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Hyperplane arrangements separating arbitrary vertex classes in n-cubes
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# Hyperplane Arrangements Separating Arbitrary Vertex Classes in n-Cubes* 

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#### Abstract

Strictly layered feedforward networks with binary neurons are viewed as maps from the vertex set of an $n$-cube to the vertex set of an $l$-cube. With only one output neuron in principle they can realize any Boolean function on $n$ inputs. We address the problem of determining the necessary and sufficient numbers of hidden units for this task by using separability properties of affine oriented hyperplane arrangements.


Keywords: feedforward networks, binary units, classification problems, hypercube, separability, affine oriented hyperplane arrangements, linear codes

[^0]
## 1 Introduction

The problem addressed in this paper stems from an unsolved question in the theory of neural networks [7]. There it was proven that so called feedforward networks may serve as universal approximators, that is, under quite general regularity assumptions a network with sufficiently many hidden neurons can approximate any member of a class of functions to any desired degree of accuracy [4], [5], [6], [8], [12]. Although these theorems guarantee the existence of neural network solutions for such problems, it is still an open question, how to find a good upper bound for the number of hidden units to use. This, of course, depends on the problem and on the desired degree of accuracy [2], [3], [10], [13].
To get better access to analytical considerations for this problem, we will reduce it in several steps. First, one may consider only categorization tasks: A set of points in the input space $\mathbb{R}^{n}$ has to be mapped e.g. to the values 1 and -1 . In a second step, this can be further reduced to the problem of approximating a Boolean function on $n$ inputs, i.e. mapping the vertices of a hypercube in $\mathbb{R}^{n}$ to values 1 and -1 .
This kind of classification problems can be treated by 2-layer networks [7], where the so called hidden layer has e.g. $l$ units getting signals from the $n$ inputs; and the single unit of the output layer gets $l$ signals from the hidden layer. Usually the units of feedforward networks are given as composition of affine functions on their input space with a differentiable transfer function of sigmoidal characteristic, for example $\sigma_{r}(x):=\tanh (r x), r \in \mathbb{R}$. Thus the output of hidden unit $i$ is given in the form

$$
o_{i}(x):=\sigma_{r}\left(\theta_{i}+\sum_{j=1}^{n} w_{i j} x_{j}\right), \quad i=1, \ldots, l, \quad x \in \mathbb{R}^{n}
$$

where $\theta_{i}$ is a constant, the bias term of the unit, and $w_{i}=\left(w_{i 1}, \ldots, w_{i n}\right) \in \mathbb{R}^{n}$ denotes its weight vector. Every such unit partitions its input space $\mathbb{R}^{n}$ into two half spaces separated by its so called center $H_{i}$, which is here defined by

$$
H_{i}:=\left\{x \in \mathbb{R}^{l} \mid w \cdot x=-\theta_{i}\right\}
$$

In the last step we let the slope of the sigmoid go to infinity, i.e. $r \rightarrow \infty$, so that the sigmoid approximates a step function, without moving the center $H_{i}$, and associates to the half spaces separated by the center the values 1 and -1 . Thus we are referring to feedforward networks with binary neurons.
Using this approach, the hidden layer of a neural network maps the binary input patterns of an $n$-cube to binary patterns of an $l$-cube. These $l$-dimensional patterns then have to be separated by the center of the output unit in such a way that the values 1 and -1 give the correct classification of the input patterns.
In section 2 we formulate the problem in geometrical terms and present some elementary results. In the following section we specify assumptions under which
compositions of hyperplane arrangements separate unions of patterns belonging to different classes. This leads to the result that each subset of the vertex set $W_{n}$ of the $n$-cube may be separated by at most $\frac{3}{n+2} \cdot 2^{n}$ affine hyperplanes. In section 4 , we obtain the result that there exist binary problems for which one needs at least $\left(2^{\frac{n}{2}}-\frac{n^{2}}{2}\right)$ affine hyperplanes to separate the patterns belonging to two different classes. Based on these results, some further issues related to the neural network context of this article are shortly discussed in the final section.

## 2 Problem Formulation and Elementary Results

For $n \geq 1$ we shall study - in some sense to be specified - separations of the $n$-cube by affine hyperplane arrangements. First we state the following

Convention: An affine oriented hyperplane $H$ in $\mathbb{R}^{n}$ consists of an affine hyperplane $H$ together with a partition

$$
\begin{equation*}
\mathbb{R}^{n}=H^{-} \uplus H \uplus H^{+} \tag{2.1}
\end{equation*}
$$

where $H^{-}$and $H^{+}$are specified open and convex half-spaces. Of course, $H^{-}$and $H^{+}$are - up to the order - uniquely determined.

Thus, if we speak about an affine oriented hyperplane $H$, we shall always assume that a partition as in (2.1) is given. To choose some affine oriented hyperplane $H$ will mean that $H^{-}$and $H^{+}$may be selected arbitrarily.

In the sequel, $W_{n}=\{1,-1\}^{n}$ will denote the vertex set of the $n$-cube for fixed $n \geq 1$.
Definition 2.1 Assume $l \geq 1$, and $A, B$ are subsets of $\mathbb{R}^{l}$. $A$ and $B$ will be called linearly separable, if there exists some affine oriented hyperplane $H$ in $\mathbb{R}^{l}$ with $A \subseteq H^{+}$and $B \subseteq H^{-}$.

Conventions: Assume $\mathcal{H}=\left(H_{1}, \ldots, H_{l}\right)$ is some l-tuple of affine oriented hyperplanes in $\mathbb{R}^{n}$ which is generic, that means

$$
W_{n} \cap \bigcup_{i=1}^{l} H_{i}=\emptyset
$$

For $1 \leq i \leq l$ we define the map $\varphi_{i}(\mathcal{H}): W_{n} \rightarrow\{1,-1\}$ by

$$
\varphi_{i}(\mathcal{H})(x):=\varphi_{i}(\mathcal{H}, x):=\left\{\begin{array}{cll}
1 & \text { if } & x \in H_{i}^{+}  \tag{2.2}\\
-1 & \text { if } & x \in H_{i}^{-}
\end{array} .\right.
$$

Now $\varphi(\mathcal{H}): W_{n} \rightarrow W_{l}$ will denote the map given by

$$
\begin{equation*}
\varphi(\mathcal{H})(x):=\varphi(\mathcal{H}, x):=\left(\varphi_{1}(\mathcal{H}, x), \ldots, \varphi_{l}(\mathcal{H}, x)\right) . \tag{2.3}
\end{equation*}
$$

For $C \subseteq W_{n}$ we write of course

$$
\begin{equation*}
\varphi(\mathcal{H})(C):=\varphi(\mathcal{H}, C):=\{\varphi(\mathcal{H}, x): x \in C\} . \tag{2.4}
\end{equation*}
$$

Definition 2.2 Assume $C \subseteq W_{n}$ and $\mathcal{H}=\left(H_{1}, \ldots, H_{l}\right)$ is some generic hyperplane arrangement of affine oriented hyperplanes in $\mathbb{R}^{n}$. We say that $\mathcal{H}$ separates the vertex set $C$, if the sets $\varphi(\mathcal{H}, C)$ and $\varphi\left(\mathcal{H}, W_{n}-C\right)$ are linearly separable (as subsets of $\mathbb{R}^{l}$ ).

From now on, we call a generic hyperplane arrangement $\left(H_{1}, \ldots, H_{l}\right)$ of affine oriented hyperplanes in $\mathbb{R}^{n}$ also an l-arrangement for brevity.
Definition 2.3 For $C \subseteq W_{n}$ with $\emptyset \neq C \neq W_{n}$ we put

$$
\begin{equation*}
h(C):= \tag{2.5}
\end{equation*}
$$

$\min \left\{l \in \mathbb{N}\right.$ : there exists some l-arrangement in $\mathbb{R}^{n}$ which separates $\left.C\right\}$.
By convention, we write

$$
\begin{equation*}
h(\emptyset)=h\left(W_{n}\right)=0 . \tag{2.6}
\end{equation*}
$$

## Remarks:

(i) By Definition 2.2, it is not trivial that every $C \subseteq W_{n}$ may be separated by some $l$-arrangement for an appropriate number $l \in \mathbb{N}$. However, we shall see later (c.f. Theorem 3.16) that every $C$ may be separated by at most $\frac{3}{n+2} \cdot 2^{n}$ affine hyperplanes; that means, we have

$$
h(C) \leq \frac{3}{n+2} \cdot 2^{n} .
$$

(ii) By the above definitions, a subset $C \subseteq W_{n}$ with $\emptyset \neq C \neq W_{n}$ satisfies $h(C)=1$ if and only if $C$ and $W_{n} \backslash C$ are linearly separable.
(iii) By Definition 2.2, every $C \subseteq W_{n}$ satisfies

$$
h(C)=h\left(W_{n} \backslash C\right)
$$

If $\mathcal{H}$ separates $C$, then one has $\varphi(\mathcal{H}, C) \cap \varphi\left(\mathcal{H}, W_{n} \backslash C\right)=\emptyset$.
(iv) By symmetry of the $l$-cube, for some $l$-arrangement $\left(H_{1}, \ldots, H_{l}\right)$ to separate a set $C \subseteq W_{n}$ it does not matter in which way the half spaces corresponding to $H_{1}, \ldots, H_{l}$ are oriented.

