## Max-Planck-Institut für Mathematik <br> in den Naturwissenschaften Leipzig

# Approximation of free-discontinuity problems by elliptic functionals via $\Gamma$-convergence <br> by <br> Emilio Acerbi and Andrea Braides 



# Approximation of free-discontinuity problems by elliptic functionals via $\Gamma$-convergence 

Emilio Acerbi<br>Dipartmento dif Matematica, Università di Parma via D'Azeglio 85a, Parma<br>Andrea Braides<br>SISSA, via Beirut 4, 34014 Trieste, Italy

## 1 Introduction

A variational formulation of some problems in Computer Vision was given by Mumford and Shah [13], and later elaborated by De Giorgi and Ambrosio [9]. In this framework, problems involving the functional

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{2} d x+\mathcal{H}^{1}\left(S_{u}\right) \tag{1}
\end{equation*}
$$

defined on the space $S B V(\Omega)$ of special functions of bounded variation are studied, where $\nabla u$ denotes the approximate gradient of $u$, and $S_{u}$ is the set of the discontinuity points of $u$. The set $S_{u}$ represents the contours of the object in a picture and $u$ is a smoothing of an imput image. Energies of the same form arise in fracture mechanics for brittle solids, where $S_{u}$ is interpreted as the crack surface and $u$ as the displacement outside the fractured region ([4]). Problems involving functionals of this form are usually called free-discontinuity problems, after a terminology introduced by De Giorgi (see [9], [5], [7]).

The Ambrosio and Tortorelli approach [6] provides a variational approximation of the Mumford and Shah functional (1) via elliptic functionals to obtain approximate smooth solutions and overcome the numerical problems due to surface detection. The unknown surface $S_{u}$ is substituted by an additional function variable $v$ which approaches the characteristic of the complement of $S_{u}$. The approximating functionals have the form

$$
\begin{equation*}
\int_{\Omega} v^{2}|\nabla u|^{2} d x+\int_{\Omega}\left(\varepsilon|\nabla v|^{2}+\frac{1}{4 \varepsilon}(1-v)^{2}\right) d x \tag{2}
\end{equation*}
$$

defined on functions $u, v$ such that $u, v \in H^{1}(\Omega)$ and $0 \leq v \leq 1$. The interaction of the terms in the second integral provide an approximate interfacial energy.

The adaptation of the Ambrosio and Tortorelli approximation to obtain as limits more complex surface energies does not seem to follow easily from their approach. A double-limit procedure to obtain non-constant energy densities is described in [1]. In this paper we study a variant of the Ambrosio and Tortorelli construction by considering functionals of the form

$$
\begin{equation*}
G_{\varepsilon}(u, v)=\int_{\Omega} \psi(v)|\nabla u|^{2} d x+\int_{\Omega}\left(\varepsilon|\nabla v|^{2}+\frac{1}{\varepsilon} W(u-v)\right) d x \tag{3}
\end{equation*}
$$

where $W$ and $\psi$ are positive function vanishing only at 0 . In this case the distance between the functions $v$ and $u$ is increasingly penalized as $\varepsilon \rightarrow 0^{+}$, generating in the limit a functional which depends on the traces $u^{ \pm}$of $u$ on both sides of $S_{u}$. We prove (Theorem 3.1) that $G_{\varepsilon}$ approximate the functional

$$
\begin{equation*}
F(u)=\int_{\Omega} \psi(u)|\nabla u|^{2} d x+\int_{S_{u}}\left(\Phi\left(u^{+}\right)+\Phi\left(u^{-}\right)\right) d \mathcal{H}^{1}, \tag{4}
\end{equation*}
$$

where $\Phi(s)=2\left|\int_{0}^{s} \sqrt{W(t)} d t\right|$ is the usual transition energy between 0 and $s$. In this case, the additional variable $v$ in $G_{\varepsilon}$ approaches $u$ times the characteristic of the complement of $S_{u}$. Functionals of the Mumford-Shah type with non-constant surface energy density are obtained by choosing $\psi(x)=1$ if $x \neq 0$.

## 2 Notation and preliminaries

We use standard notation for Sobolev and Lebesgue spaces. $\mathcal{L}^{n}$ will denote the Lebesgue measure in $\mathbf{R}^{n}$ and $\mathcal{H}^{k}$ will denote the $k$-dimensional Hausdorff measure. $\mathcal{A}(\Omega)$ and $\mathcal{B}(\Omega)$ will be the families of open and Borel sets, respectively. If $\mu$ is a Borel measure and $E$ is a Borel set, then the measure $\mu\llcorner B$ is defined as $\mu\left\llcorner B(A)=\mu(A \cap B) .[t]^{ \pm}\right.$denote the positive/negative part of $t \in \mathbf{R}$.

## $2.1 \quad \Gamma$-convergence

Let $(X, d)$ be a metric space. We say that a sequence $F_{j}: X \rightarrow[-\infty,+\infty] \Gamma$ converges to $F: X \rightarrow[-\infty,+\infty]$ (as $j \rightarrow+\infty$ ) if for all $u \in X$ we have
(i) (lower limit inequality) for every sequence $\left(u_{j}\right)$ converging to $u$

$$
\begin{equation*}
F(u) \leq \underset{j}{\liminf } F_{j}\left(u_{j}\right) ; \tag{5}
\end{equation*}
$$

(ii) (existence of a recovery sequence) there exists a sequence ( $u_{j}$ ) converging to $u$ such that

$$
\begin{equation*}
F(u) \geq \underset{j}{\limsup } F_{j}\left(u_{j}\right), \tag{6}
\end{equation*}
$$

or, equivalently by (5),

$$
\begin{equation*}
F(u)=\lim _{j} F_{j}\left(u_{j}\right) . \tag{7}
\end{equation*}
$$

The function $F$ is called the $\Gamma$-limit of $\left(F_{j}\right)$ (with respect to $d$ ), and we write $F=\Gamma-\lim _{j} F_{j}$. If $\left(F_{\varepsilon}\right)$ is a family of functionals indexed by $\varepsilon>0$ then we say that $F_{\varepsilon} \Gamma$-converges to $F$ as $\varepsilon \rightarrow 0^{+}$if $F=\Gamma$ - $\lim _{j \rightarrow+\infty} F_{\varepsilon_{j}}$ for all $\left(\varepsilon_{j}\right)$ converging to 0 .

