

Max-Planck-Institut
für Mathematik
in den Naturwissenschaften
Leipzig

On Stokes Operators with Variable Viscosity in
Bounded and Unbounded Domains

(revised version: October 2008)

by

Helmut Abels, and Yutaka Terasawa

Preprint no.: 25

2008



On Stokes Operators with Variable Viscosity in Bounded and Unbounded Domains

Helmut Abels, Yutaka Terasawa*

October 17, 2008

Abstract

We consider a generalization of the Stokes resolvent equation, where the constant viscosity is replaced by a general given positive function. Such a system arises in many situations as linearized system, when the viscosity of an incompressible, viscous fluid depends on some other quantities. We prove that an associated Stokes-like operator generates an analytic semi-group and admits a bounded H_∞ -calculus, which implies the maximal L^q -regularity of the corresponding parabolic evolution equation. The analysis is done for a large class of unbounded domains with $W_r^{2-\frac{1}{r}}$ -boundary for some $r > d$ with $r \geq q$. In particular, the existence of an L^q -Helmholtz projection is assumed.

Key words: Stokes operator, Stokes equation, unbounded domains, bounded imaginary powers, H_∞ -calculus

AMS-Classification: 35Q30, 76D07, 47A60, 47F05

1 Introduction and Assumptions

We consider the following Stokes-like resolvent system

$$\lambda v - \operatorname{div}(2\nu(x)Dv) + \nabla p = f \quad \text{in } \Omega, \quad (1.1)$$

$$\operatorname{div} v = g \quad \text{in } \Omega, \quad (1.2)$$

$$v|_{\Gamma_1} = 0 \quad \text{on } \Gamma_1, \quad (1.3)$$

$$n \cdot T(v, p)|_{\Gamma_2} = a \quad \text{on } \Gamma_2, \quad (1.4)$$

where $v: \Omega \rightarrow \mathbb{R}^d$ is the velocity of the fluid, $p: \Omega \rightarrow \mathbb{R}$ is the pressure,

$$T(v, p) = 2\nu(x)Dv - pI$$

*Research was supported by a research fellowships of the Japan Society for the Promotion of Science for young scientists.

is the stress tensor, $Dv = \frac{1}{2}(\nabla v + \nabla v^T)$, $\nu: \Omega \rightarrow (0, \infty)$ is a variable viscosity coefficient, and $\Omega \subseteq \mathbb{R}^d$, $d \geq 2$, is a suitable domain with boundary $\partial\Omega = \Gamma_1 \cup \Gamma_2$ consisting of two closed, disjoint (possibly empty) components Γ_j , $j = 1, 2$. Moreover, we denote $S(v) = 2\nu Dv$.

In the case that $\nu(x) = \nu_0 \in (0, \infty)$ is independent of x the latter system was extensively studied in many kinds of different domains relevant for mathematical fluid mechanics. The system arises as linear system of the non-stationary Navier-Stokes equations for incompressible fluids after Laplace transformation, which replaces the derivative in time by a spectral parameter λ . But in many situations the viscosity ν of an incompressible fluid depends on some quantities as e.g. the shear rate $|Dv|$ in the case of some non-Newtonian fluids, cf. e.g. Malek et al. [40], or a concentration c as in the case of diffuse interface models for free boundary value problems, cf. e.g. Abels [4].

First results on general non-stationary Stokes systems, including the latter case of variable viscosity, were obtained by Solonnikov [50, 49] in L^q -Sobolev spaces and weighted Hölder spaces and Bothe and Prüss [20] in L^q -Sobolev spaces, where applications to non-Newtonian fluids are treated as well. Some results on the Stokes system with variable viscosity in L^2 -Sobolev spaces can also be found in [4, 13], where applications to a diffuse interface models are also treated. Finally, we note that Ladyženskaja and Solonnikov [42] and later Danchin [22] obtained results for a similar non-stationary Stokes system with variable density instead of variable viscosity.

The purpose of the present contribution is to study the (generalized) Stokes resolvent equation (1.1)-(1.4) and an associated Stokes operator in L^q -Sobolev spaces, $1 < q < \infty$, in a class of general bounded and unbounded domain, which is similar to the class in [8] and which covers most cases studied so far in the case of constant viscosity. More precisely, we will show that the associated Stokes operator $-A_q$, defined below, generates an analytic semi-group e^{-tA_q} , $t \geq 0$, on $L^q(\Omega)^d$. We will even show that A_q admits a bounded H_∞ -calculus in the sense of McIntosh [44]. This has several strong implication as will be explained below.

In the case of constant viscosity the boundedness and analyticity of the Stokes semi-group was proved by Giga [32] for the case of bounded domains, Borchers and Sohr [18] and Borchers and Varnhorn [19] for the case of an exterior domain, and Farwig and Sohr [31] in the case of an aperture domain. We refer to Farwig and Sohr [30] for a general approach to unbounded and bounded domains. The case of infinite layers and layer-like domains were discussed by Abe and Shibata [2, 3], Abe [1], Abels and Wiegner [14], and Abels [12, 10]. The case of an infinite cylinder was treated by Farwig and Ri [28, 29]. For the proof of bounded imaginary powers or a bounded H^∞ -calculus in the latter domains we refer to Giga [33], Giga and Sohr [34], Noll and Saal [46], Farwig and Ri [28], and Abels [5, 7, 8, 11]. Finally, we refer to Farwig, Kozono, and Sohr [27] for results on the Stokes system in general unbounded domains with uniform C^2 -boundary in Sobolev spaces based on $L^q(\Omega) \cap L^2(\Omega)$ if $2 \leq q < \infty$ and $L^q(\Omega) + L^2(\Omega)$ if $1 < q \leq 2$.

Before we present our main results we state the assumptions on the domain and

related function spaces:

Assumption 1.1 *Let $1 < q < \infty$, let $d < r_1, r_2 \leq \infty$ such that $q, q' \leq \min(r_1, r_2)$, and let $\nu(x) = \nu_\infty + \nu'(x)$ such that $\nu'(x) \in W_{r_1}^1(\Omega)$ and $\nu(x) \geq \nu_0 > 0$ for all $x \in \Omega$. Moreover, let $\Omega \subseteq \mathbb{R}^d$, $d \geq 2$, be a domain and $\partial\Omega = \Gamma_1 \cup \Gamma_2$ with Γ_1, Γ_2 closed and disjoint satisfying the following conditions:*

- (A1) *There is a finite covering of $\bar{\Omega}$ with relatively open sets U_j , $j = 1, \dots, m$, such that U_j coincides (after rotation) with a relatively open set of $\overline{\mathbb{R}_{\gamma_j}^d}$, where $\mathbb{R}_{\gamma_j}^d := \{(x', x_d) \in \mathbb{R}^d : x_d > \gamma_j(x')\}$, $\gamma_j \in W_{r_2}^{2-\frac{1}{r_2}}(\mathbb{R}^{d-1})$. Moreover, suppose that there are cut-off functions $\varphi_j, \psi_j \in C_b^\infty(\bar{\Omega})$, $j = 1, \dots, m$, such that φ_j , $j = 1, \dots, m$, is a partition of unity, $\psi_j \equiv 1$ on $\text{supp } \varphi_j$, and $\text{supp } \psi_j \subset U_j$, $j = 1, \dots, m$.*
- (A2) *For every $f \in L^s(\Omega)^d$, $s = q, q'$, there is a unique decomposition $f = f_0 + \nabla p$ with $f_0 \in J_s(\Omega)$ and $p \in \dot{W}_{s, \Gamma_2}^1(\Omega)$ where*

$$\begin{aligned} J_s(\Omega) &:= \overline{\left\{ f \in C_{(0)}^\infty(\Omega \cup \Gamma_2)^d : \text{div } f = 0 \right\}}^{L^s(\Omega)}, \\ \dot{W}_{s, \Gamma_2}^1(\Omega) &:= \left\{ p \in \dot{W}_s^1(\Omega) : p|_{\Gamma_2} = 0 \right\}. \end{aligned}$$

- (A3) *For every $p \in \dot{W}_{s, \Gamma_2}^1(\Omega)$, $s = q, q'$, there is a decomposition $p = p_1 + p_2$ such that $p_1 \in W_s^1(\Omega)$ with $p_1|_{\Gamma_2} = 0$, $p_2 \in L_{\text{loc}}^s(\bar{\Omega})$ with $\nabla p_2 \in W_s^1(\Omega)$ and $\|(p_1, \nabla p_2)\|_{W_s^1(\Omega)} \leq C \|\nabla p\|_s$.*

Remarks 1.2 1. It is easy to see that (A1) is fulfilled for all kinds of domains with $W_{r_2}^{2-\frac{1}{r_2}}$ -boundary mentioned above. The assumption (A2) guarantees the existence of a Helmholtz-projection adapted to the boundary conditions (1.3)-(1.4). We refer to [10, 30, 31, 45, 26, 48] for the validity of the Helmholtz decomposition for these types of domains for the case $\Gamma_2 = \emptyset$. Moreover, (A3) is a technical condition needed in the Section 6 below. It is used to overcome the difficulty that multiplication with not compactly supported cut-off functions is not continuous on $\dot{W}_{q, \Gamma}^1(\Omega)$ in general. The condition is satisfied if the following extension property is valid: For every $p \in \dot{W}_q^1(\Omega)$ there is an extension $\tilde{p} \in \dot{W}_q^1(\mathbb{R}^d)$ such that $\tilde{p}|_\Omega = p$ and $\|\nabla \tilde{p}\|_q \leq C \|\nabla p\|_q$. This is the case for every (ε, ∞) -domain, cf. [21], in particular, for exterior domains. This extension property does not hold for layer-like domains, cf. [10, Section 2.4]. Nevertheless (A3) is also valid in layer-like domains, cf. [10, Lemma 2.4].

2. Let us comment on the regularity assumptions on ν and $\partial\Omega$. First of all, $\nu \in W_{r_1}^1(\Omega)$ with $r_1 > d$ implies that multiplication with ν defines a continuous mapping on $W_q^1(\Omega)$ for every $1 \leq q < r_1$, cf. Lemma 2.1 below. In particular,

this implies that $\operatorname{div}(2\nu Dv) \in L^q(\Omega)^d$ for every $v \in W_q^2(\Omega)^d$ and $1 \leq q < r_1$. Since we will partly argue by duality, we also require $q' < r_1$. Moreover, since $r_1 > d$, $W_{r_1}^1(\Omega) \hookrightarrow C^{1-\frac{d}{r_1}}(\overline{\Omega})$. Therefore $\operatorname{div}(2\nu Dv) = \nu(\Delta v + \nabla \operatorname{div} v) + \nabla \nu \cdot Dv$, where $\nabla \nu \cdot Dv$ is of lower order and the principal part $\nu(\Delta v + \nabla \operatorname{div} v)$ has Hölder continuous coefficients. The latter property is essential to apply pseudodifferential operator methods with symbol that are Hölder continuous with respect to the space variable x . Concerning the boundary regularity, we note that every $\gamma \in W_{r_2}^{2-\frac{1}{r_2}}(\mathbb{R}^{d-1})$ can be extended to some $\Gamma \in W_{r_2}^2(\mathbb{R}_+^d)$, which is then used to build suitable coordinate transformations. After transforming the (reduced) Stokes system on \mathbb{R}_γ^d to \mathbb{R}_+^d , the principal part of transformed differential operators will have coefficients depending on $\nabla \Gamma \in W_{r_2}^1(\mathbb{R}_+^d)$, which embeds again to a space of Hölder continuous functions since $r_2 > d$. Hence multiplication by $\nabla \Gamma$ plays a similar role as multiplication by ν and that is where the conditions related to r_1, r_2 in the assumptions come from. Finally, let us note that, if $\partial\Omega$ is compact, $C^{1,1}(\partial\Omega) \hookrightarrow W_{r'}^{2-\frac{1}{r'}}(\partial\Omega) \hookrightarrow W_r^{2-\frac{1}{r}}(\partial\Omega)$ for all $1 \leq r \leq r' \leq \infty$. Therefore the local regularity decreases if r_1, r_2 are chosen smaller and the case $r_1 = r_2 = \infty$ corresponds to the strongest regularity assumptions. On the other hand, the smaller r_1, r_2 are chosen, the more restrictive the condition $q, q' < \min(r_1, r_2)$ gets.

In some parts of the paper we will assume additionally that the following assumption holds:

(A4) There is some $R > 0$ such that for every $\lambda \in \Sigma_\delta$ with $|\lambda| \geq R$ there is no non-trivial solution $g \in W_q^1(\Omega)$ with $g|_{\Gamma_2} = 0$ of

$$\lambda(g, \varphi)_\Omega + (\nu \nabla g, \nabla \varphi)_\Omega = 0 \quad \text{for all } \varphi \in W_{q', \Gamma_2}^1(\Omega). \quad (1.5)$$

Here $W_{q', \Gamma_2}^1(\Omega) = \{\varphi \in W_{q'}^1(\Omega) : \varphi|_{\Gamma_2} = 0\}$. We will show later that (A4) is a consequence of Assumption 1.1, cf. Lemma 6.1 below.

The reduced Stokes operator A_q on $L^q(\Omega)^d$ is defined as

$$\begin{aligned} A_q v &= -\operatorname{div}(\nu \nabla v) + \nabla P v - \nabla \nu^T \nabla v^T \\ \mathcal{D}(A_q) &= \{v \in W_q^2(\Omega)^d : v|_{\Gamma_1} = 0, T_1' v|_{\Gamma_2} = 0\}, \end{aligned} \quad (1.6)$$

where $T_1' v$ is defined by

$$(T_1' v)_\tau = (n \cdot S(v))_\tau|_{\Gamma_2}, \quad (T_1' v)_n = \nu \operatorname{div} v|_{\Gamma_2}. \quad (1.7)$$

Here f_τ, f_n denotes the tangential, normal component, resp., of vector field f at the boundary $\partial\Omega$. Moreover, $Pv \equiv p_1 \in \dot{W}_q^1(\Omega)$ with $p_1|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$ is defined as the solution of

$$(\nabla p_1, \nabla \varphi)_\Omega = (\nu(\Delta - \nabla \operatorname{div})v, \nabla \varphi)_\Omega + (Dv, 2\nabla \nu \otimes \nabla \varphi)_\Omega, \quad (1.8)$$

$$p_1|_{\Gamma_2} = 2\nu \partial_n v_n \quad (1.9)$$

for all $\varphi \in \dot{W}_{q', \Gamma_2}^1(\Omega) = \left\{ \varphi \in \dot{W}_{q'}^1(\Omega) : \varphi|_{\Gamma_2} = 0 \right\}$. Note that the righthand-side of (1.8) defines a bounded linear functional on $\dot{W}_{q', \Gamma_2}^1(\Omega)$. The existence of a solution of (1.8)-(1.9) that is unique (upto a constant if $\Gamma_2 = \emptyset$) follows from the existence of a unique Helmholtz decomposition, i.e., (A2), cf. Lemma 2.2 below. Then $P: W_q^2(\Omega)^d \rightarrow \left\{ p \in \dot{W}_q^1(\Omega) : p|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2) \right\}$ is a bounded linear operator.