Example 2.4 (The XOR-Problem) Assume $n=2$, and put

$$
A:=\{(1,1),(-1,-1)\}, \quad B:=\{(1,-1),(-1,1)\} .
$$

If $C \subseteq W_{2}$ satisfies $C \neq A$ and $C \neq B$, then $C$ and $W_{2} \backslash C$ are linearly separable. However $A$ and $B$ are not linearly separable, because

$$
(0,0) \in \operatorname{conv} A \cap \operatorname{conv} B
$$

where conv denotes the convex closure operator.
For $i \in\{1,2\}$ put

$$
H_{i}:=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}: x_{1}+x_{2}=3-2 i\right\}
$$

as well as

$$
\begin{aligned}
H_{i}^{+} & :=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}: x_{1}+x_{2}>3-2 i\right\} \\
H_{i}^{-} & :=\mathbb{R}^{2} \backslash\left(H_{i} \cup H_{i}^{+}\right) .
\end{aligned}
$$

Then $\mathcal{H}=\left(H_{1}, H_{2}\right)$ is some 2-arrangement separating $A$ and $B$ : We get

$$
\begin{aligned}
\varphi(\mathcal{H})(\{(1,1)\}) & =\{(1,1)\}, \\
\varphi(\mathcal{H})(\{(1,-1),(-1,1)\}) & =\{(-1,1)\}, \\
\varphi(\mathcal{H})(\{(-1,-1)\}) & =\{(-1,-1)\}
\end{aligned}
$$

and thus

$$
\begin{aligned}
\varphi(\mathcal{H}, A) & =\{(1,1),(-1,-1)\}=: A^{\prime} \\
\varphi(\mathcal{H}, B) & =\{(-1,1)\}=: B^{\prime}
\end{aligned}
$$

Of course, $A^{\prime}$ and $B^{\prime}$ are linearly separable in $\mathbb{R}^{2}$. We obtain $h(A)=h(B)=2$.


Figure 1: Two hyperplanes separating the input patterns of the XOR-problem (Example 2.4), and the separating hyperplane for their image under $\varphi$.

In what follows, $\langle\cdot, \cdot\rangle$ will denote the standard scalar product in $\mathbb{R}^{l}$; that means, for $v=\left(v_{1}, \ldots, v_{l}\right) \in \mathbb{R}^{l}$ and $w=\left(w_{1}, \ldots, w_{l}\right) \in \mathbb{R}^{l}$ we write

$$
\langle v, w\rangle:=\sum_{i=1}^{l} v_{i} \cdot w_{i} .
$$

Next we prove the following simple
Lemma 2.5 Assume the l-arrangement $\mathcal{H}=\left(H_{1}, \ldots, H_{l}\right)$ separates the set $C \subseteq$ $W_{n}$. Then the following holds:
(i) If $\sigma \in S_{l}$ is some permutation, then $\left(H_{\sigma(1)}, \ldots, H_{\sigma(l)}\right)$ separates the set $C$, too.
(ii) If $W_{n} \subseteq H_{l}^{+}$or $W_{n} \subseteq H_{l}^{-}$, then $\mathcal{H}^{\prime}=\left(H_{1}, \ldots, H_{l-1}\right)$ separates $C$.
(iii) If $W_{n} \cap H_{l-1}^{+}=W_{n} \cap H_{l}^{+}$or $W_{n} \cap H_{l-1}^{+}=W_{n} \cap H_{l}^{-}$, then $\mathcal{H}^{\prime}=\left(H_{1}, \ldots, H_{l-1}\right)$ separates $C$. In particular, $\mathcal{H}^{\prime}=\left(H_{1}, \ldots, H_{l-1}\right)$ separates $C$ in case $H_{l-1}=H_{l}$.
(iv) If $H_{l+1}$ is any affine oriented hyperplane in $\mathbb{R}^{n}$ with $H_{l+1} \cap W_{n}=\emptyset$, then $\mathcal{H}^{\prime \prime}=\left(H_{1}, \ldots, H_{l}, H_{l+1}\right)$ separates $C$, too.

## Proof.

(i) If $A, B \subseteq \mathbb{R}^{l}$ are linearly separable by some affine oriented hyperplane $H$ in $\mathbb{R}^{l}$ and $\alpha: \mathbb{R}^{l} \rightarrow \mathbb{R}^{l}$ is some bijective affine map, then $\alpha(A)$ and $\alpha(B)$ are of course linearly separable by the affine hyperplane $\alpha(H)$; here we may put $\alpha(H)^{+}:=\alpha\left(H^{+}\right)$and $\alpha(H)^{-}:=\alpha\left(H^{-}\right)$. This holds in particular if $\alpha$ is some linear isomorphism which merely permutes coordinates.
(ii) Without loss of generality, we may assume $\emptyset \neq C \neq W_{n}$ and $W_{n} \subseteq H_{l}^{+}$. Thus for all $x \in W_{n}$ one has $\varphi_{l}(\mathcal{H}, x)=1$. Assume $\varphi(\mathcal{H}, C)$ and $\varphi\left(\mathcal{H}, W_{n} \backslash C\right)$ are linearly separable by the affine oriented hyperplane $H$ in $\mathbb{R}^{l}$. Then for suitable $w=\left(w_{1}, \ldots, w_{l}\right) \in \mathbb{R}^{l} \backslash\{0\}$ and $t \in \mathbb{R}$ we get

$$
\begin{gathered}
H=\left\{v \in \mathbb{R}^{l}:\langle v, w\rangle=t\right\} \\
\varphi(\mathcal{H}, C) \subseteq H^{+}=\left\{v \in \mathbb{R}^{l}:\langle v, w\rangle>t\right\} \\
\varphi\left(\mathcal{H}, W_{n} \backslash C\right) \subseteq H^{-}=\left\{v \in \mathbb{R}^{l}:\langle v, w\rangle<t\right\} .
\end{gathered}
$$

Thus, for $w^{\prime}:=\left(w_{1}, \ldots, w_{l-1}\right)$ we get

$$
\begin{gathered}
\varphi\left(\mathcal{H}^{\prime}, C\right) \subseteq\left\{v^{\prime} \in \mathbb{R}^{l-1}:\left\langle v^{\prime}, w^{\prime}\right\rangle>t-w_{l}\right\}, \\
\varphi\left(\mathcal{H}^{\prime}, W_{n} \backslash C\right) \subseteq\left\{v^{\prime} \in \mathbb{R}^{l-1}:\left\langle v^{\prime}, w^{\prime}\right\rangle<t-w_{l}\right\} .
\end{gathered}
$$

In particular, we have $w^{\prime} \neq 0$, because $C \neq \emptyset \neq W_{n} \backslash C$. Thus, $\varphi\left(\mathcal{H}^{\prime}, C\right)$ and $\varphi\left(\mathcal{H}^{\prime}, W_{n} \backslash C\right)$ are linearly separable by the affine hyperplane

$$
H^{\prime}:=\left\{v^{\prime} \in \mathbb{R}^{l-1}:\left\langle v^{\prime}, w^{\prime}\right\rangle=t-w_{l}\right\} .
$$

(iii) Without loss of generality, we may suppose $W_{n} \cap H_{l-1}^{+}=W_{n} \cap H_{l}^{+}$and $\emptyset \neq C \neq W_{n}$. Assume again that $w=\left(w_{1}, \ldots, w_{l}\right) \in \mathbb{R}^{l} \backslash\{0\}$ and $t \in \mathbb{R}$ satisfy

$$
\begin{gathered}
\varphi(\mathcal{H}, C) \subseteq\left\{v \in \mathbb{R}^{l}:\langle v, w\rangle>t\right\} \\
\varphi\left(\mathcal{H}, W_{n} \backslash C\right) \subseteq\left\{v \in \mathbb{R}^{l}:\langle v, w\rangle<t\right\} .
\end{gathered}
$$

