yields

$$\begin{aligned} \left| \int_Q g(\pi D\varphi) dx \right| &= \left| \int_Q h(v) dx \right| \\ &\leq C \|D\varphi\|_{L^4}^2 \|D\varphi - \pi D\varphi\|_{L^2} \\ &\leq \frac{\varepsilon C}{4} \|D\varphi\|_{L^4}^4 + \frac{C}{\varepsilon} \|D\varphi - \pi D\varphi\|_{L^2}^2. \end{aligned}$$

Similarly we obtain with  $a = (F_{11}, F_{22}, (F_{31} + F_{32})/2)$

$$\begin{aligned} \left| \int_Q D^2 g(\pi F)(\pi D\varphi, \pi D\varphi) dx \right| &= \left| \int_Q D^2 h(a)(v, v) \right| \\ &\leq C |F| \|D\varphi\|_{L^2} \|D\varphi - \pi D\varphi\|_{L^2} \\ &\leq \frac{\varepsilon C}{4} |F|^2 \|D\varphi\|_{L^2}^2 + \frac{C}{\varepsilon} \|D\varphi - \pi D\varphi\|_{L^2}^2. \end{aligned}$$

In combination with (2) this yields (1), provided that  $k \geq k(\varepsilon) = \frac{2C}{\varepsilon}$ .  $\square$

**Lemma 2.** Consider the function  $h : \mathbb{R}^3 \rightarrow \mathbb{R}$ ,  $h(y) = y_1 y_2 y_3$  and assume that  $v \in W^{1,\infty}(\mathbb{R}^3; \mathbb{R}^3)$  is periodic with cell  $Q = (0, 1)^3$  and  $\int_Q v = 0$ .

Let

$$A(Dv) = (\partial_2 v^1, \partial_3 v^1, \partial_1 v^2, \partial_3 v^2, \partial_1 v^3, \partial_2 v^3)$$

and assume that  $p, q \in (1, \infty)$ ,  $\frac{1}{p} + \frac{1}{q} = 1$ ,  $a \in \mathbb{R}^3$ .

Then

$$\left| \int_Q h(v) dx \right| \leq C(p) \|v\|_{L^{2p}(Q)}^2 \|A(Dv)\|_{W^{-1,q}(Q)} \quad (3)$$

$$\left| \int_Q D^2 h(a)(v, v) dx \right| \leq C(p) |a| \|v\|_{L^p(Q)} \|A(Dv)\|_{W^{-1,q}(Q)}. \quad (4)$$

*Proof.* We split  $v$  into a part  $Qv$  that is controlled by  $A(Dv)$  and a part  $Pv$  whose Fouriertransform is supported near the axes and then show that  $\int_Q h(Pv) = 0$ . Let  $a_1 \in C^\infty(S^2)$  with

$$\begin{aligned} \text{supp } a_1 &\subset \{ \xi \in S^2 : \xi_1^2 \geq 1 - \delta^2 \}, \\ a_1 = 1 &\quad \text{on } \{ \xi \in S^2 : \xi_1^2 \geq 1 - \delta^2/2 \}. \end{aligned}$$

Let  $b_1 = 1 - a_1$ , extend  $a_1$  and  $b_1$  by homogeneity to  $\mathbb{R}^3 \setminus \{0\}$  and define operators  $P_1$  and  $Q_1$  that act on periodic functions with mean zero by

$$P_1 v_1 = \mathcal{F}^{-1}(a_1 \mathcal{F} v_1), \quad Q_1 v_1 = \mathcal{F}^{-1}(b_1 \mathcal{F} v_1),$$

where  $\mathcal{F}$  denotes the discrete Fourier transform, i.e.

$$(\mathcal{F} v_1)(k) = \int_Q v_1 e^{-2\pi i k \cdot x} dx, \quad k \in \mathbb{Z}^3.$$