The connection to the original system is discussed in Section 3 below. We note that the definition of A_q , in particular the lower order term $\nu^T \nabla v^T$, is chosen such that for all $u \in \mathcal{D}(A_q)$ with $\operatorname{div} u = 0$ and $v \in W_{q'}^1(\Omega)$ with $v|_{\Gamma_1=0}, \operatorname{div} v = 0$

$$\begin{aligned} (A_q u, v)_\Omega &= (-\operatorname{div}(2\nu Du), v)_\Omega + (\nabla P u, v)_\Omega \\ &= (2\nu Du, Dv)_\Omega - (n \cdot S(u) \cdot n, v_n)_{\Gamma_2} + (2\nu \partial_n u_n, v_n)_{\Gamma_2} = (2\nu Du, Dv)_\Omega \end{aligned} \quad (1.10)$$

holds.

The main result is the following:

THEOREM 1.3 *Let $\Omega \subseteq \mathbb{R}^d$, $d \geq 2$, $\delta \in (0, \pi)$, and q, r_1, r_2 be as in Assumption 1.1. Then there is some $R > 0$ such that $(\lambda + A_q)^{-1}$ exists and*

$$\|(\lambda + A_q)^{-1}\|_{\mathcal{L}(L^q(\Omega))} \leq \frac{C_{q,\delta}}{1 + |\lambda|} \quad (1.11)$$

for all $\lambda \in \Sigma_\delta$ with $|\lambda| \geq R$. Moreover,

$$\left\| \int_{\Gamma_R} h(-\lambda)(\lambda + A_q)^{-1} d\lambda \right\|_{\mathcal{L}(L^q(\Omega))} \leq C_{q,\delta} \|h\|_{L^\infty(\Sigma_{\pi-\delta})} \quad (1.12)$$

for every $h \in H_\infty(\delta)$, where $\Gamma_R = \Gamma \setminus \overline{B_R(0)}$ and $H_\infty(\delta)$ denotes the Banach algebra of all bounded holomorphic functions $h: \Sigma_{\pi-\delta} \rightarrow \mathbb{C}$. In particular, for every $c \in \mathbb{R}$ and $0 < \delta' \leq \delta$ such that $c + \Sigma_{\delta'} \subset \rho(-A_q)$ the shifted reduced Stokes operator $c + A_q$ admits a bounded H_∞ -calculus with respect to δ' , i.e.,

$$h(c + A_q) := \frac{1}{2\pi i} \int_\Gamma h(-\lambda)(\lambda + c + A_q)^{-1} d\lambda \quad (1.13)$$

is a bounded operator satisfying

$$\|h(c + A_q)\|_{\mathcal{L}(L^q(\Omega))} \leq C_{q,\delta} \|h\|_{L^\infty(\Sigma_{\pi-\delta})} \quad (1.14)$$

for all $h \in H_\infty(\delta')$.

We note that in order to prove (1.14) for all $h \in H_\infty(\delta)$ it is sufficient to show the estimate for $h \in H(\delta)$, which consists of all $h \in H_\infty(\delta)$ such that

$$|h(z)| \leq C \frac{|z|^s}{1 + |z|^{2s}} \quad \text{for all } z \in \Sigma_{\pi-\delta}$$

for some $s > 0$, cf. Denk, Hieber, and Prüss [24, Section 2.4].

We note that (A2) is always true in the case of a bounded domain because of [48] and since $W_{r_2}^{2-\frac{1}{r_2}}(\mathbb{R}^{d-1}) \hookrightarrow C^1(\mathbb{R}^{d-1})$ if $r_2 > d$. Moreover, (A1) is trivially true and (A3) is valid too by Poincaré's inequality. In this case we obtain:

THEOREM 1.4 *Let $\Omega \subseteq \mathbb{R}^d$, $d \geq 2$, $\delta \in (0, \pi)$, and q, r_1, r_2 be as in Assumption 1.1. Moreover, assume that Ω is bounded and that $\Gamma_1 \neq \emptyset$. Then $\Sigma_\delta \cup \{0\} \subseteq \rho(-A_q)$ and*

$$\|(\lambda + A_q)^{-1}\|_{\mathcal{L}(L^q(\Omega))} \leq \frac{C_{q,\delta}}{1 + |\lambda|}$$

for all $\lambda \in \Sigma_\delta \cup \{0\}$. Moreover, A_q admits a bounded H_∞ -calculus with respect to δ .

Finally, note that, if $c + A_q$ admits a bounded H_∞ -calculus with respect to $0 < \delta < \pi$, then, choosing $h(\lambda) = \lambda^{iy}$, $y \in \mathbb{R}$, above, one obtains that $c + A_q$ has *bounded imaginary powers* $(c + A_q)^{iy}$, which satisfy

$$\|(c + A_q)^{iy}\|_{\mathcal{L}(L^q(\Omega)^d)} \leq C e^{|y|(\pi-\delta)}, \quad (1.15)$$

where we note that $\sup_{\lambda \in \Sigma_{\delta-\pi}} |\lambda^{iy}| = e^{|y|(\pi-\delta)}$. This has two important consequences, which we summarize in the following. The first one concerns so-called maximal regularity of the reduced Stokes operator A_q and follows from the well-known result due to Dore and Venni [25, Theorem 3.2] and its extension by Giga and Sohr [35, Theorem 2.1].

Theorem 1.5 *Let $1 < p < \infty$, $0 < T \leq \infty$, and let Ω, q be as in Assumption 1.1. Moreover, let $c \in \mathbb{R}$ be such that $c + A_q$ is invertible and admits a bounded H_∞ -calculus. Then for every $f \in L^p(0, T; L^q(\Omega)^d)$ there is a unique solution $u \in W_p^1(0, T; L_\sigma^q(\Omega)) \cap L^p(0, T; \mathcal{D}(A_q))$ of*

$$\begin{aligned} u'(t) + (c + A_q)u(t) &= f(t), & 0 < t < T, \\ u(0) &= 0 \end{aligned}$$

Moreover,

$$\|u'\|_{L^p(0, T; L^q)} + \|(c + A_q)u\|_{L^p(0, T; L^q)} \leq C \|f\|_{L^p(0, T; L^q)},$$

where C does not depend on T .

In particular, in the case of bounded domain with $W_{r_2}^{2-\frac{1}{r_2}}$ -boundary the latter theorem implies that A_q has *maximal regularity* on $L^q(\Omega)^d$ for all $1 < q < \infty$ with $q, q' \leq \min(r_1, r_2)$, where $d < r_1, r_2 \leq \infty$ and $\nu \in W_{r_1}^1(\Omega)$.

As a second application we note that the boundedness of $(c + A_q)^{iy}$ and (1.15) can be used to characterize the domain of the fractional powers $(c + A_q)^\alpha$, $0 < \alpha < 1$, as

$$\mathcal{D}((c + A_q)^\alpha) = (L^q(\Omega)^d, \mathcal{D}(A_q))_{[\alpha]},$$

where $(\cdot, \cdot)_{[\alpha]}$ denotes the complex interpolation functor, cf. [34, Proposition 6.1]. Here again $c \in \mathbb{R}$ is such that $c + A_q$ is invertible and admits a bounded H^∞ -calculus.

The proof of Theorem 1.3 is based on a similar result for a bent half-space \mathbb{R}_γ^d , cf. Theorem 5.1 below, which is obtained by constructing a suitable approximation of the resolvent $(\lambda + A_q)^{-1}$. The latter construction uses the technique developed in [11], combined with newer results on the general calculus of pseudodifferential boundary value problems studied in [9], adapted to the case of variable viscosity.

The structure of the article is as follows: In Section 2 we summarize some preliminaries and some notation. In Section 3 we discuss how the pressure p and the divergence equation can be eliminated from (1.1)-(1.4). This uses the ideas of Grubb and Solonnikov, cf. e.g. [39]. The reduced system contains the non-local operator Pv , which can be approximated naturally in the class of pseudodifferential boundary value problems going back to Boutet de Monvel [23] and developed further by Grubb [37] to parameter-dependent operators and by the first author to the case of non-smooth symbols [6, 9, 11]. Section 4 is devoted to some needed results on coordinate transformation and the change of operators under coordinate transformation. The main step is done in Section 5, where a suitable result for a bent half-space is proved using the previously mentioned techniques. Using the latter result, Theorem 1.3 is proved in Section 6. Finally, the result for bounded domains, i.e., Theorem 1.4, is proved in Section 7.

Acknowledgments: The authors are grateful to Gerd Grubb and one anonymous referee for several helpful comments to improve the presentation in this contribution.

2 Preliminaries

First of all, \mathbb{N} will denote the set of natural numbers (without 0) and $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$. Moreover, we denote $\mathbb{R}_+^d = \{x \in \mathbb{R}^d : x_d > 0\}$, $a \otimes b = (a_i b_j)_{i,j=1}^d$ for $a, b \in \mathbb{R}^d$, e_j denotes the j -th canonical unit vector, and $[A, B] = AB - BA$ the commutator of two operators A, B . We frequently use the decomposition $x = (x', x_d)$ of $x \in \mathbb{R}^d$, where $x' \in \mathbb{R}^{d-1}$ denote the first $(d-1)$ -components of x . Moreover, we identify \mathbb{R}^{d-1} with $\partial\mathbb{R}_+^d = \mathbb{R}^{d-1} \times \{0\}$ and $x' \in \mathbb{R}^{d-1}$ with $(x', 0)$ in the following. For completeness, we note that, if $v: \Omega \rightarrow \mathbb{R}^d$ is a suitable vector field, then $\nabla v = (\partial_j v_k)_{j,k=1}^d$. Moreover, if $A: \Omega \rightarrow \mathbb{R}^{d \times d}$ is suitable, then $\operatorname{div} A = (\sum_{j=1}^d \partial_j a_{jk})_{k=1}^d$, where $A = (a_{jk})_{j,k=1}^d$.

If X is a Banach space and X' is its dual, then

$$\langle f, g \rangle \equiv \langle f, g \rangle_{X', X} = f(g), \quad f \in X', g \in X,$$

denotes the duality product.

Let $M \subseteq \mathbb{R}^d$, $d \geq 2$. Then $C_b^k(M)$, $k \in \mathbb{N}_0$, denotes the set of all k -times continuously differentiable functions $f: M \rightarrow \mathbb{C}$ such that f and all its derivatives are bounded. Moreover, $C_b^\infty(M) = \cap_{k \in \mathbb{N}} C_b^k(M)$ and $C_{(0)}^\infty(M)$ is the set of all $f \in C^\infty(M)$ with $\operatorname{supp} f \subseteq M$ compact, and, if $\Omega \subset \mathbb{R}^d$ is a domain, then $C_0^\infty(\Omega) \equiv C_{(0)}^\infty(\Omega)$. The

usual Lebesgue-space with respect to the Lebesgue measure on Ω and the $(d-1)$ -dimensional surface measure on $\partial\Omega$ will be denoted by $L^q(\Omega)$, $L^q(\partial\Omega)$, resp., $1 \leq q \leq \infty$. Moreover, we use the abbreviations $\|\cdot\|_q \equiv \|\cdot\|_{L^q(\Omega)}$ and $\|\cdot\|_{q,\partial\Omega} \equiv \|\cdot\|_{L^q(\partial\Omega)}$. Furthermore, $L^q_{\text{loc}}(\bar{\Omega})$, $1 \leq q \leq \infty$, is defined as the space of all $f: \Omega \rightarrow \mathbb{C}$ such that $f \in L^q(B \cap \Omega)$ for all balls B with $B \cap \Omega \neq \emptyset$. The usual scalar product on $L^2(M)$ is denoted by $(\cdot, \cdot)_M$ for $M = \Omega, \partial\Omega$. Finally, if $\omega: \Omega \rightarrow (0, \infty)$, then $L^p(\Omega; \omega)$ denotes the L^p -space with respect to the measure $\omega(x) dx$.

In the following the usual Sobolev-Slobodeckij spaces based on $L^q(\Omega)$, $1 < q < \infty$, are denoted by $W_q^s(\Omega)$ and $W_q^s(M)$, $s \geq 0$, with norms $\|\cdot\|_{s,q}$ and $\|\cdot\|_{s,q,\partial\Omega}$, respectively, cf. e.g. [15], where $M \subset \mathbb{R}^d$ is a $(d-1)$ -dimensional sufficiently smooth manifold. We note that, if $0 < s < 1$, then it is sufficient to assume that M is C^1 -manifold to define $W_q^s(M)$ in the usual way. Moreover, $W_{q,0}^m(\Omega)$, $m \in \mathbb{N}$, denotes the closure of $C_0^\infty(\Omega)$ in $W_q^m(\Omega)$ and

$$W_q^{-m}(\Omega) := (W_{q',0}^m(\Omega))', \quad W_{q,0}^{-m}(\Omega) := (W_q^m(\Omega))', \quad W_q^{-s}(\partial\Omega) := (W_{q'}^s(\partial\Omega))'$$

for $m \in \mathbb{N}$ and $s > 0$, where $\frac{1}{q} + \frac{1}{q'} = 1$.

Finally, the homogeneous Sobolev space of order 1 is defined as

$$\dot{W}_q^1(\Omega) := \{p \in L_{\text{loc}}^q(\bar{\Omega}) : \nabla p \in L^q(\Omega)\}$$

normed by $\|\nabla \cdot\|_q$, where functions, which differ by a constant, are identified.

Additionally, \mathcal{F} and \mathcal{F}^{-1} denote the Fourier and inverse Fourier transformation,

$$\mathcal{F}[f](\xi) := \hat{f}(\xi) := \int_{\mathbb{R}^d} e^{-ix \cdot \xi} f(x) dx, \quad \mathcal{F}^{-1}[f](x) := \check{f}(x) := \int_{\mathbb{R}^d} e^{ix \cdot \xi} f(\xi) d\xi,$$

defined for a suitable function $f: \mathbb{R}^d \rightarrow \mathbb{C}$, where $d\xi := (2\pi)^{-d} d\xi$. Note that in the following all integrals with respect to a phase ξ will be scaled by $(2\pi)^{-d}$ as above. Moreover, we will use partial Fourier transformation

$$\mathcal{F}_{x' \mapsto \xi'}[f](\xi', x_d) := \check{f}(\xi', x_d) := \int_{\mathbb{R}^{d-1}} e^{-ix' \cdot \xi'} f(x', x_d) dx'$$

and the conjugate Fourier transformation $\bar{\mathcal{F}}[f](\xi) = \mathcal{F}[f](-\xi)$.