Now put $w^{\prime}:=\left(w_{1}, \ldots, w_{l-2}, w_{l-1}+w_{l}\right)$. Since every $v=\left(v_{1}, \ldots, v_{l}\right) \in \varphi\left(\mathcal{H}, W_{n}\right)$ satisfies $v_{l-1}=v_{l}$, we get

$$
\begin{gathered}
\varphi\left(\mathcal{H}^{\prime}, C\right) \subseteq\left\{v^{\prime} \in \mathbb{R}^{l-1}:\left\langle v^{\prime}, w^{\prime}\right\rangle>t\right\}, \\
\varphi\left(\mathcal{H}^{\prime}, W_{n} \backslash C\right) \subseteq\left\{v^{\prime} \in \mathbb{R}^{l-1}:\left\langle v^{\prime}, w^{\prime}\right\rangle<t\right\} .
\end{gathered}
$$

Now $C \neq \emptyset \neq W_{n} \backslash C$ implies $w^{\prime} \neq 0$; therefore, $\varphi\left(\mathcal{H}^{\prime}, C\right)$ and $\varphi\left(\mathcal{H}^{\prime}, W_{n} \backslash C\right)$ are linearly separable by the affine hyperplane

$$
H^{\prime}:=\left\{v^{\prime} \in \mathbb{R}^{l-1}:\left\langle v^{\prime}, w^{\prime}\right\rangle=t\right\} .
$$

(iv) Choose once more $w=\left(w_{1}, \ldots, w_{l}\right) \in \mathbb{R}^{l} \backslash\{0\}$ and $t \in \mathbb{R}$ with

$$
\begin{gathered}
\varphi(\mathcal{H}, C) \subseteq\left\{v \in \mathbb{R}^{l}:\langle v, w\rangle>t\right\} \\
\varphi\left(\mathcal{H}, W_{n} \backslash C\right) \subseteq\left\{v \in \mathbb{R}^{l}:\langle v, w\rangle\langle t\} .\right.
\end{gathered}
$$

Now put $w^{\prime \prime}:=\left(w_{1}, \ldots, w_{l}, 0\right)$. Then we get

$$
\begin{gathered}
\varphi\left(\mathcal{H}^{\prime \prime}, C\right) \subseteq\left\{v^{\prime \prime} \in \mathbb{R}^{l+1}:\left\langle v^{\prime \prime}, w^{\prime \prime}\right\rangle>t\right\}, \\
\varphi\left(\mathcal{H}^{\prime \prime}, W_{n} \backslash C\right) \subseteq\left\{v^{\prime \prime} \in \mathbb{R}^{l+1}:\left\langle v^{\prime \prime}, w^{\prime \prime}\right\rangle\langle t\} .\right.
\end{gathered}
$$

Thus, $\varphi\left(\mathcal{H}^{\prime \prime}, C\right)$ and $\varphi\left(\mathcal{H}^{\prime \prime}, W_{n} \backslash C\right)$ are linearly separable by the affine hyperplane

$$
H^{\prime}:=\left\{v^{\prime \prime} \in \mathbb{R}^{l+1}:\left\langle v^{\prime \prime}, w^{\prime \prime}\right\rangle=t\right\} .
$$

The next result shows that several subsets $C \subseteq W_{n}$ consisting of certain layers may be separated by some hyperplane arrangement which is induced by these layers in a canonical way.

Proposition 2.6 Let $\mathcal{H}=\left(H_{1}, \ldots, H_{l}\right)$ denote some l-arrangement in $\mathbb{R}^{n}$ satisfying

$$
\begin{equation*}
H_{i}^{+} \cap W_{n} \subseteq H_{i+1}^{+} \quad \text { for } \quad 1 \leq i \leq l-1 . \tag{2.7}
\end{equation*}
$$

Choose affine oriented hyperplanes $H_{0}, H_{l+1}$ in $\mathbb{R}^{n}$ with $H_{0}^{+} \cap W_{n}=\emptyset$ and $W_{n} \subseteq$ $H_{l+1}^{+}$.
Let $C \subseteq W_{n}$ denote that subset of vertices of the $n$-cube such that for every $i$ with $0 \leq i \leq l$ one has

$$
W_{n} \cap\left(H_{i+1}^{+} \backslash H_{i}^{+}\right) \subseteq\left\{\begin{array}{ccc}
C & \text { for } & i \equiv 1 \bmod 2  \tag{2.8}\\
W_{n} \backslash C & \text { for } & i \equiv 0 \bmod 2
\end{array} .\right.
$$

Then $\mathcal{H}$ separates the set $C$.

Proof. By the assumptions of the proposition, for every $x \in W_{n}$ there exists some unique $i$ with $0 \leq i \leq l$ satisfying $x \in H_{i}^{-} \cap H_{i+1}^{+}$. We get

$$
\begin{equation*}
\varphi(\mathcal{H}, x)=(\underbrace{-1, \ldots,-1}_{i}, \underbrace{1, \ldots, 1}_{l-i}), \tag{2.9}
\end{equation*}
$$

and (2.8) implies

$$
x \in\left\{\begin{array}{ccc}
C & \text { for } & i \equiv 1 \bmod 2  \tag{2.10}\\
W_{n} \backslash C & \text { for } & i \equiv 0 \bmod 2
\end{array} .\right.
$$

Put

$$
a:=\left\{\begin{array}{ccc}
0 & \text { for } & l \equiv 1 \bmod 2 \\
-1 & \text { for } & l \equiv 0 \bmod 2
\end{array},\right.
$$

and define the linear map $f: \mathbb{R}^{l} \rightarrow \mathbb{R}$ by

$$
f\left(v_{1}, \ldots, v_{l}\right):=\sum_{i=1}^{l}(-1)^{i+1} \cdot v_{i} .
$$

Consider the affine oriented hyperplane $G$ in $\mathbb{R}^{l}$ given by

$$
\begin{aligned}
G & :=\left\{v \in \mathbb{R}^{l}: f(v)=a\right\}, \\
G^{+} & :=\left\{v \in \mathbb{R}^{l}: f(v)>a\right\}, \\
G^{-} & :=\left\{v \in \mathbb{R}^{l}: f(v)<a\right\} .
\end{aligned}
$$

Then (2.9) and (2.10) imply

$$
\begin{gathered}
\varphi(\mathcal{H}, x) \in G^{-} \quad \text { for } \quad x \in C, \\
\varphi(\mathcal{H}, x) \in G^{+} \quad \text { for } \quad x \in W_{n} \backslash C .
\end{gathered}
$$

Thus $\varphi(\mathcal{H}, C)$ and $\varphi\left(\mathcal{H}, W_{n} \backslash C\right)$ are linearly separable by $G$.
Remark: The affine oriented hyperplanes $H_{0}$ and $H_{l+1}$ in the last result are of course only used for technical reasons.

One of the most important applications of Proposition 2.6 is to study the following

Problem 2.7 (Parity Problem) For $n \geq 1 p u t^{1}$

$$
\begin{equation*}
C_{P}(n):=\left\{\left(x_{1}, \ldots, x_{n}\right) \in W_{n}:\left|\left\{i: x_{i}=-1\right\}\right| \equiv 1 \bmod 2\right\} . \tag{2.11}
\end{equation*}
$$

Separate $C_{P}(n)$.

[^1]The following theorem gives an upper bound for $h\left(C_{P}(n)\right)$.
Theorem 2.8 For all $n \geq 1$ one has

$$
\begin{equation*}
h\left(C_{P}(n)\right) \leq n ; \tag{2.12}
\end{equation*}
$$

that is, $C_{P}(n)$ may be separated by some $n$-arrangement $\left(H_{1}, \ldots, H_{n}\right)$.
Proof. For $0 \leq i \leq n+1$ put

$$
\begin{aligned}
H_{i} & :=\left\{\left(v_{1}, \ldots, v_{n}\right) \in \mathbb{R}^{n}: \sum_{j=1}^{n} v_{j}=n+1-2 i\right\} \\
H_{i}^{+} & :=\left\{\left(v_{1}, \ldots, v_{n}\right) \in \mathbb{R}^{n}: \sum_{j=1}^{n} v_{j}>n+1-2 i\right\}, \\
H_{i}^{-} & :=\mathbb{R}^{n} \backslash\left(H_{i} \cup H_{i}^{+}\right) .
\end{aligned}
$$

Then $H_{0}, H_{1}, \ldots, H_{n}, H_{n+1}$ and $C=C_{P}(n)$ fulfill the assumptions of Proposition 2.6; thus $\mathcal{H}=\left(H_{1}, \ldots, H_{n}\right)$ separates $C_{P}(n)$.