The reason for the introduction of this notion is explained by the following fundamental theorem.

Theorem 2.1 Let $F=\Gamma-\lim _{j} F_{j}$, and let a compact set $K \subset X$ exist such that $\inf _{X} F_{j}=\inf _{K} F_{j}$ for all $j$. Then

$$
\begin{equation*}
\exists \min _{X} F=\liminf _{j} F_{j} . \tag{8}
\end{equation*}
$$

Moreover, if $\left(u_{j}\right)$ is a converging sequence such that $\lim _{j} F_{j}\left(u_{j}\right)=\lim _{j} \inf _{X} F_{j}$ then its limit is a minimum point for $F$.

The definition of $\Gamma$-convergence can be given pointwise on $X$. It is convenient to introduce also the notion of $\Gamma$-lower and upper limit, as follows: let $F_{\varepsilon}: X \rightarrow$ $[-\infty,+\infty]$ and $u \in X$. We define

$$
\begin{align*}
& \Gamma-\liminf _{\varepsilon \rightarrow 0^{+}} F_{\varepsilon}(u)=\inf \left\{\liminf _{\varepsilon \rightarrow 0^{+}} F_{\varepsilon}\left(u_{\varepsilon}\right): u_{\varepsilon} \rightarrow u\right\}  \tag{9}\\
& \Gamma-\limsup _{\varepsilon \rightarrow 0^{+}} F_{\varepsilon}(u)=\inf \left\{\limsup _{\varepsilon \rightarrow 0^{+}} F_{\varepsilon}\left(u_{\varepsilon}\right): u_{\varepsilon} \rightarrow u\right\} . \tag{10}
\end{align*}
$$

If $\Gamma-\liminf _{\varepsilon \rightarrow 0^{+}} F_{\varepsilon}(u)=\Gamma-\lim \sup _{\varepsilon \rightarrow 0^{+}} F_{\varepsilon}(u)$ then the common value is called the $\Gamma$-limit of $\left(F_{\varepsilon}\right)$ at $u$, and is denoted by $\Gamma$ - $\lim _{\varepsilon \rightarrow 0^{+}} F_{\varepsilon}(u)$. Note that this definition is in accord with the previous one, and that $F_{\varepsilon} \Gamma$-converges to $F$ if and only if $F(u)=\Gamma-\lim _{\varepsilon \rightarrow 0^{+}} F_{\varepsilon}(u)$ at all points $u \in X$.

We recall that:
(i) if $F=\Gamma$ - $\lim _{j} F_{j}$ and $G$ is a continuous function then $F+G=\Gamma-\lim _{j}\left(F_{j}+G\right)$;
(ii) the $\Gamma$-lower and upper limits define lower semicontinuous functions.

From (i) we get that in the computation of our $\Gamma$-limits we can drop all $d$-continuous terms. Remark (ii) will be used in the proofs combined with approximation arguments.

For an introduction to $\Gamma$-convergence we refer to [8]. For an overview of $\Gamma$ convergence techniques for the approximation of free-discontinuity problems see [7].

### 2.2 Functions of bounded variation

Let $u \in L^{1}(\Omega)$. We say that $u$ is a function of bounded variation on $\Omega$ if its distributional derivative is a measure; i.e., there exist signed measures $\mu_{i}$ such that

$$
\int_{\Omega} u D_{i} \phi d x=-\int_{\Omega} \phi d \mu_{i}
$$

for all $\phi \in C_{c}^{1}(\Omega)$. The vector measure $\mu=\left(\mu_{i}\right)$ will be denoted by $D u$. The space of all functions of bounded variation on $\Omega$ will be denoted by $B V(\Omega)$.

It can be proven that if $u \in B V(\Omega)$ then the complement of the set of Lebesgue points $S_{u}$, that will be called the jump set of $u$, is rectifiable, i.e. there exists a countable family $\left(\Gamma_{i}\right)$ of graphs of Lipschitz functions of $(n-1)$ variables
such that $\mathcal{H}^{n-1}\left(S_{u} \backslash \bigcup_{i=1}^{\infty} \Gamma_{i}\right)=0$. Hence, a normal $\nu_{u}$ can be defined $\mathcal{H}^{n-1}$-a.e. on $S_{u}$, as well as the traces $u^{ \pm}$of $u$ on both sides of $S_{u}$ as

$$
u^{ \pm}(x)=\lim _{\rho \rightarrow 0^{+}} f_{\left\{y \in B_{\rho}(x): \pm\left\langle y-x, \nu_{u}(x)\right\rangle>0\right\}} u(y) d y
$$

where $\left.f_{B} u d y=|B|^{-1} \int_{B} u d y\right\}$. In the case $n=1$ we can always choose $\nu=+1$, so that $u^{+}(x)$ and $u^{-}(x)$ coincide with the right-hand side and left-hand side (approximate) limits of $u$ at $x$, denoted by $u(x+)$ and $u(x-)$, respectively.

If $u \in B V(\Omega)$ we define the three measures $D^{a} u, D^{j} u$ and $D^{c} u$ as follows. By the Radon Nikodym Theorem we set $D u=D^{a} u+D^{s} u$ where $D^{a} u \ll \mathcal{L}^{n}$ and $D^{s} u$ is the singular part of $D u$ with respect to $\mathcal{L}^{n} . D^{a} u$ is the absolutely continuous part of $D u$ with respect to the Lebesgue measure, $D^{j} u=D u L S_{u}$ is the jump part of $D u$, and $D^{c} u=D^{s} u\left\llcorner\left(\Omega \backslash S_{u}\right)\right.$ is the Cantor part of $D u$. We can then write

$$
D u=D^{a} u+D^{j} u+D^{c} u .
$$

It can be seen that $D^{j} u=\left(u^{+}-u^{-}\right) \nu_{u} \mathcal{H}^{n-1}\left\llcorner S_{u}\right.$, and that the Radon Nikodym derivative of $D u$ with respect of $\mathcal{L}^{n}$ is the approximate gradient $\nabla u$ of $u$ (which will be also denoted by $u^{\prime}$ if $n=1$ ).