Let $\langle \xi \rangle = (1 + |\xi|^2)^{\frac{1}{2}}$, $\xi \in \mathbb{R}^d$, and let $\langle D_x \rangle^s \equiv \text{OP}(\langle \xi \rangle^s) = \mathcal{F}^{-1}[\langle \xi \rangle^s \mathcal{F}[\cdot]]$, $s \in \mathbb{R}$. Moreover, $\mathcal{S}(\mathbb{R}^d)$ denotes the space of rapidly decreasing smooth functions $f: \mathbb{R}^d \rightarrow \mathbb{C}$ and $\mathcal{S}'(\mathbb{R}^d)$ denotes the space of tempered distributions. Recall that the *Bessel potential space* $H_q^s(\mathbb{R}^d)$, $1 < q < \infty$, $s \in \mathbb{R}$, is defined as the space of all $f \in \mathcal{S}'(\mathbb{R}^d)$ for which $\langle D_x \rangle^s f \in L^q(\mathbb{R}^d)$, with norm $\|f\|_{H_q^s} = \|\langle D_x \rangle^s f\|_{L^q}$. Moreover, $\mathcal{S}(\mathbb{R}^d; X)$ and $H_q^s(\mathbb{R}^d; X)$ denote the vector-valued variants, where X is a Banach space. As in [36, 38], the space $H_q^s(\mathbb{R}_+^d) = r^+ H_q^s(\mathbb{R}^d)$ is defined as the space of all distributions of $H_q^s(\mathbb{R}^d)$ restricted to \mathbb{R}_+^d equipped with the quotient norm. Here and in the following $r^+ f$ denotes the restriction of $f \in \mathcal{S}'(\mathbb{R}^d)$ to \mathbb{R}_+^d . We refer to [17, Chapter 6] for the definition of the usual $B_{qr}^s(\mathbb{R}^d)$, $s \in \mathbb{R}$, $1 \leq q, r < \infty$ and their interpolation

properties. Moreover, we note that $B_{qq}^s(\mathbb{R}^d) = W_q^s(\mathbb{R}^d)$ for all $s > 0, s \notin \mathbb{N}$, and $1 \leq q < \infty$.

Finally, $\mathcal{C}^s(\mathbb{R}^d) \equiv B_{\infty\infty}^s(\mathbb{R}^d)$, $s > 0$, denotes the Zygmund space and $\mathcal{C}^s(\mathbb{R}^d; X) \equiv B_{\infty\infty}^s(\mathbb{R}^d; X)$ its vector-valued variant for a Banach space X . Note that $\mathcal{C}^s(\mathbb{R}^d; X) = C^s(\mathbb{R}^d; X)$ if $s > 0$ and $s \notin \mathbb{N}_0$, cf. e.g. [16, Equation (5.8)]. Here $C^s(\mathbb{R}^d; X)$ is the space of all $[s]$ -times continuously differentiable $f: \mathbb{R}^d \rightarrow X$ such that f and all its derivatives are bounded and $\partial_x^\alpha f$, $|\alpha| = [s]$, is (uniformly) Hölder continuous of degree $s - [s]$. Here $[s]$ denotes the largest integer not larger than s . The space is normed by

$$\|f\|_{\mathcal{C}^s(\mathbb{R}^d; X)} := \sum_{|\alpha| \leq [s]} \|\partial_x^\alpha f\|_{L^\infty(\mathbb{R}^d; X)} + \sum_{|\alpha| = [s]} \sup_{x \neq y} \frac{\|\partial_x^\alpha f(x) - \partial_x^\alpha f(y)\|_X}{|x - y|^{s - [s]}}.$$

In the following, let Ω be a domain as in the Assumption 1.1. First of all, using the partition of unity assumed in (A2), it is easy to reduce many of the fundamental statements on the Sobolev spaces $W_q^m(\Omega)$, $m \leq 2$, to a bent half space \mathbb{R}_γ^d , $\gamma \in W_{r_2}^{2 - \frac{1}{r_2}}(\mathbb{R}^{d-1})$. Using a suitable coordinate transformation, cf. e.g. Proposition 4.2 below, the statements for the bent half-space can be proved using the corresponding statement for \mathbb{R}_+^d . In particular, we note that the usual Sobolev embedding theorem for $W_q^1(\Omega)$ can be proved that way. As a consequence, it is easy to prove the following lemma:

Lemma 2.1 *Let $1 < q < \infty$ and $d < r \leq \infty$ such that $q \leq r$ and let Ω be a domain as in the Assumption 1.1 with $r_2 = r$. Then $\pi(f, g)(x) := f(x)g(x)$ defines a continuous, bilinear mapping $\pi: W_q^1(\Omega) \times W_r^1(\Omega) \rightarrow W_q^1(\Omega)$.*

Similarly, the interpolation inequality

$$\|f\|_{W_q^1(\Omega)} \leq c_q \|f\|_{L^q(\Omega)}^{\frac{1}{2}} \|f\|_{W_q^2(\Omega)}^{\frac{1}{2}}$$

for all $1 < q < \infty$ and $f \in W_q^2(\Omega)$ can be proved. Furthermore, there is a bounded extension operator

$$E: W_q^{1 - \frac{1}{q}}(\partial\Omega) \rightarrow W_q^1(\Omega) \quad \text{such that } Ea|_{\partial\Omega} = a \text{ for all } a \in W_q^{1 - \frac{1}{q}}(\partial\Omega).$$

This extension operator can be easily constructed using the corresponding extension operator for \mathbb{R}_+^d , the partition of unity due to (A1) and suitable coordinate transformations. Note that the corresponding statement for $\dot{W}_q^1(\Omega)$ and $\dot{W}_q^{1 - \frac{1}{q}}(\partial\Omega)$ are not true for general unbounded domains; e.g. the statement is not true for an infinite layer, cf. [10, Remark 2.6.1].

Finally, we note that, if Ω and q are as in Assumption 1.1, then (A2) implies that for every $f \in L^q(\Omega)^d$, there is a unique $p \in \dot{W}_{q, \Gamma_2}^1(\Omega)$ (upto a constant if $\Gamma_2 = \emptyset$) depending continuously on f such that

$$(\nabla p, \nabla \varphi)_\Omega = (f, \nabla \varphi)_\Omega \quad \text{for all } \varphi \in \dot{W}_{q, \Gamma_2}^1(\Omega). \quad (2.1)$$

Here p is the unique $p \in \dot{W}_{q,\Gamma_2}^1(\Omega)$ such that $f = f_0 + \nabla p$ with $f_0 \in J_q(\Omega)$, where we note that

$$(f_0, \nabla \varphi)_\Omega = 0 \quad \text{for all } \varphi \in \dot{W}_{q,\Gamma_2}^1(\Omega)$$

since it holds for all $f_0 \in C_{(0)}^\infty(\Omega \cup \Gamma_2)$ and the latter space is dense in $J_q(\Omega)$ by definition. For the following we define

$$\dot{W}_{q,\Gamma_2}^{-1}(\Omega) := (\dot{W}_{q',\Gamma_2}^1(\Omega))'. \quad (2.2)$$

Then for every $F \in \dot{W}_{q,\Gamma_2}^{-1}$ there is some $f \in L^q(\Omega)^d$ such that $\|f\|_{L^q(\Omega)^d} \leq C\|F\|_{\dot{W}_{q,\Gamma_2}^{-1}(\Omega)}$ and

$$\langle F, \varphi \rangle_{\dot{W}_{q,\Gamma_2}^{-1}, \dot{W}_{q',\Gamma_2}^1} = (f, \nabla \varphi)_\Omega \quad \text{for all } \varphi \in \dot{W}_{q',\Gamma_2}^1(\Omega).$$

This follows from the Hahn-Banach theorem by identifying $\dot{W}_{q',\Gamma_2}^1(\Omega)$ with a closed subspace of $L^{q'}(\Omega)^d$ via the mapping $\varphi \mapsto \nabla \varphi$.

We summarize these facts in the following lemma.

Lemma 2.2 *Let Ω, q be as in Assumption 1.1. Then for every $F \in \dot{W}_{q,\Gamma_2}^{-1}(\Omega)$ and $a \in W_q^{1-\frac{1}{q}}(\partial\Omega)$ there is a $p \in \dot{W}_{q,\Gamma_2}^1(\Omega)$ such that*

$$(\nabla p, \nabla \varphi)_\Omega = \langle F, \varphi \rangle_{\dot{W}_{q,\Gamma_2}^{-1}, \dot{W}_{q',\Gamma_2}^1} \quad \text{for all } \varphi \in \dot{W}_{q',\Gamma_2}^1(\Omega), \quad (2.3)$$

$$p|_{\Gamma_2} = a \quad \text{on } \Gamma_2. \quad (2.4)$$

If $\Gamma_2 \neq \emptyset$, p is uniquely determined. If $\Gamma_2 = \emptyset$, then p is uniquely determined upto a constant. Moreover, there is some constant C_q independent of F such that

$$\|\nabla p\|_{L^q(\Omega)^d} \leq C_q \left(\|F\|_{\dot{W}_{q,\Gamma_2}^{-1}(\Omega)} + \|\nabla A\|_{L^q(\Omega)} \right).$$

Proof: First of all, one can easily reduce to the case $a = 0$ by extending a to some $A \in W_q^1(\Omega)$ and considering $p - A$ instead of p and replacing F by $F - (\nabla A, \cdot)_\Omega$. Therefore we can assume that $a = 0$. Then, as explained above, we find some $f \in L^q(\Omega)^d$ such that $\langle F, \varphi \rangle = (f, \nabla \varphi)_\Omega$ for all $\varphi \in \dot{W}_{q',\Gamma_2}^1(\Omega)$ and $\|f\|_{L^q(\Omega)} \leq C\|F\|_{\dot{W}_{q,\Gamma_2}^{-1}(\Omega)}$. Now $p \in \dot{W}_{q,\Gamma_2}^1(\Omega)$ solves (2.3), (2.1), resp., if and only if $f = f_0 + \nabla p$, where $f_0 \in J_q(\Omega)$, i.e., p is determined by the Helmholtz decomposition due to (A2). ■

3 Reduction of the Stokes System

The aim of this section is to reduce the Stokes system (1.1)-(1.4) for (v, p) to a system only in terms of the velocity v and to eliminate the divergence equation $\operatorname{div} v = g$. The idea goes back to Grubb and Solonnikov, cf. e.g. [39].¹ By this reduction the

¹In the latter work only the case $\operatorname{div} v = 0$ is considered. A corresponding reduction in the general case $\operatorname{div} v = g$ was first presented in [11].

pressure can be treated efficiently even in the case of the boundary condition (1.4) when the pressure enters the boundary condition and therefore cannot be eliminated from the system by applying a Helmholtz projection.

Now we will present the corresponding reduction for the case of general viscosity. Let $v \in W_q^2(\Omega)^d$, $p \in \dot{W}_q^1(\Omega)$ with $p|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$ be a solution of (1.1)-(1.4), where we assume that $f \in L^q(\Omega)^d$, $g \in W_q^1(\Omega)$ with $g|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$ and $g \in \dot{W}_{q,\Gamma_2}^{-1}(\Omega)$, cf. (2.2), $a \in W_q^{1-\frac{1}{q}}(\Gamma_2)$, $\lambda \in \Sigma_\delta$, and let $1 < q < \infty$ with $q, q' \leq \min(r_1, r_2)$, where r_1, r_2 and Ω are as in Assumption 1.1.

Now we reduce the Stokes system to a system for v by expressing the pressure p in dependence of v and the data (f, g, a) . To this end we multiply (1.1) by an arbitrary $\nabla\varphi$ with $\varphi \in \dot{W}_{q',\Gamma_2}^1(\Omega)$. Then

$$(\nabla p, \nabla\varphi)_\Omega = (f, \nabla\varphi)_\Omega + \lambda \langle g, \varphi \rangle_{\dot{W}_{q,\Gamma_2}^{-1}, \dot{W}_{q',\Gamma_2}^1} + (\operatorname{div}(2\nu Dv), \nabla\varphi)_\Omega,$$

where

$$\begin{aligned} (\operatorname{div}(2\nu Dv), \nabla\varphi)_\Omega &= (\nu(\Delta v + \nabla \operatorname{div} v), \nabla\varphi)_\Omega + (Dv, 2\nabla\nu \otimes \nabla\varphi)_\Omega \\ &= (\nu(\Delta - \nabla \operatorname{div})v, \nabla\varphi)_\Omega + (2\nu \nabla g, \nabla\varphi)_\Omega + (Dv, 2\nabla\nu \otimes \nabla\varphi)_\Omega. \end{aligned}$$

Hence

$$\begin{aligned} (\nabla p, \nabla\varphi)_\Omega &= (f, \nabla\varphi)_\Omega + \lambda \langle g, \varphi \rangle_{\dot{W}_{q,\Gamma_2}^{-1}, \dot{W}_{q',\Gamma_2}^1(\Omega)} + (2\nu \nabla g, \nabla\varphi)_\Omega \\ &\quad + (\nu(\Delta - \nabla \operatorname{div})v, \nabla\varphi)_\Omega + (Dv, 2\nabla\nu \otimes \nabla\varphi)_\Omega \end{aligned}$$

for all $\varphi \in \dot{W}_{q',\Gamma_2}^1(\Omega)$. Now, if $Pv \in \dot{W}_q^1(\Omega)$ with $Pv|_{\Gamma_2} \in W_p^{1-\frac{1}{p}}(\Gamma_2)$ is the solution of (1.8)-(1.9), then $p = Pv + \tilde{p}$, where \tilde{p} is determined by

$$(\nabla \tilde{p}, \nabla\varphi)_\Omega = (f, \nabla\varphi)_\Omega + \lambda \langle g, \varphi \rangle_{\dot{W}_{q,\Gamma_2}^{-1}, \dot{W}_{q',\Gamma_2}^1(\Omega)} + (2\nu \nabla g, \nabla\varphi)_\Omega, \quad (3.1)$$

$$\tilde{p}|_{\Gamma_2} = -a_n \quad (3.2)$$

for all $\varphi \in \dot{W}_{q',\Gamma_2}^1(\Omega)$. Hence \tilde{p} depends only on the data (f, g, a) . Here we note that \tilde{p} is uniquely determined by (3.1) (upto a constant if $\Gamma_2 = \emptyset$) due to Lemma 2.2.

This shows that $v \in W_q^2(\Omega)^d$ solves

$$\lambda v - \operatorname{div}(\nu \nabla v) + \nabla Pv - \nabla \nu^T \nabla v^T = f_r \quad \text{in } \Omega, \quad (3.3)$$

$$v|_{\Gamma_1} = 0 \quad \text{on } \Gamma_1, \quad (3.4)$$

$$(n \cdot S(v))_\tau|_{\Gamma_2} = a_\tau \quad \text{on } \Gamma_2, \quad (3.5)$$

$$\nu \operatorname{div} v|_{\Gamma_2} = \nu g|_{\Gamma_2} \quad \text{on } \Gamma_2, \quad (3.6)$$

where

$$f_r = f - \nabla \tilde{p} + \nu \nabla g. \quad (3.7)$$

Here we have used that

$$\operatorname{div}(2\nu Dv) = \operatorname{div}(\nu \nabla v) + \nabla \nu^T \nabla v^T + \nu \nabla \operatorname{div} v.$$

We call (3.3)-(3.6) the *reduced Stokes system*. We note that by the definition of the reduced Stokes operator A_q , cf. (1.6), $v \in W_q^2(\Omega)^d$ solves (1.1)-(1.4) for some right-hand side $f_r \in L^q(\Omega)^d$ and $a_\tau = 0, \nu g|_{\Gamma_2} = 0$ if and only if $v \in \mathcal{D}(A_q)$ and $(\lambda + A_q)v = f_r$.