## 3 Separations of Unions

In this section, we want to study unions of subsets of $W_{n}$ and show that - under some certain supposition - separations of these subsets induce some separation of their union. Concerning the additional assumption, we state the following

Definition 3.1 Assume $C \subseteq W_{n}$. An l-arrangement $\mathcal{H}=\left(H_{1}, \ldots, H_{l}\right)$ is called a centered image separation of $C$, if there exists some affine hyperplane $G$ in $\mathbb{R}^{l}$, some affine map $f_{G}: \mathbb{R}^{l} \rightarrow \mathbb{R}$ with $G=f_{G}^{-1}(\{0\})$ as well as some $d>0$ such that for $x \in W_{n}$ one has

$$
f_{G}(\varphi(\mathcal{H}, x))=\left\{\begin{array}{cll}
d & \text { for } & x \in C  \tag{3.1}\\
-d & \text { for } & x \in W_{n} \backslash C
\end{array} .\right.
$$

In other words, the following two conditions hold:
(i) $\varphi(\mathcal{H}, C)$ and $\varphi\left(\mathcal{H}, W_{n} \backslash C\right)$ are linearly separable by $G$. (This means that $\mathcal{H}$ separates $C$.)
(ii) All points $\varphi(\mathcal{H}, x), x \in W_{n}$, have the same distance to $G$.

## Examples 3.2

(i) Assume $l=1$; that is, $C$ and $W_{n} \backslash C$ are linearly separable by some affine oriented hyperplane $H \subseteq \mathbb{R}^{n}$. Then the single hyperplane arrangement $\mathcal{H}=(H)$ is a centered image separation of $C$ :
If, say, $C \subseteq H^{+}$and $W_{n} \backslash C \subseteq H^{-}$, we get

$$
\varphi(\mathcal{H}, x)=\left\{\begin{array}{cll}
1 & \text { for } & x \in C \\
-1 & \text { for } & x \in W_{n} \backslash C
\end{array} .\right.
$$

Thus (3.1) holds for $d=1, G=\{0\} \subseteq \mathbb{R}$ and the identity map $f_{G}: \mathbb{R} \rightarrow \mathbb{R}$.
(ii) Assume $l=2, C \subseteq W_{n}$, and $H_{1}, H_{2} \subseteq \mathbb{R}^{n}$ are affine oriented hyperplanes satisfying

$$
\begin{gather*}
C \subseteq H_{1}^{+} \cap H_{2}^{-},  \tag{3.2}\\
W_{n} \backslash C \subseteq\left(H_{1}^{+} \cap H_{2}^{+}\right) \cup\left(H_{1}^{-} \cap H_{2}^{-}\right) . \tag{3.3}
\end{gather*}
$$

Then $\mathcal{H}:=\left(H_{1}, H_{2}\right)$ is a centered image separation of $C$ :
Put $G:=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}: x_{1}-x_{2}=1\right\}$, and define $f_{G}: \mathbb{R}^{2} \rightarrow \mathbb{R}$ by $f_{G}\left(x_{1}, x_{2}\right):=$ $x_{1}-x_{2}-1$. Then we have $G=f_{G}^{-1}(\{0\})$ as well as

$$
f_{G}(\varphi(\mathcal{H}, x))=\left\{\begin{array}{cll}
1 & \text { for } & x \in C  \tag{3.4}\\
-1 & \text { for } & x \in W_{n} \backslash C
\end{array} .\right.
$$

Example 3.3 Assume $n=2$, and put $C:=\{(1,1)\}$ as well as

$$
\begin{aligned}
H_{0} & :=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}: x_{1}+x_{2}=1\right\}, \\
H_{1} & :=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}: x_{1}=0\right\}, \\
H_{2} & :=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}: x_{2}=0\right\} .
\end{aligned}
$$



Figure 2: The two hyperplane arrangements $\mathcal{H}:=\left(H_{1}, H_{2}\right)$ and $\left(H_{0}\right)$ of Example 3.3.
$C$ and $W_{2} \backslash C$ are linearly separable by $H_{0}$; thus, by Example 3.2 (i), the single hyperplane arrangement $\left(H_{0}\right)$ is a centered image separation of $C$.
Moreover, $\mathcal{H}:=\left(H_{1}, H_{2}\right)$ separates $C$, too; however, $\mathcal{H}$ is not some centered image separation of $C$. Indeed, $\varphi(\mathcal{H}): W_{2} \rightarrow W_{2}$ is - without loss of generality - the identity map, and $G:=H_{0}$ is the unique affine hyperplane in $\mathbb{R}^{2}$ which linearly separates $C$ from $W_{2} \backslash C$ such that the three points $(1,1),(-1,1)$ and $(1,-1)$ have the same distance to $G$; however, $(-1,-1)$ has some larger distance to $G=H_{0}$.

Now we can prove the following
Proposition 3.4 Assume $C \subseteq W_{n}$, and $C_{1}, \ldots, C_{m} \subseteq W_{n}$ satisfy

$$
\begin{equation*}
C=\bigcup_{i=1}^{m} C_{i} \tag{3.5}
\end{equation*}
$$

For every $i$ with $1 \leq i \leq m$, assume that $\mathcal{H}_{i}=\left(H_{1}^{i}, \ldots, H_{l_{i}}^{i}\right)$ is some centered image separation of $C_{i}$. Then the composed hyperplane arrangement

$$
\mathcal{H}:=\left(H_{1}^{1}, \ldots, H_{l_{1}}^{1}, \ldots, H_{1}^{m}, \ldots, H_{l_{m}}^{m}\right)
$$

separates the vertex set $C$.
Proof. By assumption, for every $i$ with $1 \leq i \leq m$ there exists some $d_{i}>0$ as well as some nonconstant affine map $f_{i}: \mathbb{R}^{l_{i}} \rightarrow \mathbb{R}$ satisfying

$$
f_{i}\left(\varphi\left(\mathcal{H}_{i}, x\right)\right)=\left\{\begin{array}{cll}
d_{i} & \text { for } & x \in C_{i} \\
-d_{i} & \text { for } & x \in W_{n} \backslash C_{i}
\end{array} .\right.
$$

Now put $l:=\sum_{i=1}^{m} l_{i}$, and define the affine map $f: \mathbb{R}^{l} \rightarrow \mathbb{R}$ by

$$
f\left(a_{1}^{(1)}, \ldots, a_{l_{1}}^{(1)}, \ldots, a_{1}^{(m)}, \ldots, a_{l_{m}}^{(m)}\right):=\sum_{i=1}^{m} f_{i}\left(a_{1}^{(i)}, \ldots, a_{l_{i}}^{(i)}\right) .
$$

Put $d:=\min \left\{d_{1}, \ldots, d_{m}\right\}$. Then we get:

$$
\begin{align*}
& f(\varphi(\mathcal{H}, x)) \geq 2 d-\sum_{i=1}^{m} d_{i} \quad \text { for } \quad x \in C  \tag{3.6}\\
& f(\varphi(\mathcal{H}, x))=-\sum_{i=1}^{m} d_{i} \quad \text { for } \quad x \in W_{n} \backslash C \tag{3.7}
\end{align*}
$$

Thus, $\varphi(\mathcal{H}, C)$ and $\varphi\left(\mathcal{H}, W_{n} \backslash C\right)$ are linearly separable by the affine hyperplane

$$
H:=\left\{\left(a_{1}, \ldots, a_{l}\right) \in \mathbb{R}^{l}: f\left(a_{1}, \ldots, a_{l}\right)=d-\sum_{i=1}^{m} d_{i}\right\}
$$

Remark: Unfortunately, the last result becomes wrong if we do not suppose that each $\mathcal{H}_{i}$ is some centered image separation of $C_{i}$ but only assume that $\mathcal{H}_{i}$ separates $C_{i}$.
Consider once more Example 3.3, assume $H_{1}, H_{2}$ are as in this example, but now put $C^{\prime}:=\{(1,1),(-1,-1)\}$. The hyperplane arrangement $\mathcal{H}=\left(H_{1}, H_{2}\right)$ separates both of the sets $\{(1,1)\}$ and $\{(-1,-1)\}$. However, the composed hyperplane arrangement $\mathcal{H}^{\prime}:=\left(H_{1}, H_{2}, H_{1}, H_{2}\right)$ does not separate $C^{\prime}$, because otherwise Lemma 2.5 would imply that $\mathcal{H}$ separates $C^{\prime}$, too. But this is not the case.