A function $u \in L^{1}(\Omega)$ is a special function of bounded variation on $\Omega$ if $D^{c} u=0$, or, equivalently, if its distributional derivative can be written as

$$
D u=\nabla u \mathcal{L}^{n}+\left(u^{+}-u^{-}\right) \nu_{u} \mathcal{H}^{n-1}\left\llcorner S_{u} .\right.
$$

The space of special functions of bounded variation on $\Omega$ is denoted $S B V(\Omega)$.
For a detailed study of the properties of $B V$-functions we refer to [5], [10] and [11]. For an introduction to the study of free-discontinuity problems in the $B V$ setting we refer to [5].

### 2.3 Two lower semicontinuity results

We recall a simple lower semicontinuity result for 1-dimensional functionals defined on $\operatorname{SBV}(a, b)$ (see [2], [3], [7] Chapter 2).

Proposition 2.2 Let $\left(u_{j}\right)$ be a sequence $\operatorname{inSBV}(a, b)$ with
(i) $\left(u_{j}^{\prime}\right)$ is bounded in $L^{2}(a, b)$;
(ii) $\#\left(S_{u}\right)$ is equibounded;
(iii) $\left(u_{j}\right)$ is bounded in $L^{\infty}(a, b)$.

Then, up to passing to a subsequence, $u_{j}$ converges in $L^{1}(a, b)$ to a function $u \in \operatorname{SBV}(a, b)$. Furthermore,
(a) $u_{j}^{\prime} \rightarrow u^{\prime}$ weakly in $L^{2}(a, b)$;
(b) for all lower semicontinuous $\vartheta: \mathbf{R} \times \mathbf{R} \rightarrow[0,+\infty)$ which is also subadditive (i.e.,

$$
\vartheta(r, s) \leq \vartheta(r, t)+\vartheta(t, s)
$$

for all $r, s, t \in \mathbf{R}$ ) we have

$$
\sum_{x \in S_{u}} \vartheta(u(x-), u(x+)) \leq \liminf _{j} \sum_{x \in S_{u_{j}}} \vartheta\left(u_{j}(x-), u_{j}(x+)\right) .
$$

In particular $\#\left(S_{u}\right) \leq \liminf _{j} \#\left(S_{u_{j}}\right)$ by choosing $\vartheta=1$.
We will also use a simple version of a lower semicontinuity result by Ioffe [12].
Proposition 2.3 Let $f: \mathbf{R} \times \mathbf{R} \rightarrow[0,+\infty)$ be a lower semicontinuous function which is also convex in the second variable, and satisfying for all $T>0$

$$
|f(s, z)| \leq c_{T}\left(1+|z|^{2}\right)
$$

for all $|s| \leq T$ and $z \in \mathbf{R}$, for some $c_{T}>0$. Then, if $u_{j} \rightarrow u$ strongly in $L^{1}(\Omega)$, $\sup _{j}\left\|u_{j}\right\|_{\infty}<+\infty$ and $v_{j} \rightarrow v$ weakly in $L^{2}(\Omega)$, we have

$$
\int_{(a, b)} f(u, v) d x \leq \liminf _{j} \sum_{(a, b)} f\left(u_{j}, v_{j}\right) d x
$$

## 3 The main result

Let $W, \psi: \mathbf{R} \rightarrow[0,+\infty)$ be two functions vanishing only at $x=0$, increasing on $[0,+\infty)$ and decreasing on $(-\infty, 0]$, and assume that $W$ is continuous and $\psi$ is lower semicontinuous.

Let $\Omega$ be a bounded open subset of $\mathbf{R}^{n}$. We define the space

$$
S B V_{*}(\Omega)=\left\{u \in L^{1}(\Omega):[u-t]^{+},[u+t]^{-} \in S B V(\Omega) \text { for all } t>0\right\}
$$

Note that the approximate gradient $\nabla u$ of $u \in S B V_{*}(\Omega)$ exists for a.e. $x \in \Omega$. Moreover, if $n=1$ then $S_{u}$ is at most countable.

Theorem 3.1 Let $G_{\varepsilon}: L^{1}(\Omega) \times L^{1}(\Omega) \rightarrow[0,+\infty)$ be defined by

$$
G_{\varepsilon}(u, v)= \begin{cases}\int_{\Omega}\left(\psi(v)|\nabla u|^{2}+\frac{1}{\varepsilon} W(u-v)+\varepsilon|\nabla v|^{2}\right) d x & \text { if } u, v \in H^{1}(\Omega) \\ +\infty & \text { otherwise } .\end{cases}
$$

Then there exists the $\Gamma-\lim _{\varepsilon \rightarrow 0+} G_{\varepsilon}(u, v)=G(u, v)$ with respect to the $L^{1}(\Omega) \times$ $L^{1}(\Omega)$-convergence, and

$$
G(u, v)= \begin{cases}\int_{\Omega} \psi(u)|\nabla u|^{2} d x+\int_{S_{u}}\left(\Phi\left(u^{+}\right)+\Phi\left(u^{-}\right)\right) d \mathcal{H}^{n-1} & \text { if } u \in S B V_{*}(\Omega) \\ & \text { and } u=v \text { a.e. } \\ +\infty & \text { otherwise },\end{cases}
$$

where

$$
\begin{equation*}
\Phi(z):=2\left|\int_{0}^{z} \sqrt{W(s)} d s\right| \tag{11}
\end{equation*}
$$

for all $z \in \mathbf{R}$.
The proof of the theorem above will be given in detail only in the case $n=1$, as a consequence of the propositions in the rest of the section. In this case it suffices to consider $\Omega=(a, b)$ an interval. The case $n \geq 2$ can be easily obtained by slicing and approximation techniques from the study of the 1-dimensional case (for all the details we refer to Chapter 4 in [7]).

Proposition 3.2 Let $F$ be defined on $L^{1}(a, b)$ by $F(u)=G(u, u)$. Then $F$ is lower semicontinuous with respect to the $L^{1}$-convergence.