To summarize we have shown:

Lemma 3.1 *Let $f \in L^q(\Omega)^d$, $g \in W_q^1(\Omega) \cap \dot{W}_{q,\Gamma_2}^{-1}(\Omega)$ with $g|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$, $a \in W_q^{1-\frac{1}{q}}(\Gamma_2)$ be given. Then any $v \in W_q^2(\Omega)^d$, $p \in \dot{W}_q^1(\Omega)$ with $p|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$ solving (1.1)-(1.4) is a solution of (3.3)-(3.6) if f_r is defined by (3.7) and if \tilde{p} solves (3.1)-(3.2).*

Note that in the reduced Stokes system (3.3)-(3.6) the divergence equation $\operatorname{div} v = g$ does not appear. Hence, if we want to obtain a solution of the original Stokes system (1.1)-(1.4) by solving the reduced system, it is crucial to prove that $\operatorname{div} v = g$ if the right-hand side is chosen as above. To this end we note that, if f_r is defined by (3.7), where \tilde{p} solves (3.1)-(3.2), then g can be derived back from f_r because of

$$-(f_r, \nabla \varphi)_\Omega = \lambda \langle g, \varphi \rangle_{\dot{W}_{q,\Gamma_2}^{-1}, \dot{W}_{q',\Gamma_2}^1} + (\nu \nabla g, \nabla \varphi)_\Omega \quad (3.8)$$

for all $\varphi \in \dot{W}_{q,\Gamma_2}^1(\Omega)$. On the other hand, if $v \in W_q^2(\Omega)^d$ solves (3.3)-(3.6), then

$$-(f_r, \nabla \varphi)_\Omega = \lambda \langle \operatorname{div} v, \varphi \rangle_{\dot{W}_{q,\Gamma_2}^{-1}, \dot{W}_{q',\Gamma_2}^1} + (\nu \nabla \operatorname{div} v, \nabla \varphi)_\Omega \quad (3.9)$$

for all $\varphi \in \dot{W}_{q,\Gamma_2}^1(\Omega)$ because of (3.3) multiplied with $-\nabla \varphi$ and

$$\begin{aligned} & (\operatorname{div}(\nu \nabla v), \nabla \varphi)_\Omega - (\nabla P v, \nabla \varphi)_\Omega + (\nabla \nu^T \nabla v^T, \nabla \varphi)_\Omega \\ &= (\nu \Delta v, \nabla \varphi)_\Omega - (\nabla P v, \nabla \varphi)_\Omega + (Dv, 2\nabla \nu \otimes \nabla \varphi)_\Omega = (\nu \nabla \operatorname{div} v, \nabla \varphi)_\Omega \end{aligned}$$

for all $\varphi \in \dot{W}_{q,\Gamma_2}^1(\Omega)$ due to (1.8).

In order to conclude $\operatorname{div} v = g$ we need the following assumption.

(A4') Let $\lambda \in \mathbb{C} \setminus (-\infty, 0)$ be such that there is no non-trivial $u \in W_{q,\Gamma_2}^1(\Omega)$ with

$$\lambda(u, \varphi)_\Omega + (\nu \nabla u, \nabla \varphi)_\Omega = 0 \quad \text{for all } \varphi \in W_{q',\Gamma_2}^1(\Omega).$$

Note the assumption (A4) is just (A4') for all $\lambda \in \Sigma_\delta$ with $|\lambda| \geq R$ and some $R > 0$. As mentioned above it will be shown later that (A1)-(A3) imply (A4) and therefore (A4') for large λ .

Altogether we obtain:

Lemma 3.2 *Let $f \in L^q(\Omega)^d$, $g \in W_q^1(\Omega) \cap \dot{W}_{q,\Gamma_2}^{-1}(\Omega)$ with $g|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$, $a \in W_q^{1-\frac{1}{q}}(\Gamma_2)$ be given and let f_r be defined as in (3.7) where \tilde{p} solves (3.1)-(3.2). Moreover, assume that (A4') holds. Then any solution $v \in W_q^2(\Omega)^d$ of (3.3)-(3.6) solves (1.1)-(1.4) where $p = Pv + \tilde{p} \in \dot{W}_q^1(\Omega)$ and $p|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$. Finally, (3.3)-(3.6) has no non-trivial solution $v \in W_q^2(\Omega)^d$ with right-hand side $(f_r, a_\tau, \nu g|_{\Gamma_2}) = 0$ if and only if (1.1)-(1.4) has no non-trivial solution $v \in W_q^2(\Omega)^d$, $p \in \dot{W}_q^1(\Omega)$ with $p|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$ and right-hand side $(f, g, a) = 0$.*

Proof: If v solves (3.3)-(3.6) with f_r as in (3.7) and \tilde{p} solving (3.1)-(3.2), then (3.8)-(3.9) imply

$$\lambda \langle g - \operatorname{div} v, \varphi \rangle_{\dot{W}_{q,\Gamma_2}^{-1}, \dot{W}_{q',\Gamma_2}^1} + (\nu \nabla(g - \operatorname{div} v), \varphi) = 0 \quad \text{for all } \varphi \in W_{q',\Gamma_2}^1(\Omega).$$

On the other hand, (3.6) implies $(g - \operatorname{div} v)|_{\Gamma_2} = 0$. Therefore $g - \operatorname{div} v \in W_{q,\Gamma_2}^1(\Omega)$ and $g - \operatorname{div} v = 0$ by (A4'). Thus v solves (1.2). Concerning the boundary condition, using (1.4) it can be easily shown that

$$p|_{\Gamma_2} = (n \cdot S(v))_n|_{\Gamma_2} - a_n,$$

where $(n \cdot S(v))_n|_{\Gamma_2}$ is equal to $2\nu \partial_n v_n$. Hence (1.4) follows. Altogether we obtain that (v, p) solve (1.1)-(1.4) with p as above.

Finally, assume that (3.3)-(3.6) has no non-trivial solution $v \in W_q^2(\Omega)^d$ with right-hand side $(f_r, a_\tau, \nu g|_{\Gamma_2}) = 0$. Moreover, let $v \in W_q^2(\Omega)^d$, $p \in \dot{W}_q^1(\Omega)$ with $p|_{\Gamma_2} \in W_q^{1-\frac{1}{q}}(\Gamma_2)$ be a solution of (1.1)-(1.4) with $(f, g, a) = 0$. Then $f_r = 0$ and therefore $v \in W_q^2(\Omega)^d$ solves (3.3)-(3.6) with zero right-hand side due to Lemma 3.1. Hence $v = 0$ by the assumption and therefore the solutions of (1.1)-(1.4) are unique.

Conversely, let $v \in W_q^2(\Omega)^d$ be a solution of (3.3)-(3.6) with right-hand side zero and assume that (1.1)-(1.4) has no non-trivial solution for zero data. Then $(f_r, \tilde{p}) = 0$ if \tilde{p} satisfies (3.1)-(3.2) and if f_r satisfies (3.7) for $(f, g, a) = 0$. Hence (v, p) with $p = Pv$ solve (1.1)-(1.4) with $(f, g, a) = 0$ by the first part of the lemma. Consequently $v = 0$, which proves the converse implication. ■

4 Coordinate Transformation

We start with a simple results on extensions of $\gamma \in W_r^{2-\frac{1}{r}}(\mathbb{R}^{d-1})$.

Lemma 4.1 *Let $\gamma \in W_r^{2-\frac{1}{r}}(\mathbb{R}^{d-1})$, $1 < r < \infty$ with $r > d$, and let $\varepsilon > 0$. Then there is some $\Gamma \in W_r^2(\mathbb{R}^d)$ such that $\Gamma(x', 0) = \gamma(x')$, $\partial_{x_d} \Gamma(x', 0) = 0$ and $|\partial_{x_d} \Gamma(x', x_d)| \leq \varepsilon$ for all $x \in \mathbb{R}^d$.*

Proof: Let $\tilde{\Gamma} \in W_r^2(\mathbb{R}^d)$ be an extension of $\gamma \in W_r^{2-\frac{1}{r}}(\mathbb{R}^{d-1})$ with $\partial_{x_d}\tilde{\Gamma}(x', 0) = 0$. Then $\Gamma_\lambda = \tilde{\Gamma}(x', \lambda x_d) \in W_r^2(\mathbb{R}^d)$ is also an extension of γ with $\partial_{x_d}\Gamma_\lambda(x', 0) = 0$ and

$$\|\partial_{x_d}\Gamma_\lambda\|_{L^\infty(\mathbb{R}^d)} = |\lambda|\|\partial_{x_d}\tilde{\Gamma}\|_{L^\infty(\mathbb{R}^d)} \rightarrow_{\lambda \rightarrow 0} 0$$

since $W_r^2(\mathbb{R}^d) \hookrightarrow C_b^1(\mathbb{R}^d)$ due to $r > d$. Now we can choose $\lambda > 0$ so small that $\Gamma \equiv \Gamma_\lambda$ satisfies the statement of the lemma. \blacksquare

The following proposition states the existence of a suitable coordinate transformation, which will lead to a nice structure of the boundary symbol operators of the transformed Stokes system on the half-space. It generalizes a result due to Schumacher [47] and is proved similarly.

Proposition 4.2 *Let $\gamma \in W_r^{2-\frac{1}{r}}(\mathbb{R}^{d-1})$ with $r > d$. Then there is some $F \in W_r^2(\mathbb{R}^d)^d$ such that $F: \mathbb{R}^d \rightarrow \mathbb{R}^d$ is a C^1 -diffeomorphism, $F(\mathbb{R}_+^d) = \mathbb{R}_\gamma^d$, $F(x', 0) = (x', \gamma(x'))$, and $-\partial_{x_d}F(x)|_{x_d=0} = n(x', \gamma(x'))$, where n denotes the exterior unit normal of $\partial\mathbb{R}_\gamma^d$.*

Proof: The case $r = \infty$ was proved in [47]. Hence it only remains to consider the case $d < r < \infty$. Let $\Gamma \in W_r^2(\mathbb{R}^d)$ be as in Lemma 4.1 with $\varepsilon = \frac{1}{2}$. Then we define

$$F(x) = \begin{pmatrix} x' \\ x_d + \Gamma(x) \end{pmatrix} - x_d k_D(D_x)\tilde{n} \equiv \tilde{F}(x) - x_d k_D(D_x)\tilde{n}$$

where $k_D(D_x)a = \mathcal{F}_{\xi' \mapsto x'}^{-1}[e^{-\langle \xi' \rangle |x_d|} \hat{a}(\xi')]$ and

$$\begin{aligned} \tilde{n}(x') &= n(x', \gamma(x')) + (\partial_{x_d}\Gamma(x', 0) + 1)e_d \\ &= \frac{1}{\sqrt{1 + |\nabla\gamma(x')|^2}} \left(\frac{\nabla\gamma(x')}{\sqrt{1 + |\nabla\gamma(x')|^2}} - 1 \right) \in B_{rr}^{1-\frac{1}{r}}(\mathbb{R}^{d-1}). \end{aligned}$$

Hence $-\partial_{x_d}F(x', 0) = n(x', \gamma(x'))$ since $k_D(D_x)\tilde{n}|_{x_d=0} = \tilde{n}$. Furthermore, $\tilde{F} \in W_r^2(\mathbb{R}^d)^d \hookrightarrow C_b^1(\mathbb{R}^d)^d$ is diffeomorphism on \mathbb{R}^d since $\tilde{F}(x', x_d)$ is a strictly increasing function in x_d for every fixed $x' \in \mathbb{R}^{d-1}$. Moreover, \tilde{F} maps \mathbb{R}_+^d onto \mathbb{R}_γ^d and $\|\nabla\tilde{F}^{-1}\|_{L^\infty} \leq 2$ since $\|\nabla\tilde{F} - I\|_{L^\infty} \leq \frac{1}{2}$. We note that $x_d k_D(D_x)$ is a Poisson operator of order -1 in the sense of Definition 5.10 below. Hence $f_\pm := x_d k_D(D_x)\tilde{n}|_{\mathbb{R}_\pm^d} \in W_r^2(\mathbb{R}_\pm^d)$ because of Theorem 5.15 below. Since $f_+|_{\partial\mathbb{R}_+^d} = f_-|_{\partial\mathbb{R}_+^d} = 0$ and $\partial_{x_d}f_+|_{\partial\mathbb{R}_+^d} = \partial_{x_d}f_-|_{\partial\mathbb{R}_+^d} = \tilde{n}$, we conclude that $x_d k_D(D_x)\tilde{n} \in W_r^2(\mathbb{R}^d)$. Furthermore,

$$\|x_d k_D(D_x)\tilde{n}\|_{C^1(\mathbb{R}^d)} \leq C\|x_d k_D(D_x)\tilde{n}\|_{W_r^2(\mathbb{R}^d)} \leq C'\|\nabla'\gamma\|_{W_r^{1-\frac{1}{r}}(\mathbb{R}^{d-1})}$$

by Theorem 5.15 again. Hence there is some $\varepsilon > 0$ such that $\|x_d k_D(D_x)\tilde{n}\|_{C^1(\mathbb{R}^d)} \leq \frac{1}{4} \leq \frac{1}{2}\|\nabla\tilde{F}^{-1}\|_\infty^{-1}$ provided that $\|\nabla\gamma\|_{W_r^{1-\frac{1}{r}}(\mathbb{R}^{d-1})} \leq \varepsilon$. But then

$$\nabla F(x) = I + \nabla\Gamma \otimes e_d - \nabla x_d k_D(D_x)\tilde{n}$$

is invertible and

$$\|\nabla F^{-1}\|_\infty \leq 4 \quad \text{provided that } \|\nabla' \gamma\|_{W_r^{1-\frac{1}{r}}(\mathbb{R}^{d-1})} \leq \varepsilon.$$

Moreover, $F: \mathbb{R}^d \rightarrow \mathbb{R}^d$ is globally invertible since $y = F(x)$ is equivalent to $x = \tilde{F}^{-1}(y + x_d k_D(D_x) \tilde{n}) \equiv H_y(x)$ and $H_y: \mathbb{R}^d \rightarrow \mathbb{R}^d$ is a contraction since $|\nabla_x H_y(x)| \leq \frac{1}{2}$.