As an important special case of Proposition 3.4, we get

Proposition 3.5 Assume $C, C_{1}, \ldots, C_{m} \subseteq W_{n}$ satisfy

$$
C=\bigcup_{i=1}^{m} C_{i} .
$$

Moreover, suppose that for each $i$ with $1 \leq i \leq m$, the sets $C_{i}$ and $W_{n} \backslash C_{i}$ are linearly separable by some affine oriented hyperplane $H_{i}$ in $\mathbb{R}^{n}$. Then $\mathcal{H}:=$ $\left(H_{1}, \ldots, H_{m}\right)$ separates the set $C$.

Proof. This result is a trivial consequence of Example 3.2 (i) and Proposition 3.4 .

We can now also prove that each subset $C \subseteq W_{n}$ may be separated by some $l$-arrangement for an appropriate number $l \in \mathbb{N}$. More precisely, we get the following

## Theorem 3.6

(i) For each $x \in W_{n}$, the sets $\{x\}$ and $W_{n} \backslash\{x\}$ are linearly separable.
(ii) Each subset $C \subseteq W_{n}$ may be separated by some l-arrangement consisting of $l \leq 2^{n-1}$ affine oriented hyperplanes; that is, one has

$$
\begin{equation*}
h(C) \leq 2^{n-1} . \tag{3.8}
\end{equation*}
$$

## Proof.

(i) We write $x=\left(\varepsilon_{1}, \ldots, \varepsilon_{n}\right)$ with $\varepsilon_{i} \in\{-1,1\}$ for $1 \leq i \leq n$. Then the sets $\{x\}$ and $W_{n} \backslash\{x\}$ are linearly separable by the affine hyperplane

$$
H:=\left\{\left(v_{1}, \ldots, v_{n}\right) \in \mathbb{R}^{n}: \sum_{i=1}^{n} \varepsilon_{i} \cdot v_{i}=n-1\right\} .
$$

(ii) By Remark (iii) following Definition 2.3, we have $h(C)=h\left(W_{n} \backslash C\right)$; therefore, we may assume $|C| \leq\left|W_{n} \backslash C\right|$ and thus $|C| \leq 2^{n-1}$. But then (3.8) follows trivially from (i) and Proposition 3.5.

At the end of this section, we improve the inequality (3.8).
As a further consequence of Proposition 3.4, we prove
Proposition 3.7 Assume $C, C_{1}, \ldots, C_{m} \subseteq W_{n}$ satisfy

$$
C=\bigcup_{i=1}^{m} C_{i} .
$$

Moreover, for $1 \leq i \leq m$ suppose that there exist affine oriented hyperplanes $G_{i}, H_{i} \subseteq \mathbb{R}^{n}$ as well as subsets $A_{i}, B_{i} \subseteq W_{n}$ satisfying

$$
\begin{gather*}
W_{n}=A_{i} \uplus B_{i} \uplus C_{i},  \tag{3.9}\\
\varphi\left(\left(G_{i}, H_{i}\right), x\right)=\left\{\begin{array}{ccc}
(-1,-1) & \text { for } & x \in A_{i} \\
(1,-1) & \text { for } & x \in C_{i} \\
(1,1) & \text { for } & x \in B_{i}
\end{array}\right. \tag{3.10}
\end{gather*} .
$$

Then the composed hyperplane arrangement $\left(G_{1}, H_{1}, \ldots, G_{m}, H_{m}\right)$ separates the set $C$.

Proof. In view of (3.9) and (3.10) we may conclude by Example 3.2 (ii) that for each $i$ with $1 \leq i \leq m$, the pair $\left(G_{i}, H_{i}\right)$ is a centered image separation of $C_{i}$. Thus Proposition 3.4 yields what we want.

As a special case of Proposition 3.7, we want to point out the following
Proposition 3.8 Suppose $C, C_{1}, \ldots, C_{m} \subseteq W_{n}$ satisfy

$$
C=\bigcup_{i=1}^{m} C_{i}
$$

Moreover, assume that for each $i$ with $1 \leq i \leq m$ there exists some affine hyperplane $K_{i}$ in $\mathbb{R}^{n}$ satisfying

$$
\begin{equation*}
W_{n} \cap K_{i}=C_{i} . \tag{3.11}
\end{equation*}
$$

Then one has $h(C) \leq 2 m$.
Proof. For $1 \leq i \leq m$, we may choose affine oriented hyperplanes $G_{i}, H_{i}$ in $\mathbb{R}^{n}$ which are parallel to $K_{i}$ such that the following conditions hold:

$$
\begin{gathered}
\left(G_{i} \cup H_{i}\right) \cap W_{n}=\emptyset, \\
G_{i}^{-} \cap H_{i}^{+}=\emptyset, \\
G_{i}^{+} \cap H_{i}^{-} \cap W_{n}=K_{i} \cap W_{n}=C_{i} .
\end{gathered}
$$

Now we can apply Proposition 3.7 to the sets

$$
A_{i}:=W_{n} \cap G_{i}^{-} \cap H_{i}^{-}, \quad B_{i}:=W_{n} \cap G_{i}^{+} \cap H_{i}^{+}
$$

and conclude that the hyperplane arrangement $\left(G_{1}, H_{1}, \ldots, G_{m}, H_{m}\right)$ separates $C$.

In the last part of this section, we want to improve - for all $C \subseteq W_{n}$ - the upper bound for $h(C)$ as stated in Theorem 3.6 (ii). For this purpose, we study so called frames which cover $W_{n}$. First of all, we recall the following

Definition 3.9 The Hamming distance on $W_{n}$ is the metric $d_{H}: W_{n} \times W_{n} \rightarrow$ $\{0,1, \ldots, n\}$ defined by

$$
\begin{equation*}
d_{H}\left(\left(x_{1}, \ldots, x_{n}\right),\left(x_{1}^{\prime}, \ldots, x_{n}^{\prime}\right)\right):=\left|\left\{i: x_{i} \neq x_{i}^{\prime}\right\}\right| . \tag{3.12}
\end{equation*}
$$

Definition 3.10 $A$ subset $F \subseteq W_{n}$ is called $a$ frame in $W_{n}$, if $F$ consists of $a$ distinguished element $y_{0} \in W_{n}$, called the root of $F$, as well as all its neighbours with respect to $d_{H}$; that is

$$
\begin{equation*}
F=\left\{y_{0}\right\} \cup\left\{y \in W_{n}: d_{H}\left(y, y_{0}\right)=1\right\} . \tag{3.13}
\end{equation*}
$$

Clearly, every frame $F$ in $W_{n}$ satisfies $|F|=n+1$.
The following result shows why we are interested to study frames in $W_{n}$.
Proposition 3.11 Assume $F_{1}, \ldots, F_{m}$ are frames in $W_{n}$ which cover $W_{n}$; that means, one has

$$
\begin{equation*}
W_{n}=\bigcup_{i=1}^{m} F_{i} . \tag{3.14}
\end{equation*}
$$

Then for every $C \subseteq W_{n}$ we have

$$
\begin{equation*}
h(C) \leq \frac{3}{2} \cdot m \tag{3.15}
\end{equation*}
$$

Proof. Let $y_{1}, \ldots, y_{m}$ denote the roots of $F_{1}, \ldots, F_{m}$, respectively. By symmetry, we may assume that there exists some $t$ with $\frac{m}{2} \leq t \leq m$ such that $y_{1}, \ldots, y_{t} \in C$ as well as $y_{t+1}, \ldots, y_{m} \in W_{n} \backslash C$. (If $t<\frac{m}{2}$, Remark (iii) following Definition 2.3 shows that we may exchange the roles of $C$ and $W_{n} \backslash C$.)
Put $C_{i}:=C \cap F_{i}$ for $1 \leq i \leq m$.
We prove that $C_{1}, \ldots, C_{t}$ may be separated by one single hyperplane and that $C_{t+1}, \ldots, C_{m}$ may be separated by some centered image separation consisting of two hyperplanes. Finally, we shall apply Proposition 3.4.
For $1 \leq i \leq m$, write $y_{i}=\left(\varepsilon_{i 1}, \ldots, \varepsilon_{i n}\right)$, and for $1 \leq j \leq n$ let $y_{i j}$ denote the unique vertex in $F_{i}$ which differs from $y_{i}$ exactly in the $j$-th component. Put

$$
\begin{gathered}
J_{i}:=\left\{j \in\{1, \ldots, n\}: y_{i j} \in C_{i}\right\}, \quad j_{i}:=\left|J_{i}\right|, \\
K_{i}:=\{1, \ldots, n\} \backslash J_{i}, \quad k_{i}:=\left|K_{i}\right| .
\end{gathered}
$$