Proof. (a) lower semicontinuity on non-negative functions: let $t>0$, let

$$
\phi_{t}(z)= \begin{cases}\Phi(z) & \text { if } z>t \\ 0 & \text { if } z \leq t\end{cases}
$$

and let $\theta_{t}(y, z)=\phi_{t}(y)+\phi_{t}(z)$. The function $\theta_{t}$ is subadditive and lower semicontinuous.

For all $v \in S B V_{*}(a, b)$ with $v \geq 0$ let $v^{t}=v \vee t$; note that

$$
\begin{aligned}
F(v) & \geq F_{t}\left(v^{t}\right):=\int_{(a, b)} \psi\left(v^{t}\right)\left|\left(v^{t}\right)^{\prime}\right|^{2} d x+\sum_{S_{v^{t}}} \theta_{t}\left(\left(v^{t}\right)^{+},\left(v^{t}\right)^{-}\right) \\
& \geq \psi(t) \int_{(a, b)}\left|\left(v^{t}\right)^{\prime}\right|^{2} d x+\Phi(t) \#\left(S_{v^{t}}\right)
\end{aligned}
$$

If $u_{j} \rightarrow u$ in $L^{1}(a, b)$ with $u_{j} \geq 0$ and $F\left(u_{j}\right) \leq c$, we deduce from the inequality above that $u_{j}^{t} \rightarrow u^{t}$ weakly in $S B V(a, b)$. From the lower semicontinuity of $F_{t}$ we have $u^{t} \in S B V(a, b)$ and

$$
\liminf _{j} F\left(u_{j}\right) \geq \int_{(a, b)}\left|\left(u^{t}\right)^{\prime}\right|^{2} d x+\sum_{S_{u_{j}^{t}}} \theta\left(\left(u^{t}\right)^{+},\left(u^{t}\right)^{-}\right)
$$

Taking the supremum for $t>0$ we get $u \in S B V_{*}(a, b)$ and

$$
\underset{j}{\liminf } F\left(u_{j}\right) \geq F(u)
$$

(b) lower semicontinuity on non-positive functions: the proof is the same as in Step (a).
(c) conclusion: the lower semicontinuity of $F$ follows by noting that $F(u)=$ $F\left([u]^{+}\right)+F\left([u]^{-}\right)$.

We "localize" the functionals $G_{\varepsilon}$ by defining for all $A$ open subset of $(a, b)$ and $u, v \in L^{1}(a, b)$

$$
G_{\varepsilon}(u, v, A)= \begin{cases}\int_{A}\left(\psi(v)\left|u^{\prime}\right|^{2}+\frac{1}{\varepsilon} W(u-v)+\varepsilon|\nabla v|^{2}\right) d x & \text { if } u, v \in H^{1}(a, b) \\ +\infty & \text { otherwise }\end{cases}
$$

Lemma 3.3 Let $t, T>0$ and let $u_{0}, v_{0} \in \mathbf{R}$ and $u, v \in H^{1}(0, T)$ satisfy

$$
\left\{\begin{array} { l } 
{ u _ { 0 } , v _ { 0 } > t } \\
{ u ( 0 ) = u _ { 0 } } \\
{ v ( 0 ) = v _ { 0 } } \\
{ v ( x ) > t \text { for all } x \in ( 0 , T ) } \\
{ v ( T ) = t }
\end{array} \quad \text { or } \quad \left\{\begin{array}{l}
u_{0}, v_{0}<-t \\
u(0)=u_{0} \\
v(0)=v_{0} \\
v(x)<-t \text { for all } x \in(0, T) \\
v(T)=-t
\end{array}\right.\right.
$$

Then

$$
G_{\varepsilon}(u, v,(0, T)) \geq \psi(t) \frac{\left(u_{0}-\inf [u]^{+}\right)^{2}}{T}+\left[\Phi\left(\left(\inf [u]^{+}\right) \wedge v_{0}\right)-\Phi(t)\right]^{+}
$$

in the case $u_{0}, v_{0}>t$, while

$$
G_{\varepsilon}(u, v,(0, T)) \geq \psi(-t) \frac{\left(u_{0}+\inf [u]^{-}\right)^{2}}{T}+\left[\Phi\left(-\left(\inf [u]^{-}\right) \wedge\left(-v_{0}\right)\right)-\Phi(-t)\right]^{+}
$$

in the case $u_{0}, v_{0}<-t$. The same estimates hold if the boundary conditions at 0 and at $T$ are interchanged.

Proof. We deal with the case $u_{0}, v_{0}>t$ only, the other case being dealt with in a symmetric way. First, note that

$$
\begin{equation*}
\int_{(0, T)} \psi(v)\left|u^{\prime}\right|^{2} d x \geq \psi(t) \frac{\left(u_{0}-\inf [u]^{+}\right)^{2}}{T} \tag{12}
\end{equation*}
$$

Let

$$
\bar{x}=\sup \left\{t \in[0, T]: v(t)=\inf [u]^{+}\right\}
$$

$(\bar{x}=0$ if $v<\inf u$ on $[0, T])$. Suppose first that $\inf [u]^{+} \leq v_{0}$; then

$$
\begin{align*}
\int_{\bar{x}}^{T}\left(\frac{1}{\varepsilon} W(u-v)+\varepsilon\left|v^{\prime}\right|^{2}\right) d x & \geq \int_{\bar{x}}^{T}\left(\frac{1}{\varepsilon} W\left(\left(\inf [u]^{+}\right)-v\right)+\varepsilon\left|v^{\prime}\right|^{2}\right) d x \\
& \left.\geq 2 \int_{\bar{x}}^{T} \sqrt{W\left(\left(\inf [u]^{+}\right)-z\right)}\left|v^{\prime}\right|\right) d x \\
& \geq 2\left|\int_{\inf [u]^{+}}^{t} \sqrt{W\left(\left(\inf [u]^{+}\right)-s\right)} d s\right| \\
& \geq 2\left|\int_{t}^{\inf [u]^{+}} \sqrt{W(s)} d s\right| \\
& =\Phi\left(\inf [u]^{+}\right)-\Phi(t) \tag{13}
\end{align*}
$$

In the case $\inf [u]^{+}>v_{0}$, the same computation carries on with $v_{0}$ in place of $\inf [u]^{+}$.