For the general case we consider $\gamma_\lambda(x') = \gamma(\lambda x')$, $\lambda > 0$. Then

$$\|\nabla \gamma_\lambda\|_{W_r^{1-\frac{1}{r}}(\mathbb{R}^{d-1})} \leq C \|\nabla \gamma_\lambda\|_{L^r(\mathbb{R}^{d-1})}^{\frac{1}{r}} \|\nabla \gamma_\lambda\|_{W_r^{1-\frac{1}{r}}(\mathbb{R}^{d-1})}^{1-\frac{1}{r}} \xrightarrow{\lambda \rightarrow 0} 0$$

since $r > d$. Hence we can apply the first part and obtain a C^1 -diffeomorphism $F_\lambda: \mathbb{R}^d \rightarrow \mathbb{R}^d$ with respect to γ_λ . But then

$$F = \delta_{\lambda^{-1}} \circ F_\lambda \circ \delta_\lambda \quad \text{where } (\delta_\lambda f)(x) = f(\lambda x)$$

is a C^1 -diffeomorphism with the desired properties. ■

In the following we denote $(F^*u)(x) := u(F(x))$ for $u: \mathbb{R}_+^d \rightarrow \mathbb{R}$ and $(F^{*, -1}v)(x) := v(F^{-1}(x))$ for $v: \mathbb{R}_+^d \rightarrow \mathbb{R}$, where F is as in the latter proposition.

Corollary 4.3 *Let $\gamma \in W_r^{2-\frac{1}{r}}(\mathbb{R}^{d-1})$ with $r > d$. Then*

$$\begin{aligned} F^*: W_q^1(\mathbb{R}_+^d) &\rightarrow W_q^1(\mathbb{R}_+^d), \quad F^*: \dot{W}_q^1(\mathbb{R}_+^d) \rightarrow \dot{W}_q^1(\mathbb{R}_+^d) && \text{for all } 1 \leq q \leq \infty, \\ F^*: W_q^2(\mathbb{R}_+^d) &\rightarrow W_q^2(\mathbb{R}_+^d) && \text{for all } 1 \leq q \leq r \end{aligned}$$

continuously. Moreover, the corresponding statements are true for $F^{*, -1}$. Finally, if $(F_0^*a)(x') = a(x', \gamma(x'))$ for $a \in C_b^1(\partial \mathbb{R}_+^d)$ and $(F_0^{*, -1}a)(x) = a(F^{-1}(x)|_{\partial \mathbb{R}_+^d})$ for $a \in C_b^1(\mathbb{R}^{d-1})$, then

$$F_0^*: W_q^s(\partial \mathbb{R}_+^d) \rightarrow W_q^s(\mathbb{R}^{d-1})$$

is a bounded mapping for all $1 < q < \infty$, $0 \leq s < 1$, with continuous inverse $F_0^{*, -1}$.

Proof: The first statements easily follow from the chain and product rule, where we note that

$$\nabla(F^*u) = \nabla F(x)(\nabla u)(F(x))$$

where $\nabla F \in W_r^1(\mathbb{R}_+^d)$ and $(\nabla u)(F(x)) \in W_q^1(\mathbb{R}_+^d)$ if $u \in W_q^2(\Omega)$. Therefore $\nabla F F^*(\nabla u) \in W_q^1(\mathbb{R}_+^d)$ for all $1 \leq q \leq r$ due to Lemma 2.1.

For the last statement we note that $W_q^s(\partial \mathbb{R}_+^d)$ is normed by

$$\|a\|_{W_q^s(\partial \mathbb{R}_+^d)}^q = \|a\|_{L^q(\partial \mathbb{R}_+^d)}^q + \int_{L^q(\partial \mathbb{R}_+^d)} \int_{L^q(\partial \mathbb{R}_+^d)} \frac{|a(x) - a(y)|^q}{|x - y|^{d-1+sq}} d\sigma(x) d\sigma(y),$$

where $d\sigma$ denotes integration with respect to the surface measure on $\partial\mathbb{R}_\gamma^d$. Since $F_0 \equiv F|_{\mathbb{R}^{d-1}}: \mathbb{R}^{d-1} \rightarrow \partial\mathbb{R}_\gamma^d$ is a C^1 -diffeomorphism, $\|F_0^*a\|_{L^q(\mathbb{R}^{d-1})} \leq C\|a\|_{L^q(\partial\mathbb{R}_\gamma^d)}$ and

$$\begin{aligned} & \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^{d-1}} \frac{|a(F_0(x')) - a(F_0(y'))|^q}{|x' - y'|^{d-1+sq}} dx' dy' \\ & \leq C \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^{d-1}} \frac{|a(F_0(x')) - a(F_0(y'))|^q}{|F_0(x') - F_0(y')|^{d-1+sq}} J(x') J(y') dx' dy' \\ & = C \int_{\partial\mathbb{R}_\gamma^d} \int_{\partial\mathbb{R}_\gamma^d} \frac{|a(x) - a(y)|^q}{|F_0^{-1}(x) - F_0^{-1}(y)|^{d-1+sq}} d\sigma(x) d\sigma(y) \leq C\|a\|_{B_{qq}^s(\partial\mathbb{R}_\gamma^d)}^q \end{aligned}$$

where $J(z') = \det(\nabla F_0(z') \nabla F_0(z'))^{\frac{1}{2}}$. Hence $F_0^*: W_q^s(\partial\mathbb{R}_\gamma^d) \rightarrow W_q^s(\mathbb{R}^{d-1})$ is continuous. The statement for $F_0^{*, -1}$ is proved in the same way. \blacksquare

Corollary 4.4 *Let $d < r_2 \leq \infty$, $1 \leq q < \infty$, and let $\Omega \subseteq \mathbb{R}^d$, $d \geq 2$, be a domain satisfying the assumption (A1). Then there are linear bounded operators $E_0: W_q^{1-\frac{1}{q}}(\partial\Omega) \rightarrow W_q^1(\Omega)$ and $E_1: W_q^{2-\frac{1}{q}}(\partial\Omega) \times W_q^{1-\frac{1}{q}}(\partial\Omega) \rightarrow W_q^2(\Omega)$ if $1 < q \leq r$ such that*

$$\gamma_0 E_0 a = a \quad \text{and} \quad \begin{pmatrix} \gamma_0 \\ \gamma_1 \end{pmatrix} E_1 b = b$$

for all $a \in W_q^{1-\frac{1}{q}}(\partial\Omega)$, $b \in W_q^{2-\frac{1}{q}}(\partial\Omega) \times W_q^{1-\frac{1}{q}}(\partial\Omega)$.

Proof: First let $\Omega = \mathbb{R}_\gamma^d$ with $\gamma \in W_{r_2}^{2-\frac{1}{r_2}}(\mathbb{R}^{d-1})$. Using Proposition 4.2 and Corollary 4.3, the statement is easily reduced to the corresponding statements for a half-space \mathbb{R}_+^d , where we note that $-\partial_d F^* v|_{\mathbb{R}^{d-1}} = F_0^* \partial_n v|_{\partial\mathbb{R}_\gamma^d} = F_0^* \gamma_1 v$ for all $v \in C_{(0)}^1(\overline{\mathbb{R}_\gamma^d})$.

If Ω is a general domain satisfying the assumption (A1), then the statement for E_0 is easily reduced to the case of finitely many bent half-spaces $\mathbb{R}_{\gamma_j}^d$ using the partition of unity assumed in (A1). The extension operator $E_1 b$ can be constructed as follows: Let $v \in W_q^2(\Omega)$ be such that $v|_{\partial\Omega} = b_1$, where $b = (b_1, b_2)$. Moreover, let $w_j \in W_q^2(\mathbb{R}_{\gamma_j}^d)$ be such that $w_j|_{\partial\mathbb{R}_{\gamma_j}^d} = 0$ and $\partial_n w_j|_{\partial\mathbb{R}_{\gamma_j}^d} = \psi_j b_2 - \psi_j \partial_n v|_{\partial\mathbb{R}_{\gamma_j}^d}$. Then $w = \sum_{j=1}^N \varphi_j w_j$ satisfies $w|_{\partial\Omega} = 0$ and $\partial_n w|_{\partial\Omega} = b_2 - \partial_n v|_{\partial\Omega}$. Therefore $E_1 b := v + w$ has the desired properties. Obviously, the extension operators can be constructed to become bounded operators. \blacksquare

In the following we will denote the variables and operators corresponding to the original problem in \mathbb{R}_γ^d by x, ξ, ∇, \dots and of the transformed problem in \mathbb{R}_+^d by $\underline{x}, \underline{\xi}, \underline{\nabla}, \dots$. Similarly, $\underline{a}(\underline{x}', \underline{\xi})$ will indicate the symbols of the transformed problem and $a(\xi)$ the symbols of the model operator (the corresponding operator on \mathbb{R}_+^d).

In the following, let $U = U(\underline{x}')$ be an orthonormal matrix which maps the exterior normal vector

$$\underline{n}(\underline{x}') = \frac{1}{\sqrt{1 + |\nabla' \gamma(\underline{x}')|^2}} \begin{pmatrix} \nabla' \gamma(\underline{x}') \\ -1 \end{pmatrix}$$

on $\partial\mathbb{R}_\gamma^d$ at the point $(\underline{x}', \gamma(\underline{x}'))$ to $-e_d$, which is the exterior normal on \mathbb{R}_+^d .

Using this notation,

$$\nabla F^{*, -1} v = F^{*, -1} U^T(\underline{x}') A(\underline{x}) \nabla v = F^{*, -1} \text{OP}(U^T(\underline{x}') A(\underline{x}) i \underline{\xi}) v,$$

where $A(\underline{x}) \underline{\xi} = U(\underline{x}') (\nabla_{\underline{x}} F(\underline{x}))^{-1} \underline{\xi}$ and $v \in C^1(\overline{\mathbb{R}_\gamma^d})$. Then $(A|_{x_d=0})^{-T}$ has the structure

$$A(\underline{x}', 0)^{-T} = U(\underline{x}') \begin{pmatrix} I' & -\underline{n}'(\underline{x}') \\ \nabla' \gamma(\underline{x}')^T & -\underline{n}_d(\underline{x}') \end{pmatrix} = \begin{pmatrix} A'(\underline{x}')^{-T} & 0 \\ 0 & 1 \end{pmatrix} \quad (4.1)$$

due to Proposition 4.2, where $A'(\underline{x}', 0)$ depends smoothly on $\nabla' \gamma(\underline{x}')$. Hence $A|_{x_d=0}$ has the same structure with $A'(\underline{x}', 0)^{-T}$ replaced by $A'(\underline{x}', 0)$.

Remark 4.5 Note that relation (4.1) is of much simpler structure as the corresponding relation in the previous work [11, Equation (5.15)]. This leads to some simplifications in the present proofs. The more complicated structure in [11] was due to the simple coordinate transformation $\tilde{F}(x) = \begin{pmatrix} x' \\ x_d + \gamma(x') \end{pmatrix}$, which was used in order to deal with a boundary of regularity $C^{1,1}$. The coordinate transformation due to Proposition 4.2 admits to work $C^{1,1}$ -boundary again (if $r_2 = \infty$). But it has the same structural properties as the coordinate transformation used in [32, 33], i.e., that normal directions are preserved at the boundary, which leads to (4.1). Note that, if one would apply directly the coordinate transformation used in [32, 33], one would need higher regularity assumptions on $\partial\Omega$ e.g. $C^{2,1}$ instead of $C^{1,1}$.

In the following we will for simplicity write $A(\underline{x}')$ instead of $A((\underline{x}', 0))$. Moreover, we denote $\gamma_j u = (-\partial_{x_d})^j u|_{\partial\mathbb{R}_+^d}$ and $\gamma_n v = n \cdot \gamma_0 v$. More generally, the transformed differential and trace operators needed in the following are considered in the next lemma.

Lemma 4.6 *Let $v \in C_{(0)}^\infty(\overline{\mathbb{R}_\gamma^d})$, $u \in C_{(0)}^\infty(\overline{\mathbb{R}_\gamma^d})^d$, and let F be as in Proposition 4.2. Then*

$$\begin{aligned} F^* \nabla v &= \underline{\nabla} F^* v, & F^* \operatorname{div} u &= \underline{\operatorname{div}} F^* u, & F^* \Delta u &= \underline{\Delta} F^* u + R_1 F^* u, \\ F_0^* \gamma_n u &= \underline{\gamma}_n F^* u, & F_0^* \gamma_1 v &= \underline{\gamma}_1 F^* v, & F_0^* T_1' u &= \underline{t}_1'(\underline{x}', D_x) F^* u, \end{aligned}$$

where

1. $\underline{\nabla} = \text{OP}(U^T(\underline{x}') A(\underline{x}) i \underline{\xi})$, $\underline{\operatorname{div}} u = \text{OP}((A(\underline{x}) i \underline{\xi})^T U(\underline{x}')) u$, $\underline{\Delta} = -\text{OP}(|A(\underline{x}) \underline{\xi}|^2)$, $\underline{\gamma}_n = -e_d \cdot \gamma_0 U(\underline{x}')$, and $\underline{\gamma}_1 = \underline{\gamma}_n \underline{\nabla} = -\gamma_0 \partial_d$.
2. R_1 is a differential operator of order 1 with L^{r_2} -coefficients, $r_2 > d$.
3. $\underline{t}_1'(\underline{x}', D_x) u = -\gamma_0 U^T(\underline{x}') \text{OP} \begin{pmatrix} i \underline{\xi}_d I' & A'(\underline{x}') i \underline{\xi}' \\ (A'(\underline{x}') i \underline{\xi}')^T & i \underline{\xi}_d \end{pmatrix} U(\underline{x}') u$.

If additionally $\gamma_0 u = 0$, then

$$F_0^* \gamma_n (\Delta - \nabla \operatorname{div}) u = \underline{t}_0(\underline{x}', D_x) F^* u$$

where $\underline{t}_0(\underline{x}', D_x) = \operatorname{OP}'((A'(\underline{x}') i \xi')^T (U(\underline{x}') \gamma_1))$.