Assume first that $1 \leq i \leq t$, that means $y_{i}=\left(\varepsilon_{i 1}, \ldots, \varepsilon_{i n}\right) \in C_{i}$. In this case, define the linear map $f_{i}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ by

$$
f_{i}\left(v_{1}, \ldots, v_{n}\right):=\sum_{j \in J_{i}} \varepsilon_{i j} \cdot v_{j}+3 \cdot \sum_{j \in K_{i}} \varepsilon_{i j} \cdot v_{j},
$$

and define the affine oriented hyperplane $H_{i}$ in $\mathbb{R}^{n}$ by

$$
\begin{aligned}
H_{i} & :=\left\{v \in \mathbb{R}^{n}: f_{i}(v)=n+2 \cdot k_{i}-3\right\}, \\
H_{i}^{+} & :=\left\{v \in \mathbb{R}^{n}: f_{i}(v)>n+2 \cdot k_{i}-3\right\}, \\
H_{i}^{-} & :=\mathbb{R}^{n} \backslash\left(H_{i} \cup H_{i}^{+}\right) .
\end{aligned}
$$

Then one has

$$
\begin{aligned}
f_{i}\left(y_{i}\right) & =f_{i}\left(\varepsilon_{i 1}, \ldots, \varepsilon_{i n}\right)=n+2 \cdot k_{i}, \\
f_{i}\left(y_{i j}\right) & =n+2 \cdot k_{i}-2 \quad \text { for } j \in J_{i}, \\
f_{i}(w) & <n+2 \cdot k_{i}-3 \quad \text { for } w \in W_{n} \backslash C_{i} .
\end{aligned}
$$

Thus, we have $C_{i} \subseteq H_{i}^{+}$and $W_{n} \backslash C_{i} \subseteq H_{i}^{-}$. In particular, the single hyperplane arrangement $\left(H_{i}\right)$ is a centered image separation of $C_{i}$ (cf. Example 3.2 (i).)

Now, suppose $t<i \leq m$, that means $y_{i}=\left(\varepsilon_{i 1}, \ldots, \varepsilon_{i n}\right) \in W_{n} \backslash C_{i}$. In this case, define the linear map $f_{i}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ by

$$
f_{i}\left(v_{1}, \ldots, v_{n}\right):=3 \cdot \sum_{j \in J_{i}} \varepsilon_{i j} \cdot v_{j}+\sum_{j \in K_{i}} \varepsilon_{i j} \cdot v_{j},
$$

and define the affine oriented hyperplane $H_{i}$ in $\mathbb{R}^{n}$ by

$$
\begin{aligned}
H_{i} & :=\left\{v \in \mathbb{R}^{n}: f_{i}(v)=n+2 \cdot j_{i}-3\right\}, \\
H_{i}^{+} & :=\left\{v \in \mathbb{R}^{n}: f_{i}(v)>n+2 \cdot j_{i}-3\right\}, \\
H_{i}^{-} & :=\mathbb{R}^{n} \backslash\left(H_{i} \cup H_{i}^{+}\right) .
\end{aligned}
$$

Moreover, define the affine oriented hyperplane $G_{i}$ in $\mathbb{R}^{n}$ by

$$
\begin{aligned}
G_{i} & :=\left\{\left(v_{1}, \ldots, v_{n}\right) \in \mathbb{R}^{n}: \sum_{j=1}^{n} \varepsilon_{i j} \cdot v_{j}=n-3\right\}, \\
G_{i}^{+} & :=\left\{\left(v_{1}, \ldots, v_{n}\right) \in \mathbb{R}^{n}: \sum_{j=1}^{n} \varepsilon_{i j} \cdot v_{j}>n-3\right\}, \\
G_{i}^{-} & :=\mathbb{R}^{n} \backslash\left(G_{i} \cup G_{i}^{+}\right) .
\end{aligned}
$$

Then for $t<i \leq m$ one has

$$
\begin{aligned}
C_{i} & \subseteq H_{i}^{-} \cap G_{i}^{+}, \\
F_{i} \backslash C_{i} & \subseteq H_{i}^{+} \cap G_{i}^{+}, \\
W_{n} \backslash F_{i} & \subseteq H_{i}^{-} \cap G_{i}^{-} .
\end{aligned}
$$

Thus, Example 3.2 (ii) shows that $\left(H_{i}, G_{i}\right)$ is a centered image separation of $C_{i}$.

Altogether, Proposition 3.4 shows that

$$
\mathcal{H}:=\left(H_{1}, \ldots, H_{t}, H_{t+1}, G_{t+1}, \ldots, H_{m}, G_{m}\right)
$$

separates

$$
C=\bigcup_{i=1}^{m} C_{i} .
$$

Since we could assume $t \geq \frac{m}{2}$, we obtain

$$
h(C) \leq t+2 \cdot(m-t)=2 m-t \leq \frac{3}{2} \cdot m
$$

as claimed.

We still have the problem to cover $W_{n}$ by certain frames $F_{1}, \ldots, F_{m}$ for some $m$ as small as possible. Of course, there can exist a covering of pairwise disjoint frames only in case $n+1=2^{r}$ for some $r \in \mathbb{N}$. In this case, arguments from the theory of Linear Codes show that there exist indeed $\frac{2^{n}}{n+1}$ frames which cover $W_{n}$. First, we recall the following

Proposition 3.12 Assume $\mathbb{F}$ is a finite field with $q$ Elements, suppose $n, k, r \in \mathbb{N}$ satisfy $n=k+r$, and presume $3 \leq d \leq n$. Then the following two conditions are equivalent:
(i) There exists some $k$-dimensional subspace $U$ of the vector space $\mathbb{F}^{n}$ such that all $v, v^{\prime} \in U$ with $v \neq v^{\prime}$ differ in at least $d$ coordinates.
(ii) There exists some subset $A$ of the vector space $\mathbb{F}^{r}$ with $|A|=n$ such that every subset $I$ of $A$ with $|I|=d-1$ is linearly independent.

Proof. This is Satz 12.2 in [1].
Now, we identify - of course - the vertex set $W_{n}=\{1,-1\}^{n}$ with the vector space $\mathbb{F}_{2}{ }^{n}$ in the obvious way, where $\mathbb{F}_{2}=\{1,0\}$ denotes the field with 2 elements.
We can now prove
Proposition 3.13 Assume $n \geq 3$ satisfies $n+1=2^{r}$ for some $r \in \mathbb{N}$. Then there exist $\frac{2^{n}}{n+1}=2^{n-r}$ pairwise disjoint frames in $W_{n}$ which constitute a covering of $W_{n}$.

Proof. We apply Proposition 3.12 for $k=n-r$ and $d=3$. Put $A:=\mathbb{F}_{2}{ }^{r} \backslash\{0\}$; then every subset of $A$ consisting of 2 elements is linearly independent over $\mathbb{F}_{2}$. Since $|A|=2^{r}-1=n$, Proposition 3.12, (ii) $\Rightarrow$ (i), shows that there exists some $k$-dimensional subspace $U$ of $\mathbb{F}_{2}{ }^{n}$ such that all $v, v^{\prime} \in U$ with $v \neq v^{\prime}$ differ in at least 3 coordinates. This means - and that is the decisive conclusion - that all
of those frames in $\mathbb{F}_{2}{ }^{n}$ whose roots lie in $U$ are pairwise disjoint.
Moreover, we have

$$
|U|=2^{k}=2^{n-r}=\frac{2^{n}}{n+1}
$$

and this proves what we want, namely, that there exist $\frac{2^{n}}{n+1}$ pairwise disjoint frames in $W_{n}$. Since all of these frames have exactly $n+1$ vertices, they must of course cover $W_{n}$.