Note that  $\mathcal{F} v_1(0) = 0$  since  $v_1$  has mean zero. Now  $b_1$  can be written as

$$b_1(\xi) = \frac{\xi_2}{|\xi|} m_2(\xi) + \frac{\xi_3}{|\xi|} m_3(\xi),$$

where

$$m_2(\xi) = \frac{\xi_2 |\xi|}{\xi_2^2 + \xi_3^2} b_1(\xi) \quad \text{and} \quad m_3(\xi) = \frac{\xi_3 |\xi|}{\xi_2^2 + \xi_3^2} b_1(\xi).$$

Standard results on Fourier multipliers (see [SW 71] Cor. 3.16, p. 263) yield

$$\begin{aligned} \|Q_1 v_1\|_q &\leq C(q) \|(\partial_2 v_1, \partial_3 v_1)\|_{-1,q}, \\ \|P_1 v_1\|_p + \|Q_1 v_1\|_p &\leq C(p) \|v_1\|_p. \end{aligned}$$

(Here we used the abbreviations  $\|\cdot\|_p = \|\cdot\|_{L^p(Q)}$  and  $\|\cdot\|_{-1,q} = \|\cdot\|_{W^{-1,q}(Q)}$ ) Analogously we define  $P_2, Q_2, P_3$  and  $Q_3$  and we let

$$Pv = \begin{pmatrix} P_1 v_1 \\ P_2 v_2 \\ P_3 v_3 \end{pmatrix}, \quad Qv = \begin{pmatrix} Q_1 v_1 \\ Q_2 v_2 \\ Q_3 v_3 \end{pmatrix}.$$



Then  $P + Q = id$  and

$$\|Qv\|_q \leq C(q)\|A(Dv)\|_{-1,q}, \quad (5)$$

$$\|Pv\|_p + \|Qv\|_p \leq C(p)\|v\|_p. \quad (6)$$

To prove (3) we expand  $h(v) = h(Pv + Qv)$ . In view of (5) and (6) it suffices to verify that

$$\int_Q h(Pv) = 0. \quad (7)$$

By construction  $\mathcal{F}P_i v_i$  is supported on the cone  $\Lambda_i = \{\xi \in \mathbb{R}^3 : \xi_i^2 \geq (1 - \delta^2)|\xi|^2\}$  and thus

$$\int_Q h(Pv) dx = \sum_{\substack{k^{(i)} \in \Lambda_i \cap \mathbb{Z}^3 \\ k^{(1)} + k^{(2)} + k^{(3)} = 0}} \mathcal{F}(P_1 v_1)(k^{(1)}) \mathcal{F}(P_2 v_2)(k^{(2)}) \mathcal{F}(P_3 v_3)(k^{(3)}).$$

Now the assumptions  $k^{(i)} \in \Lambda_i$  and  $k^{(1)} + k^{(2)} + k^{(3)} = 0$  imply that

$$\begin{aligned} (1 - \delta^2)|k^{(1)}|^2 &\leq |k_1^{(1)}|^2 \leq 2 \left( |k_1^{(2)}|^2 + |k_1^{(3)}|^2 \right) \\ &\leq 2\delta^2 \left( |k^{(2)}|^2 + |k^{(3)}|^2 \right). \end{aligned}$$

Adding to this the two other inequalities obtained by cyclic permutation of the indices we see that

$$(1 - \delta^2) \sum_j |k^{(j)}|^2 \geq 4\delta^2 \sum_j |k^{(j)}|^2.$$

Taking  $\delta < \frac{1}{\sqrt{5}}$  we conclude that  $k^{(1)} = k^{(2)} = k^{(3)} = 0$ . This implies (7) since the  $v_i$  have mean zero, so that  $\mathcal{F}(P_i v_i)(0) = 0$ . Thus (3) is proved and the proof of (4) is similar.  $\square$

### 3 Trilinear compensated compactness

The following consequence of Lemma 2 is not used in the proof of Theorem 1, but provides a nice example in trilinear compensated compactness (see [Ta 79], [Ta 98] for general expositions of compensated compactness). A systematic study of trilinear quantities in the context of  $m \times m$  hyperbolic systems is undertaken in [JMR 95]. In this case the number  $m$  of dependent variables and of constraints is the same, and one can easily check that for  $m \geq 3$  one can only expect good results for differential constraints with variable coefficients that in addition satisfy suitable genericity conditions. In the situation of Lemma 2 there are more differential constraints than dependent variables and less sophisticated methods suffice.