Proof: The proof is done in the same way as in [11, Lemma 5.6] except for the last statement. In order to prove the last statement, we use the identity

$$n \cdot (\Delta - \nabla \operatorname{div}) u|_{\partial \mathbb{R}_\gamma^d} = \operatorname{div}_\tau \partial_n u|_{\partial \mathbb{R}_\gamma^d} \quad \text{if } \gamma_0 u = 0.$$

Here $\operatorname{div}_\tau w = \operatorname{Tr}(P_\tau \nabla W)|_{\partial \mathbb{R}_\gamma^d}$ for all $w \in C^1(\partial \mathbb{R}_\gamma^d)^d$ where $W \in C^1(\overline{\mathbb{R}_\gamma^d})^d$ is an arbitrary extension of w and $P_\tau = P_\tau(x)$ denotes the orthogonal projection onto the tangent space of $\partial \mathbb{R}_\gamma^d$ at $x \in \partial \mathbb{R}_\gamma^d$. It is easy to check that

$$F_0^*(P_\tau)(\underline{x}') = U^T(\underline{x}')(I - e_d \otimes e_d)U(\underline{x}').$$

Hence

$$\begin{aligned} F_0^*(\operatorname{div}_\tau w) &= \operatorname{Tr}(U^T(\underline{x}')(I - e_d \otimes e_d)U(\underline{x}')U^T(\underline{x}')A(\underline{x}')\nabla F^* w)|_{x_d=0} \\ &= \operatorname{Tr}(U^T(\underline{x}')(I - e_d \otimes e_d)A(\underline{x}')\nabla F^* w)|_{x_d=0} \\ &= \mathcal{F}_{\xi \mapsto x}^{-1} [\operatorname{Tr}(U^T(\underline{x}')(I - e_d \otimes e_d)A(\underline{x}')i\xi \otimes \hat{v}(\xi))]|_{x_d=0} \\ &= \mathcal{F}_{\xi' \mapsto x'}^{-1} [(A'(\underline{x}') i \xi')^T (U(\underline{x}') \dot{v}(\xi', 0))'] \end{aligned}$$

where $v = F^* w$. From this identity the statement follows because of $F_0^*(\partial_n u|_{\partial \mathbb{R}_\gamma^d}) = \gamma_1 F_0^* u$. \blacksquare

Lemma 4.7 *Let $d < r_2 \leq \infty$, $1 < q \leq r_2$, $j = 0, 1$, $\lambda \in \mathbb{C}$, and let $\Omega \subseteq \mathbb{R}^d$, $d \geq 2$, be a domain satisfying the assumption (A1). Then there is a continuous extension operator $E_j: W_q^{2-j-\frac{1}{q}}(\Omega) \rightarrow W_q^2(\Omega)$ such that*

$$\langle \lambda \rangle \|E_j a\|_{L^q(\Omega)} + \|\nabla^2 E_j a\|_{L^q(\Omega)} \leq C \left(\langle \lambda \rangle^{1-\frac{j}{2}-\frac{1}{2q}} \|a\|_{L^q(\partial\Omega)} + \|a\|_{W_q^{2-j-\frac{1}{q}}(\partial\Omega)} \right) \quad (4.2)$$

for $j = 0, 1$ and $T_1' E_1 a = a$ as well as $E_0 a|_{\partial\Omega} = a$, where T_1' is defined as in (1.7).

Proof: First let $j = 0$ and let $\Omega = \mathbb{R}_\gamma^d$, $\gamma \in W_{r_2}^{2-\frac{1}{r_2}}(\mathbb{R}^{d-1})$. Using the coordinate transformation due Proposition 4.2, the statement is easily reduced to case of a half-space \mathbb{R}_+^d . In the latter case the statement can be reduced to the case $\lambda = 1$ by the same scaling argument as in [38, Section 1.1]. If $j = 0$ and Ω is a general domain satisfying the assumption (A1), then one can prove the statement easily with the aid of the partition of unity and the statement for a bent half space.

Next let $j = 1$. Then we choose $E_1 a \in W_q^2(\Omega)$ such that $E_1 a|_\Omega = 0$ and $\partial_n E_1 a|_{\partial\Omega} = \nu^{-1} a$. By the same arguments as in the case $j = 0$ one can choose

$E_1 a$ such that (4.2) holds. (Again one reduces to the case of a half-space and uses a simple scaling argument). Then

$$\begin{aligned} (T'_1 E_1 a)_\tau &= \nu ((\partial_n E_1 a)_\tau + \nabla_\tau E_1 a_n)|_{\partial\Omega} = a_\tau + 0 \\ (T'_1 E_1 a)_n &= \nu (\operatorname{div}((I - n \otimes n)E_1 a) + (\partial_n E_1 a)_n)|_{\partial\Omega} = 0 + a_n \end{aligned}$$

since $E_1 a|_{\partial\Omega} = 0$. Hence $T'_1 E_1 a = a$. ■

5 Construction of the Approximative Resolvent

The proof of Theorem 1.3 is based on the following result.

THEOREM 5.1 *Let \mathbb{R}_γ^d , $d \geq 2$, $\gamma \in W_{r_2}^{2-\frac{1}{r_2}}(\mathbb{R}^{d-1})$, be a bent half-space, let ν, q, r, r_2, τ be as in Assumption 1.1, $j = 0, 1$, and let $\delta \in (0, \pi)$. Then there are bounded operators $R_{j,\lambda}: L^q(\mathbb{R}_\gamma^d)^d \rightarrow W_q^2(\mathbb{R}_\gamma^d)^d$, $G_{j,\lambda}: L^q(\mathbb{R}_\gamma^d)^d \rightarrow W_q^1(\mathbb{R}_\gamma^d)^d$ such that*

$$(\lambda - \operatorname{div}(\nu \nabla \cdot))R_{j,\lambda}f + \nabla G_{j,\lambda}f = f + S_{j,\lambda}f \quad \text{in } \mathbb{R}_\gamma^d, \quad (5.1)$$

$$R_{0,\lambda}f|_{\partial\mathbb{R}_\gamma^d} = 0 \quad \text{on } \partial\mathbb{R}_\gamma^d \quad \text{if } j = 0, \quad (5.2)$$

$$T'_1 R_{1,\lambda}f = 0 \quad \text{on } \partial\mathbb{R}_\gamma^d \quad \text{if } j = 1, \quad (5.3)$$

for every $f \in L^q(\mathbb{R}_\gamma^d)^d$ and $\lambda \in \mathbb{C} \setminus (-\infty, 0]$ as well as

$$(\nabla G_{j,\lambda}f, \nabla \varphi)_{\mathbb{R}_\gamma^d} = (\nu(\Delta - \nabla \operatorname{div})R_{j,\lambda}f, \nabla \varphi)_{\mathbb{R}_\gamma^d} + \langle S'_{j,\lambda}f, \varphi \rangle_{W_{q,0}^{-1}, W_q^1} \quad (5.4)$$

for all $\varphi \in W_q^1(\mathbb{R}_\gamma^d)$ with $\varphi|_{\partial\mathbb{R}_\gamma^d} = 0$ if $j = 1$ and

$$G_{1,\lambda}f|_{\partial\mathbb{R}_\gamma^d} = 2\nu(\partial_n R_{1,\lambda}f)_n|_{\partial\mathbb{R}_\gamma^d} + S''_\lambda f \quad \text{on } \partial\mathbb{R}_\gamma^d \quad (5.5)$$

where

$$\|S_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d))} + \|S'_{0,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d), W_{q,0}^{-1}(\mathbb{R}_\gamma^d))} \leq C_{q,\delta}(1 + |\lambda|)^{-\varepsilon}, \quad (5.6)$$

$$\|S'_{1,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d), W_q^{-1}(\mathbb{R}_\gamma^d))} + \|S''_\lambda\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d), W_q^{1-\frac{1}{q}}(\partial\mathbb{R}_\gamma^d))} \leq C_{q,\delta}(1 + |\lambda|)^{-\varepsilon} \quad (5.7)$$

uniformly in $\lambda \in \Sigma_\delta$ for some $\varepsilon > 0$. Moreover,

$$(1 + |\lambda|)\|R_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d))} + \|\nabla^2 R_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d))} \leq C_{q,\delta}, \quad (5.8)$$

$$(1 + |\lambda|^{\frac{1}{2}})\|G_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d))} + \|\nabla G_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d))} \leq C_{q,\delta}, \quad (5.9)$$

$$\left\| \int_{\Gamma_R} h(-\lambda) R_{j,\lambda} d\lambda \right\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d))} \leq C_{q,\delta} \|h\|_\infty, \quad (5.10)$$

uniformly in $\lambda \in \Sigma_\delta$ and $h \in H(\delta)$.

Remark 5.2 Here the operator $G_{j,\lambda}$ represents the principal part of $PR_{j,\lambda}$, cf. (1.8)-(1.9) and note that the term $\nabla \nu^T Dv$ is of lower order compared to $\nu(\Delta - \nabla \operatorname{div})v$. Lower order terms in general will give rise to a contribution to the remainder terms $S_{j,\lambda}$, $S'_{j,\lambda}$, and S''_λ .

The theorem will be proved with aid of the calculus of pseudodifferential boundary value problems with non-smooth coefficient as developed in [9, 11].

5.1 Pseudodifferential Operators with Non-Smooth Coefficients

In the following we denote $D_{x_j} = \frac{1}{i} \partial_{x_j}$ and $D_x = (D_{x_1}, \dots, D_{x_d})$.

Definition 5.3 Let X be a Banach space and let $\tau > 0$. Then the symbol space $\mathcal{C}^\tau S_{1,0}^m(\mathbb{R}^d \times \mathbb{R}^d; X)$, $m \in \mathbb{R}$, is the set of all functions $p: \mathbb{R}^d \times \mathbb{R}^d \rightarrow X$ that are smooth with respect to ξ and are in $\mathcal{C}^\tau(\mathbb{R}^d)$ with respect to x satisfying

$$\|D_\xi^\alpha p(\cdot, \xi)\|_{\mathcal{C}^\tau(\mathbb{R}^d; X)} \leq C_\alpha \langle \xi \rangle^{m-|\alpha|}$$

for all $\alpha \in \mathbb{N}_0^d$. Moreover, we define for $k \in \mathbb{N}$ the semi-norm

$$|p|_k^{(m)} := \sup_{|\alpha| \leq k, \xi \in \mathbb{R}^d} \langle \xi \rangle^{|\alpha|-m} \|D_\xi^\alpha p(\cdot, \xi)\|_{\mathcal{C}^\tau(\mathbb{R}^d; X)}.$$

Finally, $\mathcal{C}^\tau S_{1,0}^m(\mathbb{R}^d \times \mathbb{R}^d; X)$ denotes the corresponding space with \mathcal{C}^τ replaced by C^τ .

Given $p \in \mathcal{C}^\tau S_{1,0}^m(\mathbb{R}^d \times \mathbb{R}^d; \mathcal{L}(X_0, X_1))$, where X_0, X_1 are two Banach spaces, we define

$$\begin{aligned} p(x, D_x)u &\equiv \operatorname{OP}(p(x, \xi))u = \int_{\mathbb{R}^d} e^{ix \cdot \xi} p(x, \xi) \hat{u}(\xi) d\xi \quad \text{and} \\ p(D_x, x)u &\equiv \operatorname{OP}(p(y, \xi))u = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} e^{i(x-y) \cdot \xi} p(y, \xi) u(y) dy d\xi \end{aligned} \quad (5.11)$$

for $u \in \mathcal{S}(\mathbb{R}^d; X_0)$ are the associated pseudodifferential operators in L - and R -form, respectively; also called x -form and y -form. Here the second integral has to be understood as iterated integral or oscillatory integral, cf. [41, Theorem 2.2]. If $p \in \mathcal{C}^\tau S_{1,0}^m(\mathbb{R}^{d-1} \times \mathbb{R}^{d-1}; \mathcal{L}(X_0, X_1))$, then $p(x', D_{x'}) = \operatorname{OP}'(p(x', \xi'))$ and $p(D_{x'}, x') = \operatorname{OP}'(p(y', \xi'))$ denote the corresponding pseudodifferential operators acting on functions defined on \mathbb{R}^{d-1} .

Concerning boundedness on Bessel potential spaces, we recall

THEOREM 5.4 Let $\tau > 0$, $1 < q < \infty$, $m \in \mathbb{R}$, and let H_0, H_1 be Hilbert spaces. If $p \in \mathcal{C}^\tau S_{1,0}^m(\mathbb{R}^d \times \mathbb{R}^d; \mathcal{L}(H_0, H_1))$ and $s \in (-\tau, \tau)$, then $p(x, D_x)$ and $p(D_x, x)$ extend to bounded linear operators

$$\begin{aligned} p(x, D_x): H_q^{s+m}(\mathbb{R}^d; H_0) &\rightarrow H_q^s(\mathbb{R}^d; H_1) \quad \text{and} \\ p(D_x, x): H_q^s(\mathbb{R}^d; H_0) &\rightarrow H_q^{s-m}(\mathbb{R}^d; H_1). \end{aligned}$$

Moreover, the operators depend continuously on the symbols with respect to the operator norm and the symbol semi-norms.

We refer to [11, Theorem 3.2] for references and comments on the proof. The continuous dependence is not stated explicitly there; but this follows from linearity of the mapping $p \mapsto (p(x, D_x), p(D_x, x))$ and the fact that the operator norms can be bounded in terms of the symbol semi-norms only.

Note that the latter theorem is also true for $p \in C^\tau S_{1,0}^m(\mathbb{R}^d \times \mathbb{R}^d; \mathcal{L}(H_0, H_1))$ since $C^\tau(\mathbb{R}^d; X) = \mathcal{C}^\tau(\mathbb{R}^d; X)$ for $\tau \notin \mathbb{N}$ and $(-\tau, \tau)$ is an open interval. (Hence the result for $\tau \in \mathbb{N}$ follows from the result for $\tau' \notin \mathbb{N}$ with $|s| < \tau' < \tau$.)

In order to deal with the low regularity of $\nu \in W_{r_1}^1(\Omega)$ and $\gamma \in W_{r_2}^{2-\frac{1}{r_2}}(\mathbb{R}^{d-1})$ we need the following commutator estimate.

Lemma 5.5 *Let $a \in B_{rr}^\tau(\mathbb{R}^d)$, $\tau > 0$, $1 \leq r \leq \infty$, such that $\tau > \frac{d}{r}$. Then*

$$[a(x), \langle D_x \rangle^s]: H_q^{s-\theta}(\mathbb{R}^d) \rightarrow L^q(\mathbb{R}^d)$$

is a bounded operator for all $0 \leq s \leq \tau$, $1 < q < \infty$ with $q \leq r$ and all $0 < \theta < \min(1, \tau - \frac{d}{r})$.

The lemma is a consequence of Marschall [43, Corollary 3.4], where we note that $[a(x), \langle D_x \rangle^s] = \langle D_x \rangle^s a(x) - OP(a(x)\langle \xi \rangle^s)$.

Next we define a non-smooth variant of the classes of parameter-dependent pseudodifferential operators studied in [37]. To this end, we denote $\rho(\xi, \mu) = \langle \xi \rangle \langle (\xi, \mu) \rangle^{-1}$.

Definition 5.6 *Let $m, \nu \in \mathbb{R}$. Then $C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^d \times \overline{\mathbb{R}}_+^{d+1})$ is the space of all functions $p(x, \xi, \mu)$ smooth w.r.t. (ξ, μ) and in C^τ w.r.t. x such that*

$$\|D_\xi^\alpha D_\mu^j p(\cdot, \xi, \mu)\|_{C^\tau(\mathbb{R}^d)} \leq C_{\alpha,j}(\rho(\xi, \mu)^{\nu-|\alpha|} + 1) \langle \xi, \mu \rangle^{m-|\alpha|-j}$$

uniformly in $(\xi, \mu) \in \overline{\mathbb{R}}_+^{d+1}$ and for all $\alpha \in \mathbb{N}_0^d$, $j \in \mathbb{N}_0$. Moreover, let

$$|p|_k^{(m,\nu)} = \sup_{|\alpha|, j \leq k, (\xi, \mu) \in \overline{\mathbb{R}}_+^{d+1}} \|D_\xi^\alpha D_\mu^j p(\cdot, \xi, \mu)\|_{C^\tau(\mathbb{R}^d)} (\rho(\xi, \mu)^{\nu-|\alpha|} + 1)^{-1} \langle \xi, \mu \rangle^{-m+|\alpha|+j}$$

be the corresponding increasing sequence of semi-norms.