For all $t>0$ and $r, s \in \mathbf{R}$ we set

$$
\begin{align*}
\Phi_{t}(r) & =\left[\Phi\left([r]^{+}\right)-\Phi(t)\right]^{+}+\left[\Phi\left([-r]^{-}\right)-\Phi(-t)\right]^{+}  \tag{14}\\
\vartheta_{t}(r, s) & =\Phi_{t}(r)+\Phi_{t}(s) \tag{15}
\end{align*}
$$

Proposition 3.4 Let $u \in L^{1}(a, b)$ and let $x \in S_{u}$. If $u_{\varepsilon} \rightarrow u$ and $v_{\varepsilon} \rightarrow u$ in $L^{1}(a, b)$ then

$$
\liminf _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon},\left(x_{0}, x_{1}\right)\right) \geq \vartheta_{t}(u(x-), u(x+))
$$

for all $t>0$ and for all $x_{0}<x<x_{1}$.
Proof. We deal with the case $u(x+), u(x-) \geq t>0$, the changes in the other cases being clear from the proof and from the statement of Lemma 3.3. It is not restrictive to suppose that we have $\liminf _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon},\left(x_{0}, x_{1}\right)\right)<+\infty$.

Let $\left(\varepsilon_{j}\right)$ be a sequence of positive numbers converging to 0 such that

$$
\lim _{j} G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}\right)=\liminf _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon}\right)
$$

Up to restricting the interval $\left(x_{0}, x_{1}\right)$, we can suppose that

$$
\begin{align*}
u_{\varepsilon_{j}}\left(x_{0}\right) \rightarrow u\left(x_{0}\right)>t, & u_{\varepsilon_{j}}\left(x_{1}\right) \rightarrow u\left(x_{1}\right)>t \\
v_{\varepsilon_{j}}\left(x_{0}\right) \rightarrow u\left(x_{0}\right)>t, & v_{\varepsilon_{j}}\left(x_{1}\right) \rightarrow u\left(x_{1}\right)>t . \tag{16}
\end{align*}
$$

Note that $\lim _{j} \inf _{\left(x_{0}, x_{1}\right)}\left|v_{\varepsilon_{j}}\right|=0$; otherwise, a subsequence of $\left(u_{\varepsilon_{j}}\right)$ would be equibounded in $H^{1}\left(x_{0}, x_{1}\right)$ and then $u \in H^{1}\left(x_{0}, x_{1}\right)$ contradicting the fact that $x \in S_{u}$.

Denote

$$
x_{0}^{j}=\inf \left\{x \in\left(x_{0}, x_{1}\right): v_{\varepsilon_{j}}(x)=t\right\}, \quad x_{1}^{j}=\sup \left\{x \in\left(x_{0}, x_{1}\right): v_{\varepsilon_{j}}(x)=t\right\},
$$

which are attained for $j$ large enough. By Lemma 3.3, we then have

$$
\begin{align*}
G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}},\left(x_{0}, x_{1}\right)\right) \geq & G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}},\left(x_{0}, x_{0}^{j}\right)\right)+G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}},\left(x_{1}^{j}, x_{1}\right)\right) \\
\geq & \psi(t) \frac{1}{\left(x_{0}^{j}-x_{0}\right)}\left|u_{\varepsilon_{j}}\left(x_{0}\right)-\inf _{\left(x_{0}, x_{0}^{j}\right)}\left[u_{\varepsilon_{j}}\right]^{+}\right|^{2} \\
& +\Phi_{t}\left(\left(\inf _{\left(x_{0}, x_{0}^{j}\right)}\left[u_{\varepsilon_{j}}\right]^{+}\right) \vee v_{\varepsilon_{j}}\left(x_{0}\right)\right) \\
& +\psi(t) \frac{1}{\left(x_{1}-x_{1}^{j}\right)}\left|u_{\varepsilon_{j}}\left(x_{1}\right)-\inf _{\left(x_{1}^{j}, x_{1}\right)} u_{\varepsilon_{j}}\right|^{2} \\
& +\Phi_{t}\left(\left(\inf _{\left(x_{1}^{j}, x_{1}\right)}\left[u_{\varepsilon_{j}}\right]^{+}\right) \vee v_{\varepsilon_{j}}\left(x_{0}\right)\right) . \tag{17}
\end{align*}
$$

With fixed $\eta>0$, up to restricting the interval $\left(x_{0}, x_{1}\right)$ further, we can suppose that

$$
\limsup _{j}\left(\left|u_{\varepsilon_{j}}\left(x_{0}\right)-u(x-)\right|+\left|v_{\varepsilon_{j}}\left(x_{0}\right)-u(x-)\right|\right)<\eta,
$$

$$
\underset{j}{\limsup }\left(\left|u_{\varepsilon_{j}}\left(x_{1}\right)-u(x+)\right|+\left|u_{\varepsilon_{j}}\left(x_{0}\right)-u(x-)\right|\right)<\eta
$$

Then from (17) we deduce first that

$$
\begin{aligned}
& \limsup _{j}\left|\left(\inf _{\left(x_{0}, x_{0}^{j}\right)}\left[u_{\varepsilon_{j}}\right]^{+}\right)-u(x-)\right| \leq c \frac{1}{\psi(t)} \sqrt{x_{1}-x_{0}}+\eta, \\
& \limsup \left|\left(\inf _{\left(x_{1}^{j}, x_{1}\right)}\left[u_{\varepsilon_{j}}\right]^{+}\right)-u(x+)\right| \leq c \frac{1}{\psi(t)} \sqrt{x_{1}-x_{0}}+\eta,
\end{aligned}
$$

and, consequently, that

$$
\begin{aligned}
& \liminf _{j} G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}},\left(x_{0}, x_{1}\right)\right) \\
& \quad \geq \vartheta_{t}\left(u(x-)-c \frac{1}{\psi(t)} \sqrt{x_{1}-x_{0}}-\eta, u(x+)-c \frac{1}{\psi(t)} \sqrt{x_{1}-x_{0}}-\eta\right)
\end{aligned}
$$