We still have to consider coverings of $W_{n}$ by frames in case $n+1$ is not a power of 2 . But then we make use of the following simple

Lemma 3.14 Assume $F_{1}, \ldots, F_{m}$ are frames in $W_{n}$ with

$$
W_{n}=\bigcup_{i=1}^{m} F_{i}
$$

Then there exist $2 m$ frames in $W_{n+1}$ covering $W_{n+1}$.
Proof. Let $y_{1}, \ldots, y_{m}$ denote the roots of the frames $F_{1}, \ldots, F_{m}$, respectively. Then the frames in $W_{n+1}$ exhibiting the roots

$$
\left(y_{1}, 1\right), \ldots,\left(y_{m}, 1\right),\left(y_{1},-1\right), \ldots,\left(y_{m},-1\right)
$$

satisfy what we want.
For $x \in \mathbb{R}$, let $[x]$ denote the Gaussian integer; that is the largest $k \in \mathbb{Z}$ satisfying $k \leq x$.
We can now prove
Proposition 3.15 Assume $n \geq 1$. Then there exist

$$
f_{n}:=2^{n-\left[\log _{2}(n+1)\right]}
$$

frames in $W_{n}$ which cover $W_{n}$. Moreover, one has

$$
\begin{equation*}
f_{n} \leq \frac{2^{n+1}}{n+2} \tag{3.16}
\end{equation*}
$$

Proof. For $n=1$ and $n=2$, the assertions are obvious, because in these special cases, there exists a covering of $W_{n}$ consisting of $n$ frames.
Now assume $n \geq 3$. The first assertion is clear by Proposition 3.13, if $n+1$ is a power of 2. If, on the other hand, $2^{r}<n+1<2^{r+1}$ holds for some $r \in \mathbb{N}$, the first assertion follows from Proposition 3.13 and a repeated application of Lemma 3.14 for the values $n^{\prime}=2^{r}-1, n^{\prime}=2^{r}, \ldots, n^{\prime}=n-1$. Note that

$$
\left[\log _{2}(n+1)\right]=r
$$

does not depend on $n$ as long as $2^{r} \leq n+1<2^{r+1}$.
To verify (3.16), assume again that $r \in \mathbb{N}$ satisfies $2^{r} \leq n+1 \leq 2^{r+1}-1$. Then we get $2^{-r} \leq \frac{2}{n+2}$ and thus

$$
f_{n}=2^{n-r} \leq \frac{2^{n+1}}{n+2}
$$

Now we can summarize Proposition 3.11 and Proposition 3.15 and obtain directly the following result, which is rather better than Theorem 3.6 (ii).

Theorem 3.16 For every $n \in \mathbb{N}$ and $C \subseteq W_{n}$ we have

$$
\begin{equation*}
h(C) \leq 3 \cdot 2^{n-1-\left[\log _{2}(n+1)\right]} \leq \frac{3}{n+2} \cdot 2^{n} \tag{3.17}
\end{equation*}
$$

In particular, one has $h(C)=\mathcal{O}\left(\frac{2^{n}}{n}\right)$.
Note that - in general - the second bound in (3.17) is of course slightly worse than the first bound; however, the second bound is more manageable.

## 4 A Worst Case Lower Bound for $h(C)$

In the last sections, we have been mainly interested in upper bounds for $h(C)$, $C \subseteq W_{n}$; Theorem 3.16 shows that $h(C)$ grows at most exponentially with $n$. In this section, we want to derive some lower bound for the number

$$
\begin{equation*}
h_{n}:=\max \left\{h(C): C \subseteq W_{n}\right\} . \tag{4.1}
\end{equation*}
$$

We shall see that $h_{n}$ grows at least exponentially with $n$. To this end, we shall use arguments concerning numbering of unordered pairs $\left\{C, W_{n} \backslash C\right\}$ for $C \subseteq W_{n}$ such that $C$ and $W_{n} \backslash C$ are linearly separable. First, we state the following

Definition 4.1 For $n \geq 1$ let $t(n)$ denote the number of unordered partitions $\left\{C, C^{\prime}\right\}$ of $W_{n}$ for which $C$ and $C^{\prime}$ are linearly separable.

## Remarks:

(i) Since $\left|W_{n}\right|=2^{n}$, there exist

$$
\frac{1}{2} \cdot 2^{\left|W_{n}\right|}=2^{\left(2^{n}-1\right)}
$$

unordered partitions of $W_{n}$ into two sets.
(ii) The partition $\left\{\emptyset, W_{n}\right\}$ has to be considered while computing $t(n)$.

Example: Assume $n=2$. There exist 8 unordered partitions of $W_{2}$ into two sets. By Example 2.4, only one of these partitions does not contribute to the computation of $t(2)$; thus we have $t(2)=7$.

For general $n \in \mathbb{N}$ we want to obtain nontrivial upper bounds for $t(n)$. First we recall the following

Proposition 4.2 Assume $k>n \geq 1$, and in $\mathbb{R}^{n}$ there are given $k$ points $y_{1}, \ldots, y_{k}$ in general position; that means, every subset $Y^{\prime}$ of $Y=\left\{y_{1}, \ldots, y_{k}\right\}$ with $\left|Y^{\prime}\right|=n+1$ is affinely independent. Let $s(n, k)$ denote the number of unordered partitions $\left\{Y_{1}, Y_{2}\right\}$ of $Y$ such that $Y_{1}$ and $Y_{2}$ are linearly separable. Then one has

$$
\begin{equation*}
s(n, k)=\sum_{j=0}^{n}\binom{k-1}{j} . \tag{4.2}
\end{equation*}
$$

Proof. This result is shown in [14].
Certainly, the vertices of $W_{n}$ are far from being in general position; however, the next result relates the numbers $t(n)$ and $s\left(n, 2^{n}\right)$.

Proposition 4.3 For every $n \in \mathbb{N}$ one has

$$
\begin{equation*}
t(n) \leq s\left(n, 2^{n}\right) \tag{4.3}
\end{equation*}
$$

Proof. Assume $H_{1}, \ldots, H_{t(n)}$ are affine hyperplanes in $\mathbb{R}^{n}$ which do not intersect $W_{n}$ and such that any two distinct $H_{i}, H_{j}, 1 \leq i<j \leq t(n)$, induce distinct unordered partitions of $W_{n}$. For any $x \in W_{n}$ we choose some open set $U_{x}$ in $\mathbb{R}^{n}$ with $x \in U_{x}$ such that $U_{x} \cap H_{i}=\emptyset$ holds for all $i$ with $1 \leq i \leq t(n)$ and $U_{x} \cap U_{x^{\prime}}=\emptyset$ holds for all $x, x^{\prime} \in W_{n}$ with $x \neq x^{\prime}$. Now, for any set $U_{x}, x \in W_{n}$, we choose some $y(x) \in U_{x}$ such that the points $y(x), x \in W_{n}$, are in general position. By our choice of the sets $U_{x}$, the affine hyperplanes $H_{1}, \ldots, H_{t(n)}$ induce $t(n)$ distinct unordered partitions of the set $Y:=\left\{y(x): x \in W_{n}\right\}$; this yields what we want.

Proposition 4.2 and Proposition 4.3 will yield an upper bound for $t(n)$. First, we prove

Lemma 4.4 Assume $m, k \in \mathbb{N}$ satisfy $3 m \leq k$. Then one has

$$
\begin{equation*}
\sum_{j=0}^{m-1}\binom{k-1}{j} \leq\binom{ k-1}{m} \tag{4.4}
\end{equation*}
$$

Proof. For fixed $k \in \mathbb{N}$, we proceed by induction on $m$. In case $m=1$ we have $3 \leq k$ by the assumption of the lemma, and (4.4) states the even weaker inequality $1 \leq k-1$.
Now assume $2 \leq m \leq \frac{k}{3}$, and we have already proved that

$$
\sum_{j=0}^{m-2}\binom{k-1}{j} \leq\binom{ k-1}{m-1}
$$

Then we get in view of $2 m \leq k-m$ :

$$
\sum_{j=0}^{m-1}\binom{k-1}{j} \leq 2 \cdot\binom{k-1}{m-1}=\frac{2 m}{k-m} \cdot\binom{k-1}{m} \leq\binom{ k-1}{m}
$$

Now we obtain the following
Proposition 4.5 For all $n \in \mathbb{N}$ with $n \geq 2$ we have

$$
\begin{equation*}
t(n) \leq 2 \cdot\binom{2^{n}-1}{n}+1 \tag{4.5}
\end{equation*}
$$

Proof. For $n=2$ we have $t(2)=7=2 \cdot\binom{3}{2}+1$. For $n=3$ we get by Proposition 4.2 and Proposition 4.3

$$
t(3) \leq s(3,8)=\sum_{j=0}^{3}\binom{7}{j}=1+7+21+35=64<71=2 \cdot\binom{7}{3}+1
$$