We note that

$$(\rho(\xi, \mu)^\nu + 1) \langle \xi, \mu \rangle^m \simeq \begin{cases} \langle \xi, \mu \rangle^m & \text{if } \nu \geq 0, \\ \langle \xi \rangle^\nu \langle \xi, \mu \rangle^{m-\nu} & \text{if } \nu < 0. \end{cases}$$

Remark 5.7 If $p \in C^\tau S_{1,0}^{m,\nu}$ and $m' > m$, then $p \in C^\tau S_{1,0}^{m',\nu}$ with $|p|_k^{(m',\nu)} \leq \langle \mu \rangle^{m-m'} |p|_k^{(m,\nu)}$ for all $k \in \mathbb{N}_0$. Moreover, if $m \leq 0$, $\nu \geq 0$ and if we look at p as a parameter-independent symbol with fixed $\mu \geq 0$, then $|p(\cdot, \mu)|_k^{(m)} \leq C |p|_k^{(m,\nu)}$ uniformly in $\mu \in \overline{\mathbb{R}}_+$.

In order to deal with the symbols after coordinate transformation, we use the following simple lemma.

Lemma 5.8 *Let $p(\xi, \mu) \in S_{1,0}^{m,\nu}(\mathbb{R}^d \times \overline{\mathbb{R}}_+^{d+1})$, $m, \nu \in \mathbb{R}$, and $A \in C^\tau(\mathbb{R}^d)^{d \times d}$, $\tau > 0$, with $A^{-1} \in C^\tau(\mathbb{R}^d)^{d \times d}$. Then $q(x, \xi, \mu) := p(A(x)\xi, \mu) \in C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^d \times \overline{\mathbb{R}}_+^{d+1})$, and for every $k \in \mathbb{N}_0$ there is some $k' \in \mathbb{N}_0$ such that $|q|_k^{(m,\nu)} \leq C|p|_{k'}^{(m,\nu)}$, where C depends only on $\|A\|_{C^\tau}$, $\|A^{-1}\|_{C^\tau}$, k, m, ν , and d .*

Proof: The proof is a simple variant of the proof of [11, Lemma 5.4]. ■

5.2 Pseudodifferential Boundary Value Problems with Non-Smooth Coefficients

We recall a non-smooth version of parameter-dependent Green operators developed in [37] as defined in [11] with the only difference that $C^{0,1}$ -regularity w.r.t. x is replaced by C^τ -regularity for some $\tau > 0$. We use the notation of [37] except that $\gamma_j u = (-1)^d \partial_d^j u|_{\partial \mathbb{R}_+^d}$. Recall that $\overline{\mathbb{R}}_{++}^2 = \overline{\mathbb{R}}_+ \times \overline{\mathbb{R}}_+$.

We start with the definition of the symbol-kernels of non-smooth Poisson, trace, and singular Green operators.

Definition 5.9 *The space $C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^N \times \overline{\mathbb{R}}_+^d, \mathcal{S}(\overline{\mathbb{R}}_+))$, $m, \nu \in \mathbb{R}$, $d, N \in \mathbb{N}$, consists of all functions $\tilde{f}(x, \xi', \mu, y_d)$, which are smooth in $(\xi', \mu, y_d) \in \overline{\mathbb{R}}_+^d \times \overline{\mathbb{R}}_+$, are in $C^\tau(\mathbb{R}^N)$ with respect to x , and satisfy*

$$\begin{aligned} & \|y_d^l \partial_{y_d}^{l'} \partial_\mu^j D_{\xi'}^\alpha \tilde{f}(\cdot, \xi', \mu, \cdot)\|_{C^\tau(\mathbb{R}^N; L_{y_d}^2(\mathbb{R}_+))} \\ & \leq C_{\alpha,j,l,l'}(\rho(\xi', \mu)^{\nu-[l-l']_+-|\alpha|} + 1) \langle \xi', \mu \rangle^{m+\frac{1}{2}-l+l'-|\alpha|-j} \end{aligned} \quad (5.12)$$

for all $\alpha \in \mathbb{N}_0^{d-1}$, $j, l, l' \in \mathbb{N}_0$.

Similarly, the space $C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^N \times \overline{\mathbb{R}}_+^d, \mathcal{S}(\overline{\mathbb{R}}_{++}^2))$, $m, \nu \in \mathbb{R}$, $d, N \in \mathbb{N}$, is the space of all $\tilde{f}(x, \xi', y_d, z_d)$, which are smooth in $(\xi', \mu, y_d, z_d) \in \overline{\mathbb{R}}_+^d \times \overline{\mathbb{R}}_{++}^2$ and which are in $C^\tau(\mathbb{R}^N)$ with respect to x such that

$$\begin{aligned} & \|y_d^k \partial_{y_d}^{k'} z_d^l \partial_{z_d}^{l'} \partial_\mu^j D_{\xi'}^\alpha \tilde{f}(\cdot, \xi', \cdot)\|_{C^\tau(\mathbb{R}^N; L_{y_d, z_d}^2(\mathbb{R}_{++}^2))} \\ & \leq C_{\alpha,j,k,k',l,l'}(\rho^{\nu-[k-k']_+-[l-l']_+-|\alpha|} + 1) \langle \xi', \mu \rangle^{m+1-k+k'-l+l'-|\alpha|-j} \end{aligned} \quad (5.13)$$

for all $\alpha \in \mathbb{N}_0^{d-1}$, $j, k, k', l, l' \in \mathbb{N}_0$, where $\rho = \rho(\xi', \mu)$. Finally, m is called the degree of the symbols $f \in C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^N \times \overline{\mathbb{R}}_+^d, \mathcal{K})$, $\mathcal{K} = \mathcal{S}(\overline{\mathbb{R}}_+), \mathcal{S}(\overline{\mathbb{R}}_{++}^2)$.

Now the Poisson operators with non-smooth coefficients are defined in almost the same way as in the smooth case:

Definition 5.10 *Let $\tilde{k} = \tilde{k}(x, \xi', y_n) \in C^\tau S_{1,0}^{m-1,\nu}(\mathbb{R}^d \times \overline{\mathbb{R}}_+^d, \mathcal{S}(\overline{\mathbb{R}}_+))$, $m, \nu \in \mathbb{R}$. Then we define the Poisson operator of order m by*

$$k(x, \mu, D_x)a = \mathcal{F}_{\xi' \mapsto x'}^{-1} \left[\tilde{k}(x, \xi', \mu, x_d) \hat{a}(\xi') \right], \quad a \in \mathcal{S}(\mathbb{R}^{d-1}).$$

Finally, we note that the *boundary symbol operator* $k(x, \xi', \mu, D_d): \mathbb{C} \rightarrow \mathcal{S}(\overline{\mathbb{R}}_+)$ is defined as a one-dimensional operator with symbol-kernel $\tilde{k}(x, \xi', \mu, y_d)$ for fixed (x', ξ', μ) , which is simply defined by $k(x, \xi', \mu, D_d)a = \tilde{k}(x, \xi', \mu, x_d)a$ for all $a \in \mathbb{C}$. As usually, Poisson operators can be considered as operator-valued pseudodifferential operators with values in $\mathcal{L}(\mathbb{C}; H)$, where H is a suitable space of functions on \mathbb{R}_+ , e.g. $H^m(\mathbb{R}_+)$ or $L^2(\mathbb{R}_+, x_d^s)$, $m, s \geq 0$. Having this in mind, $k(D_x, x', \mu) = OP'(k(y', \xi', \mu, D_d))$ denotes the corresponding pseudodifferential operator in y -form as defined in (5.11).

The trace and singular Green operators are defined as follows:

Definition 5.11 *Let $m, \nu \in \mathbb{R}$ and let $r \in \mathbb{N}_0$.*

1. *If $\tilde{t}_0 \in C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^{d-1} \times \overline{\mathbb{R}}_+, \mathcal{S}(\overline{\mathbb{R}}_+))$, $s_j \in C^\tau S_{1,0}^{m-j,\nu}(\mathbb{R}^{d-1} \times \mathbb{R}^{d-1})$, $j = 0, \dots, r-1$, then the associated trace operator of order m and class r is defined as*

$$\begin{aligned} t(x', \mu, D_x)f &= \sum_{j=0}^{r-1} s_j(x', \mu, D_{x'}) \gamma_j f + t_0(x', \mu, D_x)f \\ t_0(x', \mu, D_x)f &= \mathcal{F}_{\xi' \mapsto x'}^{-1} \left[\int_0^\infty \tilde{t}_0(x', \xi', \mu, y_d) \dot{f}(\xi', y_d) dy_d \right], \end{aligned}$$

where $\dot{f}(\xi', x_d) = \mathcal{F}_{x' \mapsto \xi'}[f(\cdot, x_d)]$.

2. *If $\tilde{g}_0 \in C^\tau S_{1,0}^{m-1,\nu}(\mathbb{R}^d \times \overline{\mathbb{R}}_+, \mathcal{S}(\overline{\mathbb{R}}_+^2))$, $\tilde{k}_j \in C^\tau S_{1,0}^{m-j-1,\nu}(\mathbb{R}^d \times \overline{\mathbb{R}}_+, \mathcal{S}(\overline{\mathbb{R}}_+))$ for $j = 0, \dots, r-1$, then the associated singular Green operator of order m and class r is defined as*

$$\begin{aligned} g(x, \mu, D_x)f &= \sum_{j=0}^{r-1} k_j(x, \mu, D_x) \gamma_j f + g_0(x, \mu, D_x)f, \\ g_0(x, \mu, D_x)f &= \mathcal{F}_{\xi' \mapsto x'}^{-1} \left[\int_0^\infty \tilde{g}_0(x, \xi', \mu, x_d, y_d) \dot{f}(\xi', y_d) dy_d \right], \end{aligned}$$

where \dot{f} is as above and $k_j(x, \mu, D_x)$ denotes the Poisson operator with symbol-kernel $\tilde{k}_j(x, \xi', \mu, y_d)$ (in x -form).

Finally, the boundary symbol operators $t(x', \xi', \mu, D_d)$, $g(x, \xi', \mu, D_d)$ and the corresponding operators in R -form $t(D_x, x')$, $g(D_x, x)$ are defined in the same way as for the Poisson operator. Note that, if $t'(x', \mu, D_x)$ is a trace operator of class 0, then

$$(t(x', \mu, D_x)\varphi, \psi)_{\mathbb{R}^{d-1}} = (\varphi, k(D_x, x', \mu)\psi)_{\mathbb{R}_+^d}, \quad (5.14)$$

where $\tilde{k}(x', \xi', \mu, y_d) = \overline{\tilde{t}(x', \xi', \mu, y_d)}$ and $\varphi \in \mathcal{S}(\overline{\mathbb{R}}_+^d)$, $\psi \in \mathcal{S}(\mathbb{R}^{d-1})$. Hence trace operators can be considered as adjoints of Poisson operators plus a sum of usual trace

operators $s_j(x', \mu, D_{x'})\gamma_j$, cf. e.g. [37, Proposition 2.4.2]. Moreover, if $k(x, \mu, D_x)$ is a Poisson operator, then

$$(k(x, \mu, D_x)\psi, \varphi)_{\mathbb{R}_+^d} = (\psi, t(D_x, x, \mu)\varphi)_{\mathbb{R}^{d-1}}, \quad (5.15)$$

where $\tilde{t}(x, \xi', \mu, y_d) = \overline{\tilde{k}(x, \xi', y_d)}$ and $\varphi \in \mathcal{S}(\overline{\mathbb{R}_+^d})$, $\psi \in \mathcal{S}(\mathbb{R}^{d-1})$. Similarly, if $g_0(x', \mu, D_x)$ is a singular Green operator of class 0 in x -form, then

$$(g_0(x', \mu, D_x)\varphi, \psi)_{\mathbb{R}_+^d} = (\varphi, g_1(D_x, x', \mu)\psi)_{\mathbb{R}_+^d} \quad (5.16)$$

for all $\varphi, \psi \in \mathcal{S}(\overline{\mathbb{R}_+^d})$, where $\tilde{g}_1(x, \xi', \mu, y_d, z_d) = \overline{\tilde{g}_0(x, \xi', \mu, z_d, y_d)}$. We note that most of the time the symbol kernels $\tilde{k}(x, \xi', y_d), \tilde{t}_0(x, \xi', y_d), \tilde{g}_0(x, \xi', y_d, z_d)$ will be independent of x_d , which is denoted by x' instead of x in the symbol-kernel.

We refer to [37] and [9, Definition 5.2] for the definition of the (global) transmission condition for a pseudodifferential symbol $p \in S_{1,0}^m(\mathbb{R}^d \times \mathbb{R}^d)$ and a variant for $p \in C^\tau S_{1,0}^m(\mathbb{R}^d \times \mathbb{R}^d)$. We will not use this property *directly* since we will mainly deal with differential operators or with the mapping property $p(D_x, x)_+ : L^q(\Omega) \rightarrow W_q^2(\Omega)$ for $p \in C^\tau S_{1,0}^{-2}(\mathbb{R}^d \times \mathbb{R}^d)$, which holds without the transmission condition. For completeness we recall the general definition of a Green operator with non-smooth coefficients as in [9].

Definition 5.12 *A Green operator (in L -form) of order $m \in \mathbb{Z}$, class $r \in \mathbb{N}_0$, and regularity $\nu \in \mathbb{R}$ with coefficients in C^τ is defined as*

$$a(x, \mu, D_x) = \begin{pmatrix} p(x, \mu, D_x)_+ + g(x', \mu, D_x) & k(x', \mu, D_x) \\ t(x', \mu, D_x) & s(x', \mu, D_{x'}) \end{pmatrix},$$

where $k(x', \mu, D_x)$, $t(x', \mu, D_x)$, and $g(x', \mu, D_x)$ are Poisson, trace, and singular Green operators of order m , regularity ν , and class r , $p(x', \mu, D_x)_+ = r^+ p(x', \mu, D_x) e^+$, $p \in C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^d \times \overline{\mathbb{R}_+^d})$, is a truncated pseudodifferential operator satisfying the transmission condition in the sense of [9, Definition 5.2] and $s \in C^\tau S_{1,0}^{m-1,\nu}(\mathbb{R}^{d-1} \times \overline{\mathbb{R}_+^d})$.

In the following we will often restrict ourselves to parameter-independent symbols and operators. The corresponding symbol classes $C^\tau S_{1,0}^d(\mathbb{R}^{d-1} \times \mathbb{R}^{d-1}, \mathcal{K})$, $\mathcal{K} = \mathcal{S}(\overline{\mathbb{R}_+})$, $\mathcal{S}(\overline{\mathbb{R}_{++}^2})$, are defined as above with the restriction that the symbols are independent of μ and the symbol estimates hold for $\mu = 0$, cf. [9] for details.

Moreover, if \tilde{f} is a Poisson, trace, or singular Green symbol-kernel, then $|\tilde{f}|_k^{(m,\nu)}$, $k \in \mathbb{N}$, are the semi-norms (monotonically increasing in k) associated to (5.12), (5.13), resp., in the usual way, cf. Definitions 5.3 and 5.6. The semi-norms of parameter-independent symbols will be denoted by $|\tilde{f}|_k^{(m)}$.