As $\eta$ and $x_{1}-x_{0}$ can be taken arbitrarily small, we have the thesis.
Remark 3.5 From the previous proposition we immediately get:
(a) for every open subset $\Omega^{\prime}$ of $(a, b)$ we have

$$
\liminf _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon}, \Omega^{\prime}\right) \geq \sum_{S_{u} \cap \Omega^{\prime}} \vartheta_{t}(u(x-), u(x+))
$$

if $u_{\varepsilon} \rightarrow u$ and $v_{\varepsilon} \rightarrow u$ in $L^{1}(a, b)$;
(b) if $\Gamma-\lim \inf _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}(u, u)<+\infty$ then for all $t>0$

$$
\#\left(\left\{x \in S_{u}:|u(x-)| \vee|u(x+)|>t\right\}\right)<+\infty .
$$

Proposition 3.6 We have $G \leq \Gamma-\liminf _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}$.
Proof. Let $u_{\varepsilon} \rightarrow u$ and $v_{\varepsilon} \rightarrow v$ in $L^{1}(a, b)$ be such that

$$
\liminf _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon}\right)<+\infty
$$

Then we have

$$
\liminf _{\varepsilon \rightarrow 0^{+}} \frac{1}{\varepsilon} \int_{(a, b)} W\left(u_{\varepsilon}-v_{\varepsilon}\right) d x<+\infty
$$

which implies $u=v$.
Let $\left(\varepsilon_{j}\right)$ be a sequence of positive numbers converging to 0 such that

$$
\lim _{j} G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}\right)=\liminf _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon}\right)
$$

and such that $u_{\varepsilon_{j}} \rightarrow u, v_{\varepsilon_{j}} \rightarrow u$ a.e. We denote

$$
M=\left\{x \in(a, b): \lim _{j} u_{\varepsilon_{j}}(x)=\lim _{j} v_{\varepsilon_{j}}(x)=u(x)\right\} .
$$

Let $t>0$ be fixed. Thanks to Remark 3.5(a) we can suppose that $t \notin$ $\left\{|u(x+)|,|u(x-)|: x \in S_{u}\right\}$.

We may select a double-indexed family $\left\{x_{i}^{N}: N \in \mathbf{N}, i=0, \ldots, 2^{N}\right\}$ of points in $[a, b]$ such that

$$
a=x_{0}^{N}<x_{1}^{N}<\cdots<x_{2^{N}}^{N}
$$

$x_{i}^{N} \notin S_{u}, x_{i}^{N} \in M$ (except for $i=0,2^{N}$ ), and

$$
2^{-N-1} \leq x_{i+1}^{N}-x_{i}^{N} \leq 2^{-N+1}, \quad x_{2 i}^{N}=x_{i}^{N}
$$

for all $N$ and $i$. We can also suppose that there exits the $\operatorname{limits} \lim _{j} u_{\varepsilon_{j}}(a)=$ $\lim _{j} v_{\varepsilon_{j}}(a)=u(a+)$ and $\lim _{j} u_{\varepsilon_{j}}(b)=\lim _{j} v_{\varepsilon_{j}}(b)=u(b-)$. This is not restrictive, upon first restricting our analysis to $(a+\eta, b-\eta)$ for some small $\eta>0$, and then letting $\eta$ tend to 0 .

Fix $N \in \mathbf{N}$, and set

$$
J_{i}=J_{i}^{N}=\left(x_{i-1}^{N}, x_{i}^{N}\right), \quad i=1, \ldots, 2^{N}
$$

and

$$
a_{N}=\left\{i \in\left\{1, \ldots, 2^{N}\right\}:|u| \leq t \text { a.e. on } J_{i}\right\} .
$$

For all $i \notin a_{N}$ we can choose a point $\bar{x}_{i} \in J_{i} \cap M$ such that $\left|u\left(\bar{x}_{i}\right)\right|>t$. We can therefore suppose that

$$
u_{\varepsilon_{j}}\left(\bar{x}_{i}\right)>t, v_{\varepsilon_{j}}\left(\bar{x}_{i}\right)>t \quad \text { for all } i \text { and } j
$$

or

$$
u_{\varepsilon_{j}}\left(\bar{x}_{i}\right)<-t, v_{\varepsilon_{j}}\left(\bar{x}_{i}\right)<-t \quad \text { for all } i \text { and } j
$$

in the cases $u\left(\bar{x}_{i}\right)>t$ and $u\left(\bar{x}_{i}\right)<-t$, respectively. Upon extracting a subsequence of $\left(\varepsilon_{j}\right)$ we can also assume that for all $i \notin a_{N}$ only one of the two following possibilities is realized:
(i) for all $j$ we have $\left|v_{\varepsilon_{j}}(x)\right|>t / 2$ for all $x \in J_{i}$;
(ii) for all $j$ there exists $y_{i}^{j} \in J_{i}$ such that $\left|v_{\varepsilon_{j}}\left(y_{i}^{j}\right)\right| \leq t / 2$.

We then set

$$
b_{N}=\left\{i \notin a_{N}: \text { (i) holds }\right\}, \quad c_{N}=\left\{i \notin a_{N}: \text { (ii) holds }\right\} .
$$

Note that if $i \in c_{N}$ then from Lemma 3.3 we deduce that, in the case that $u\left(\bar{x}_{i}\right)>t$,

$$
\begin{aligned}
G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}, J_{i}\right) & \geq \psi\left(\frac{t}{2}\right) 2^{N-1}\left(t-\left(\inf _{J_{i}} u_{\varepsilon_{j}} \vee \frac{t}{2}\right)\right)^{2}+\Phi_{t}\left(\inf _{J_{i}} u_{\varepsilon_{j}} \vee \frac{t}{2}\right) \\
& \geq \psi\left(\frac{t}{2}\right)\left(t-\left(\inf _{J_{i}} u_{\varepsilon_{j}} \vee \frac{t}{2}\right)\right)^{2}+\Phi_{t}\left(\inf _{J_{i}} u_{\varepsilon_{j}} \vee \frac{t}{2}\right) \\
& \geq c(t)>0
\end{aligned}
$$

where $c(t)$ is a constant depending only on $t$. The same conclusion holds in the case $u\left(\bar{x}_{i}\right)<-t$, with the obvious changes coming from Lemma 3.3. Hence, $\#\left(c_{N}\right) \leq c$, independent of $N$.