For $n \geq 4$ we have $3 n \leq 2^{n}$, and thus Proposition 4.2, Proposition 4.3 and Lemma 4.4 yield with $m=n$ and $k=2^{n}$ :

$$
t(n) \leq \sum_{j=0}^{n}\binom{2^{n}-1}{j}=\sum_{j=0}^{n-1}\binom{2^{n}-1}{j}+\binom{2^{n}-1}{n} \leq 2 \cdot\binom{2^{n}-1}{n}
$$

as claimed.
Now we are able to prove the following main result of this section.
Theorem 4.6 Assume $n \geq 2$, and choose $l=l_{n} \in \mathbb{N}$ such that every subset $C \subseteq W_{n}$ may be separated by some $l^{\prime}$-arrangement for an appropriate number $l^{\prime} \leq l$. Then one has

$$
\begin{equation*}
l \geq-\frac{n^{2}}{2}+\sqrt{\frac{n^{4}}{4}+2^{n}}>2^{\frac{n}{2}}-\frac{n^{2}}{2} \tag{4.6}
\end{equation*}
$$

In other words, we have

$$
\begin{equation*}
h_{n} \geq-\frac{n^{2}}{2}+\sqrt{\frac{n^{4}}{4}+2^{n}}>2^{\frac{n}{2}}-\frac{n^{2}}{2} . \tag{4.7}
\end{equation*}
$$

Proof. In view of (2.5) and (4.1), the inequality (4.7) is of course only a reformulation of the first assertion. To prove (4.6), we first note that Lemma 2.5 (iv) implies that every $C \subseteq W_{n}$ may be separated by some $l$-arrangement.
Let $\mathcal{H}_{0}$ denote some set of affine hyperplanes in $\mathbb{R}^{n}$ with $\left|\mathcal{H}_{0}\right|=t(n)$ and not intersecting $W_{n}$ such that these $t(n)$ affine hyperplanes induce exactly the $t(n)$ distinct unordered partitions of $W_{n}$ into two linearly separable sets.

Now, any of all the $2^{\left(2^{n}-1\right)}$ unordered partitions $\left\{C, C^{\prime}\right\}$ of $W_{n}$ is uniquely determined by (at least) some l-arrangement $\mathcal{H}=\left(H_{1}, \ldots, H_{l}\right)$ with $H_{1}, \ldots, H_{l} \in \mathcal{H}_{0}$ and some affine oriented hyperplane $H$ in $\mathbb{R}^{l}$ which linearly separates $\varphi(\mathcal{H}, C)$ and $\varphi\left(\mathcal{H}, C^{\prime}\right)$. There exist $2^{l} \cdot(t(n))^{l} l$-arrangements consisting of $l$ oriented affine hyperplanes in $\mathcal{H}_{0}$; the factor $2^{l}$ arises from the orientations. Thus we get

$$
\begin{equation*}
2^{l} \cdot(t(n))^{l} \cdot t(l) \geq 2^{\left(2^{n}-1\right)} \tag{4.8}
\end{equation*}
$$

Note that the affine oriented hyperplane $H$ in $\mathbb{R}^{l}$ causes the factor $t(l)$ instead of $2 \cdot t(l)$, because we consider unordered partitions $\left\{C, C^{\prime}\right\}$ of $W_{n}$.

By the assumption of the theorem, we have $n \geq 2$ and thus also $l \geq 2$. Therefore, Proposition 4.5 and (4.8) yield

$$
\begin{equation*}
2^{l} \cdot\left(2 \cdot\binom{2^{n}-1}{n}+1\right)^{l} \cdot\left(2 \cdot\binom{2^{l}-1}{l}+1\right) \geq 2^{\left(2^{n}-1\right)} \tag{4.9}
\end{equation*}
$$

Furthermore, for $m \geq 2$ we have

$$
\begin{equation*}
2 \cdot\binom{2^{m}-1}{m}+1 \leq 2^{\left(m^{2}-1\right)} \tag{4.10}
\end{equation*}
$$

This inequality is clear for $m=2$, while for $m \geq 3$ we get

$$
2 \cdot\binom{2^{m}-1}{m}+1 \leq 2 \cdot \frac{\left(2^{m}\right)^{m}}{m!}<2^{\left(m^{2}-1\right)}
$$

Now (4.9) and (4.10), applied to $m=n$ and $m=l$, yield

$$
2^{l} \cdot 2^{\left(n^{2}-1\right) \cdot l} \cdot 2^{\left(l^{2}-1\right)} \geq 2^{\left(2^{n}-1\right)}
$$

Simplification of this inequality yields

$$
2^{n^{2} \cdot l+l^{2}} \geq 2^{\left(2^{n}\right)}
$$

that is

$$
l^{2}+n^{2} \cdot l-2^{n} \geq 0
$$

and thus

$$
l \geq-\frac{n^{2}}{2}+\sqrt{\frac{n^{4}}{4}+2^{n}}>2^{\frac{n}{2}}-\frac{n^{2}}{2}
$$

as claimed.

Note that the inequality (4.7) is trivial for $n=1$. Thus, by summarizing Theorem 3.16 and Theorem 4.6 we obtain

Theorem 4.7 For every $n \in \mathbb{N}$ one has

$$
\begin{equation*}
2^{\frac{n}{2}}-\frac{n^{2}}{2}<-\frac{n^{2}}{2}+\sqrt{\frac{n^{4}}{4}+2^{n}} \leq h_{n} \leq \frac{3}{n+2} \cdot 2^{n} . \tag{4.11}
\end{equation*}
$$

The two left terms in (4.11) are almost equal for large $n$, and differ considerably only for small $n$. Although the bounds of $h_{n}$ specified in (4.11) differ quantitatively in some essential manner, we see yet that $h_{n}$ grows exponentially with $n$.

## 5 Conclusions

With respect to a theory of feedforward networks the derived results, as stated in Theorem 4.7, are understood as a first step in a program which tries to make use of geometric techniques to solve open problems in this context. Here we addressed the problem of determining the minimal number of hidden neurons of a feedforward network, which should be able to solve any given binary classification problem for $n$ inputs, i.e. to realize any Boolean function on $n$ inputs. The derived upper bound (4.11), although it is better than the weaker bound $2^{n-1}$ or other known results reported in the literature, is still too high to be of practical relevance for real world applications of these networks. In fact, it is well known that many problems can be solved with much less neurons; for instance, the parity problem (Problem 2.7) for $n$ inputs can always be solved with $n$ hidden neurons. On the other hand, Theorem 4.7 states, that for a given $n$ there always exists a class of binary classification problems for which a solution needs more than $\left(2^{\frac{n}{2}}-\frac{n^{2}}{2}\right)$ hidden neurons. Of course, this lower bound gets effective only for large $n$. Thus, its main use is for asymptotic considerations. But, since $h_{n}$ must grow exponentially with $n$, it also provides the discouraging insight that a large class of Boolean problems needs also very large networks for a solution.
From the viewpoint of these results the following questions may be of relevance: One may classify the problems according to the minimal number of hyperplanes a solution has to use. Although it might be difficult to decide, in which class a given problem has to be located, the cardinality of these classes is of interest. For $n$ large, are most of the problems "trivial" in the sense that the minimal number of hyperplanes a solution needs is much less than the lower bound (4.11) for $h_{n}$ ? Or are most problems "complex" in the sense that the minimal number of hyperplanes a solution needs is larger than this lower bound?
Furthermore, many interesting problems, represented by a vertex set $C$, inherit a symmetry property like, for instance, the parity problem (Problem 2.7). Lower
and upper bounds of $h(C)$ of course will depend on this symmetry and might be effectively reduced for a known symmetry of the problem. The combination of the geometric techniques used in this paper with group theoretical aspects of binary classification problems will lead to more specific and much stronger results.
The strength of feedforward networks is their ability to "learn"; i.e. there exists a potential function and a gradient descend algorithm, called backpropagation, which, under certain conditions, is able to find solutions for a given problem [11]. These networks have to use smooth transfer functions instead of the step functions referred to in this paper. Our results also apply to these type of networks because, as outlined in the introduction, the hyperplanes used in our arguments still can be identified with the centers of graded neurons. On the other hand, there exists a conjecture, that for networks using sigmoidal (S-shaped) transfer functions the lower bounds for $h_{n}$ should be further reducible.

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[^1]:    ${ }^{1}$ Here - as in the sequel - $|A|$ denotes the cardinality of a finite set $A$.