**Corollary 3.** Suppose that

$$\begin{aligned} v_k &\rightharpoonup v \quad \text{in } L^3_{loc}(\mathbb{R}^3; \mathbb{R}^3), \\ A(Dv_k) &\rightarrow A(Dv) \quad \text{in } W^{-1,3}_{loc}(\mathbb{R}^3; \mathbb{R}^3). \end{aligned}$$

Then

$$\begin{aligned} h(v_k) &\rightharpoonup h(v) \quad \text{in } \mathcal{D}'(\mathbb{R}^3), \\ v_k^i v_k^j &\rightharpoonup v^i v^j \quad \text{in } L^{\frac{3}{2}}_{loc}(\mathbb{R}^3), \quad \text{for } i \neq j. \end{aligned}$$

*Proof.* Assume first that  $v = 0$ . In this case it suffices to show that

$$\int_{\mathbb{R}^3} h(v_k) \varphi^3 dx \rightarrow 0 \quad \forall \varphi \in \mathcal{D}(\mathbb{R}^3). \quad (8)$$

Indeed if (8) holds for all  $\varphi \in \mathcal{D}(\mathbb{R}^3)$  it holds by density for all  $\varphi \in C_0^0(\mathbb{R}^3)$  since  $\{h(v_k)\}$  is bounded in  $L^1_{loc}$ . Now every function  $\psi \in \mathcal{D}(\mathbb{R}^3)$  can be written as  $\psi = \varphi^3$  with  $\varphi \in C_0^0(\mathbb{R}^3)$ . To prove (8) we may assume after scaling and translation, that  $\text{supp } \varphi \subset Q = (0, 1)^3$  and we let

$$\bar{v}_k = \int_Q \varphi v_k, \quad \tilde{v}_k = \varphi v_k - \bar{v}_k.$$

Then

$$\begin{aligned} \tilde{v}_k &\rightharpoonup 0 \quad \text{in } L^3(Q), \quad \bar{v}_k \rightarrow 0, \\ A(D\tilde{v}_k) &\rightarrow 0 \quad \text{in } W^{-1,3}(Q). \end{aligned}$$

Lemma 2 implies that

$$\begin{aligned} \int_{\mathbb{R}^3} h(v_k) \varphi^3 dx &= \int_Q h(\varphi v_k) dx \\ &= \int_Q h(\bar{v}_k) + Dh(\bar{v}_k) \tilde{v}_k + \frac{1}{2} D^2 h(\bar{v}_k)(\tilde{v}_k, \tilde{v}_k) + h(\tilde{v}_k) dx \\ &\rightarrow 0, \quad \text{as } k \rightarrow \infty. \end{aligned}$$

This shows that

$$h(v_k) \rightharpoonup 0 \quad \text{in } \mathcal{D}' \quad (9)$$

if  $v = 0$ . Using (4) one shows similarly that

$$v_k^i v_k^j \rightharpoonup 0 \quad \text{in } L^{3/2}_{loc} \quad \text{if } i \neq j. \quad (10)$$

One first obtains convergence in  $\mathcal{D}$  but the  $L^3_{loc}$  bound on  $v_k$  implies weak convergence in  $L^{3/2}_{loc}$ .

Finally if  $v \neq 0$  let  $w_k = v_k - v$ . Expanding  $h(v_k) = h(v + w_k)$  and using (9) and (10) for  $v_k$  we obtain the desired assertion.  $\square$

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