Let now

$$
u_{t}=[u-u]^{+}-[u+t]^{-} .
$$

If $i \in a_{N}$ then we trivially have

$$
\begin{equation*}
\liminf _{j} G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}, J_{i}\right) \geq 0=\int_{J_{i}} \psi(u)\left|u_{t}^{\prime}\right|^{2} d x \tag{18}
\end{equation*}
$$

If $i \in b_{N}$, we first note that

$$
\liminf _{j} G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}, J_{i}\right) \geq \liminf _{j} \int_{J_{i}} \psi\left(v_{\varepsilon_{j}}\right)\left|u_{\varepsilon_{j}}^{\prime}\right|^{2} d x \geq \psi\left(\frac{t}{2}\right) \liminf _{j} \int_{J_{i}}\left|u_{\varepsilon_{j}}^{\prime}\right|^{2} d x
$$

from which we deduce, upon extracting a subsequence, that ( $u_{\varepsilon_{j}}$ ) converges weakly to $u$ in $H^{1}\left(J_{i}\right)$, and that we may suppose that $\left\|u_{\varepsilon_{j}}\right\|_{L^{\infty}\left(J_{i}\right)} \leq C<+\infty$. Moreover, letting $\tilde{v}_{\varepsilon_{j}}=\left(v_{\varepsilon_{j}} \wedge C\right) \vee(-C)$, after noting that

$$
G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}, J_{i}\right) \geq G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, \tilde{v}_{\varepsilon_{j}}, J_{i}\right)
$$

and that $\tilde{v}_{\varepsilon_{j}} \rightarrow u$ in $L^{1}\left(J_{i}\right)$ we obtain

$$
\begin{align*}
\underset{j}{\liminf } G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}, J_{i}\right) & \geq \liminf _{j} G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, \tilde{v}_{\varepsilon_{j}}, J_{i}\right) \\
& \geq \liminf _{j} \int_{J_{i}} \psi\left(\tilde{v}_{\varepsilon_{j}}\right)\left|u_{\varepsilon_{j}}^{\prime}\right|^{2} d x \\
& \geq \int_{J_{i}} \psi(u)\left|u^{\prime}\right|^{2} d x \tag{19}
\end{align*}
$$

If $i \in c_{N}$, by Remark 3.5(a) we estimate

$$
\begin{equation*}
\liminf _{j} G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}, J_{i}\right) \geq \sum_{S_{u} \cap J_{i}} \vartheta_{t}(u(x-), u(x+)) . \tag{20}
\end{equation*}
$$

We remark, moreover, that:
(a) if $i \in a_{N}$ then $u_{t}=0$ in $J_{i}$, which in particular implies that $S_{u_{t}} \cap J_{i}=\emptyset$, so that $\vartheta_{t}(u(x-), u(x+))=0$ for all $x \in S_{u} \cap J_{i}$;
(b) if $i \in b_{N}$ then $u \in H^{1}\left(J_{i}\right)$ and in particular $S_{u} \cap J_{i}=\emptyset$; hence,

$$
\begin{equation*}
\sum_{i \in c_{N}} \sum_{x \in S_{u} \cap J_{i}} \vartheta_{t}(u(x-), u(x+))=\sum_{x \in S_{u}} \vartheta_{t}(u(x-), u(x+)) . \tag{21}
\end{equation*}
$$

We set $K_{N}=\bigcup_{i \in c_{N}} J_{i}$. From (18)-(21) we deduce that

$$
\underset{j}{\liminf } G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}\right) \geq \int_{(a, b) \backslash K_{N}} \psi(u)\left|u_{t}^{\prime}\right|^{2} d x+\sum_{x \in S_{u}} \vartheta_{t}(u(x-), u(x+))
$$

Upon noting that
(a) if $i \in a_{N}$ then $\{2 i-1,2 i\} \subset a_{N+1}$;
(b) if $i \in b_{N}$ then $\{2 i-1,2 i\} \subset a_{N+1} \cup b_{N+1}$,
we get that $K_{N+1} \subset K_{N}$, and from $\# c_{N} \leq c$ and $\left|J_{i}\right| \leq c 2^{-N}$ we deduce that $\left|K_{N}\right| \rightarrow 0$. From the Dominated Convergence Theorem we then obtain, letting $N \rightarrow+\infty$,

$$
\underset{j}{\liminf } G_{\varepsilon_{j}}\left(u_{\varepsilon_{j}}, v_{\varepsilon_{j}}\right) \geq \int_{(a, b)} \psi(u)\left|u_{t}^{\prime}\right|^{2} d x+\sum_{x \in S_{u}} \vartheta_{t}(u(x-), u(x+))
$$

Note that

$$
(\psi(t) \wedge \psi(-t)) \int_{(a, b)}\left|u_{t}^{\prime}\right|^{2} d x+(\Phi(t) \wedge \Phi(-t)) \#\left(S_{u_{t}}\right)<+\infty
$$

whence we deduce that $\#\left(S_{u_{t}}\right)<+\infty$ and $u_{t} \in H^{1}\left((a, b) \backslash S_{u_{t}}\right)$. In particular, $u \in S B V_{*}(a, b)$.

Eventually, the thesis of the proposition is obtained by letting $t \rightarrow 0^{+}$and using the Dominated Convergence Theorem again.

Proposition 3.7 We have $G \geq \Gamma-\lim \sup _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}$.
Proof. First, let $u \in S B V(a, b)$ with

$$
\int_{(a, b)}\left|u_{t}^{\prime}\right|^{2} d x+\#\left(S_{u}\right)<+\infty
$$

By the local nature of the construction below, we can suppose $S_{u}=\{0\}$, with $0 \in(a, b)$. We have to construct a family $\left(u_{\varepsilon}, v_{\varepsilon}\right)$ such that

$$
F(u) \geq \limsup _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon}\right) .
$$

We perform the construction only for $x>0$, the construction for $x<0$ being symmetric.

With fixed $\eta>0$ let $T>0$ and $v_{T} \in H^{1}(0, T)$ be such that

$$
\begin{gathered}
v_{T}(0)=0, \quad v_{T}(T)=u(0+) \\
\int_{0}^{T}\left(W\left(u(0+)-v_{T}\right)+\left|v_{T}^{\prime}\right|^{2}\right) d x \leq \Phi(u(0+))+\eta \\
\frac{1}{T} \int_{0}^{1} W(\tau u(0+)) d \tau \leq \eta
\end{gathered}
$$

We set, for $\varepsilon>0$ sufficiently small:

$$
\begin{aligned}
& u_{\varepsilon}(x)= \begin{cases}\frac{x}{T \varepsilon} u(0+) & \text { if } 0 \leq x<\frac{\varepsilon}{T} \\
u(0+) & \text { if } \frac{\varepsilon}{T} \leq x<\varepsilon\left(T+\frac{1}{T}\right) \\
u\left(x-\varepsilon\left(T+\frac{1}{T}\right)\right) & \text { if } x \geq \varepsilon\left(T+\frac{1}{T}\right),\end{cases} \\
& v_{\varepsilon}(x)= \begin{cases}0 & \text { if } 0 \leq x<\frac{\varepsilon}{T} \\
v_{T}\left(\frac{x}{\varepsilon}-\frac{1}{T}\right) & \text { if } \frac{\varepsilon}{T} \leq x<\varepsilon\left(T+\frac{1}{T}\right) \\
u\left(x-\varepsilon\left(T+\frac{1}{T}\right)\right) & \text { if } x \geq \varepsilon\left(T+\frac{1}{T}\right) .\end{cases}
\end{aligned}
$$

It can be immediately verified that $u_{\varepsilon} \rightarrow u$ and $v_{\varepsilon} \rightarrow u$ in $L^{1}(a, b)$. Moreover,

$$
\lim _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon},(0, b)\right) \leq \int_{(0, b)} \psi(u)\left|u^{\prime}\right|^{2} d x+\Phi(u(0+))+2 \eta
$$

From the corresponding construction for $x<0$ we obtain eventually

$$
\lim _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{\varepsilon}, v_{\varepsilon}\right) \leq \int_{(a, b)} \psi(u)\left|u^{\prime}\right|^{2} d x+\Phi(u(0+))+\Phi(u(0-))+4 \eta=G(u, u)
$$

which gives the desired inequality by the arbitrariness of $\eta>0$, after noting that the functions $u_{\varepsilon}$ and $v_{\varepsilon}$ belong to $H^{1}(a, b)$ thanks to the condition $u_{\varepsilon}(0)=v_{\varepsilon}(0)=$ 0 .

In the general case $u \in S B V_{*}(a, b)$ with $F(u)<+\infty$, consider the family $\left(u_{t}\right)_{t>0}$ defined by

$$
u_{t}=[u-t]^{+}-[u+t]^{-} .
$$

Note that $F\left(u_{t}\right) \leq F(u), u_{t} \in S B V(a, b)$ and

$$
\int_{(a, b)}\left|u^{\prime}\right|^{2} d x+\#\left(S_{u_{t}}\right)<+\infty
$$

therefore, by the first part of the proof,

$$
\Gamma-\limsup _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}\left(u_{t}, u_{t}\right) \leq F\left(u_{t}\right) \leq F(u),
$$

and the proof is concluded by letting $t \rightarrow 0$, so that $u_{t} \rightarrow u$ in $L^{1}(a, b)$, and recalling the lower semicontinuity of $v \mapsto \Gamma-\lim \sup _{\varepsilon \rightarrow 0^{+}} G_{\varepsilon}(v, v)$.

Acknowledgements This paper was written while both authors wasere visiting the Max-Planck-Institute for Mathematics in the Sciences at Leipzig. The second author acknowledges financial support from the European Union program "Training and Mobility of Researchers" through Marie-Curie fellowship ERBFMBICT972023.

## References

[1] R. Alicandro, A. Braides and J. Shah, Approximation of non-convex functionals in GBV, Interfaces and Free Boundaries, to appear.
[2] L. Ambrosio, A compactness theorem for a new class of functions of bounded variation, Boll. Un. Mat. Ital. 3-B (1989), 857-881.
[3] L. Ambrosio, Existence theory for a new class of variational problems, Arch. Rational Mech. Anal. 111 (1990), 291-322.
[4] L. Ambrosio and A. Braides, Energies in SBV and variational models in fracture mechanics. Homogenization and Applications to Material Sciences, (D. Cioranescu, A. Damlamian, P. Donato eds.), GAKUTO, Gakkōtosho, Tokio, Japan, 1997, p. 1-22.
[5] L. Ambrosio, N. Fusco and D. Pallara, Special Functions of Bounded Variation and Free Discontinuity Problems, Oxford University Press, Oxford, to appear.
[6] L. Ambrosio and V. M. Tortorelli, Approximation of functionals depending on jumps by elliptic functionals via $\Gamma$-convergence, Comm. Pure Appl. Math. 43 (1990), 999-1036.
[7] A. Braides, Approximation of Free-discontinuity Problems, Lecture Notes in Mathematics, Springer Verlag, Berlin, to appear.
[8] G. Dal Maso, An Introduction to $\Gamma$-convergence, Birkhäuser, Boston, 1993.
[9] E. De Giorgi and L. Ambrosio, Un nuovo funzionale del calcolo delle variazioni, Atti Accad. Naz. Lincei Rend. Cl. Sci. Fis. Mat. Natur. 82 (1988), 199-210.
[10] L. C. Evans and R. F. Gariepy, Measure theory and fine properties of functions, CRC Press, Boca Raton 1992.
[11] H. Federer, Geometric Measure Theory. Springer Verlag, New York, 1969.
[12] A.D. Ioffe, On lower semicontinuity of integral functionals. I and II. SIAM J. Control Optim. 15 (1977) 521-538 and 991-1000.
[13] D. Mumford and J. Shah, Optimal approximation by piecewise smooth functions and associated variational problems, Comm. Pure Appl. Math. 17 (1989), 577-685.