Remarks 5.13 1. As in Remark 5.7, $|\tilde{f}|_k^{(m+\varepsilon,\nu)} \leq \langle \mu \rangle^{-\varepsilon} |\tilde{f}|_k^{(m,\nu)}$ for all $\varepsilon > 0$.

2. If \tilde{f} is a parameter-dependent Poisson or trace symbol-kernel of degree $m \leq -\frac{1}{2}$, regularity $\nu \geq 0$, then $\tilde{f}(\cdot, \mu)$, $\mu \geq 0$ fixed, is a parameter-independent symbol-kernel of the same degree with $|\tilde{f}(\cdot, \mu)|_k^{(m)} \leq |\tilde{f}|_k^{(m, \nu)}$ uniformly in $\mu > 0$. The same is true for parameter-dependent singular Green symbol-kernels of degree $m \leq -1$.

Remark 5.14 Let $a_j(x, \xi', D_d)$, $j = 1, 2$, be the boundary symbol operator of a Poisson, trace, singular Green operator, or a pseudodifferential operators with the transmission condition of order m_j (and class r_j) with coefficients in C^{τ_j} . As observed in [9, Remark 4.5], the composition $a_1(x, \xi', D_d)a_2(x', \xi', D_d) = a(x, \xi', D_d)$ of the boundary symbol operators is again a boundary symbol operator if the composition is well-defined and the coefficients of a_2 are independent of x_d . The boundary symbol operator of the composition is also denoted by $(a_1 \circ_d a_2)(x, \xi', D_d)$.

The following theorem summarizes some mapping properties of trace and singular Green operators in R -form, which will be used in the following.

THEOREM 5.15 *Let $1 < q < \infty$.*

1. *Let $t \in C^\tau S_{1,0}^m(\mathbb{R}^{d-1} \times \mathbb{R}^{d-1}, \mathcal{S}(\overline{\mathbb{R}}_+))$, $m \in \mathbb{R}$, be a trace operator of order d and class 0. Then $t(D_x, x')$ extend to a bounded operator*

$$t(D_x, x'): L^q(\mathbb{R}_+^d) \rightarrow B_{qq}^{-m-\frac{1}{q}}(\mathbb{R}^{d-1}).$$

2. *Let $g \in C^\tau S_{1,0}^{-m-1}(\mathbb{R}^{d-1} \times \mathbb{R}^d, \mathcal{S}(\overline{\mathbb{R}}_{++}^2))$, $m \in \mathbb{R}$, be a singular Green operator of order $-m$ and class 0. Then $g(D_x, x')$ extends to a bounded operator*

$$g(D_x, x'): L^q(\mathbb{R}_+^d) \rightarrow W_q^m(\mathbb{R}_+^d).$$

All operators depend continuously on the symbols with respect to the operator norm and the symbol semi-norms.

Proof: The theorem follows directly from [9, Theorem 4.8] and duality using (5.15)-(5.16). ■

The following lemma summarizes the results concerning composition of non-smooth pseudodifferential operators which we need in Section 5.6.

Lemma 5.16 *Let $1 < q < \infty$ and $d < r \leq \infty$ such that $q \leq r$ and let $d_1 \in \mathbb{N}_0$. Moreover, let $p_1(x, D_x) = \sum_{|\alpha| \leq d_1} a_\alpha(x) D_x^\alpha$ be a differential operator of order d_1 with coefficients $a_\alpha \in W_r^1(\mathbb{R}^d)$, $r > d$, for all $|\alpha| \leq d_1$ and let $t(x', D_x) = \sum_{|\alpha| \leq d_1-1} b_\alpha(x') \gamma_0 D_x^\alpha$ be a differential trace operator of order $d_1 - 1$, class d_1 , and with coefficients $b_\alpha \in W_r^{1-\frac{1}{r}}(\mathbb{R}^{d-1})$.*

1. Let $\tilde{g} \in C^\tau S_{1,0}^{-d_1-1}(\mathbb{R}^{d-1} \times \mathbb{R}^{d-1}, \mathcal{S}(\overline{\mathbb{R}}_{++}^2))$. Then

$$\begin{aligned} p_1(x, D_x)g(D_x, x') - (p_1|_{x_d=0} \circ_d g)(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow L^q(\mathbb{R}_+^d), \\ t(x', D_x)g(D_x, x') - (t \circ_d g)(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow B_{qq}^{1-\frac{1}{q}}(\mathbb{R}^{d-1}), \\ \gamma_0 g(D_x, x') - (\gamma_0 \circ_d g)(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow B_{qq}^{d_1-\frac{1}{q}}(\mathbb{R}^{d-1}) \end{aligned}$$

with operator norms bounded by $C(p_1)|g|_k^{(-d_1-1+\varepsilon)}$, $C(t)|g|_k^{(-d_1-1+\varepsilon)}$, resp., for some $\varepsilon, C > 0$, $k \in \mathbb{N}$. Moreover,

$$\begin{aligned} t(x', D_x)g(D_x, x') - (t \circ_d g)(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow L^q(\mathbb{R}^{d-1}), \\ \gamma_0 g(D_x, x') - (\gamma_0 \circ_d g)(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow L^q(\mathbb{R}^{d-1}) \end{aligned}$$

with operator norm bounded by $C(t)|g|_k^{(-d_1-\frac{1}{q}+\varepsilon)}$, $C|g|_k^{(-1-\frac{1}{q}+\varepsilon)}$, resp., for some $\varepsilon, C > 0$, $k \in \mathbb{N}$.

2. Let $p_2 \in C^\tau S_{1,0}^{-d_1}(\mathbb{R}^d \times \mathbb{R}^d)$. Then

$$p_1(x', D_x)p_2(D_x, x)_+ - (p_1 \cdot p_2)(D_x, x)_+ : L^q(\mathbb{R}_+^d) \rightarrow L^q(\mathbb{R}_+^d)$$

with operator-norms bounded by $C(p_1)|p_2|_k^{(-d_1+\varepsilon)}$ for some $\varepsilon, C > 0$, $k \in \mathbb{N}_0$. Moreover, if p_2 satisfies the (global) transmission condition, cf. [9, Definition 5.2], and $d_1 \geq 1$, then

$$\begin{aligned} t(x', D_x)p_2(D_x, x)_+ - (t \circ_d p_2|_{x_d=0})(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow B_{qq}^{1-\frac{1}{q}}(\mathbb{R}^{d-1}) \\ \gamma_0 p_2(D_x, x)_+ - (\gamma_0 \circ_d p_2|_{x_d=0})(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow B_{qq}^{d_1-\frac{1}{q}}(\mathbb{R}^{d-1}) \end{aligned}$$

with operator norms bounded by $C(t)|p_2|_k^{(-d_1+\varepsilon)}$ for some $\varepsilon, C(t) > 0$, $k \in \mathbb{N}$. Finally,

$$\begin{aligned} t(x', D_x)p_2(D_x, x)_+ - (t \circ_d p_2|_{x_d=0})(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow L^q(\mathbb{R}^{d-1}) \\ \gamma_0 p_2(D_x, x)_+ - (\gamma_0 \circ_d p_2|_{x_d=0})(D_x, x') &: L^q(\mathbb{R}_+^d) \rightarrow L^q(\mathbb{R}^{d-1}) \end{aligned}$$

with operator norms bounded by $C(t)|p_2|_k^{(-d_1+\frac{1}{q}+\varepsilon)}$, $C|p_2|_k^{(-\frac{1}{q}+\varepsilon)}$, resp.

Proof: First we consider the compositions with $p_1(x, D_x)$. Since $p_1(x, D_x) = \sum_{|\alpha| \leq d_1} a_\alpha(x) D_x^\alpha$ and $D_x^\alpha p_2(D_x, x) = OP(\xi^\alpha p_2(y, \xi))$ as well as

$$D_x^\alpha g(D_x, x') = OP'(OP_d(\xi^\alpha) \circ g(y', \xi', D_d)),$$

it suffices to consider the case $d_1 = 0$ and $p_1(x, D_x) = a(x)$. But, using the relations

$$\begin{aligned} (a(x)g(D_x, x)\varphi, \psi)_{\mathbb{R}_+^d} &= (\varphi, g_1(x, D_x)\bar{a}(x)\psi)_{\mathbb{R}_+^d}, \\ (a(x)p_2(D_x, x)_+\varphi, \psi)_{\mathbb{R}_+^d} &= (\varphi, \bar{p}_2(x, D_x)_+\bar{a}(x)\psi)_{\mathbb{R}_+^d} \end{aligned}$$

for all $\varphi, \psi \in \mathcal{S}(\overline{\mathbb{R}}_+^d)$, cf. (5.16), where $\overline{p_2}(x, \xi) = \overline{p_2(x, \xi)}$ and $\tilde{g}_1(x', \xi', x_d, y_d) = \overline{\tilde{g}(x', \xi', y_d, x_d)}$, the corresponding statements 1.-2. follow from [9, Theorem 3.6, Theorem 5.9] with the choice $0 < \theta < \min(1, 1 - \frac{d}{r})$, where $\bar{g}, \overline{p_2}$ are considered as symbols of order $-d_1 + \varepsilon$ for $0 < \varepsilon \leq \theta$.

Concerning the compositions with $t(x', D_x)$, one can reduce to the case $t(x', D_x) = a(x')\gamma_0$ and $d_1 = 1$ similarly as before. Therefore

$$\begin{aligned} t(x', D_x)g(D_x, x') &= a(x')\gamma_0g(D_x, x), \\ t(x', D_x)p_2(D_x, x')_+ &= a(x')\gamma_0p_2(D_x, x)_+, \end{aligned}$$

where $\gamma_0g(D_x, x)$ and $\gamma_0p_2(D_x, x)_+$ are trace operators of class 0, cf. Remark 5.14. Let $\tilde{t}(D_x, x)$ denote one of them and let $s = 1 - \frac{1}{q}$ if $q \geq 2$ and $s \in (1 - \frac{1}{q}, 1 - \frac{1}{r})$ if $q < 2$. Then

$$\langle D_{x'} \rangle^s a(x') \tilde{t}(D_x, x') = a(x') \langle D_{x'} \rangle^s \tilde{t}(D_x, x') + [\langle D_{x'} \rangle^s, a(x')] \tilde{t}(D_x, x'),$$

where $\langle D_{x'} \rangle^s \tilde{t}(D_x, x')$ is a trace operator of order $-\frac{1}{q}$ if $q \geq 2$ and order $s - 1$ if $q < 2$. Hence we can apply [9, Theorem 4.13] to the first term (again using (5.14)) and Lemma 5.5 together with Theorem 5.15 to the second term to prove the statements of the lemma with $B_{qq}^{1-\frac{1}{q}}(\mathbb{R}^{d-1})$ replaced by $H_q^s(\mathbb{R}^{d-1}) + B_{qq}^s(\mathbb{R}^{d-1})$. If $q \geq 2$, then $H_q^s(\mathbb{R}^{d-1}) = H_q^{1-\frac{1}{q}}(\mathbb{R}^{d-1}) \hookrightarrow B_{qq}^{1-\frac{1}{q}}(\mathbb{R}^{d-1})$, cf. e.g. [51, Section 2.3.3, Remark 4]. If $1 < q < 2$, then $s > 1 - \frac{1}{q}$ and we use that $H_q^s(\mathbb{R}^{d-1}) \hookrightarrow B_{qq}^{1-\frac{1}{q}}(\mathbb{R}^{d-1})$, cf. [51, Section 2.3.3, Remark 4] again. This finishes the proof. \blacksquare

Lemma 5.17 *Let $\tilde{t}_0 \in C^\tau S_{1,0}^m(\mathbb{R}^d \times \mathbb{R}^{d-1}, \mathcal{S}(\overline{\mathbb{R}}_+))$ for some $\tau > 0$, $m \in \mathbb{R}$. Then*

$$\text{OP}'(\tilde{t}_0(y, \xi', D_d) - \tilde{t}_0(y', 0, \xi', D_d)): L^q(\mathbb{R}_+^d) \rightarrow B_{qq}^{-m-\frac{1}{q}}(\mathbb{R}^{d-1})$$

with operator norm bounded by $C|t_0|_k^{(m-\varepsilon)}$ for some $\varepsilon > 0$.

Proof: Using (5.15) the result directly follows from [9, Theorem 4.11]. \blacksquare

Finally, we need the following simple lemma when dealing with coordinate transformations.

Lemma 5.18 *Let $\tilde{f}(\xi', \mu, x_d) \in C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^{d-1} \times \overline{\mathbb{R}}_+^d, \mathcal{S}(\overline{\mathbb{R}}_+))$, $m, \nu \in \mathbb{R}$, $\tau > 0$. Moreover, let $A(x') \in C^\tau(\mathbb{R}^{d-1})^{(d-1) \times (d-1)}$, $\tau > 0$, such that $A^{-1}(x') \in C^\tau(\mathbb{R}^{d-1})^{(d-1) \times (d-1)}$, $c \in C^\tau(\mathbb{R}^{d-1} \times \mathbb{R}^{d-1})$, $c(x') \geq c_0 > 0$. Then $\tilde{g}(x', \xi', \mu, x_d) := \tilde{f}(A(x')\xi', \mu, c(x')x_d) \in C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^{d-1} \times \overline{\mathbb{R}}_+^d, \mathcal{S}(\overline{\mathbb{R}}_+))$ and for every $k \in \mathbb{N}_0$ there is some $k' \in \mathbb{N}_0$ such that $|\tilde{g}|_k^{(m,\nu)} \leq C(\|A\|_{C^\tau}, \|A^{-1}\|_{C^\tau})|\tilde{f}|_{k'}^{(m,\nu)}$. The same statement is true if $\tilde{f} \in C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^{d-1} \times \overline{\mathbb{R}}_{++}^d, \mathcal{S}(\overline{\mathbb{R}}_{++}^2))$ is independent of x' and if we set*

$$\tilde{g}(x', \xi', \mu, x_d, y_d) := \tilde{f}(A(x')\xi', \mu, c(x')x_d, c(x')y_d).$$

Proof: The proof of the lemma is the same as the proof of [11, Lemma 5.5] just replacing $C^{0,1}$ -norms by C^τ -norms. \blacksquare

Finally, if $\tilde{k}, \tilde{t} \in S_{1,0}^{m,\nu}(\mathbb{R}^{d-1} \times \overline{\mathbb{R}}_+^d, \mathcal{S}(\overline{\mathbb{R}}_+))$ and $\tilde{g} \in C^\tau S_{1,0}^{m,\nu}(\mathbb{R}^{d-1} \times \overline{\mathbb{R}}_+^d, \mathcal{S}(\overline{\mathbb{R}}_{++}^2))$, then we define for $c > 0$ and $a \in \mathbb{C}, f \in \mathcal{S}(\overline{\mathbb{R}}_+)$

$$\begin{aligned} k(x', \xi', \mu, cD_d)a &:= \tilde{k}(x', \xi', \mu, c^{-1}x_d)a, \\ t(x', \xi', \mu, cD_d)f &:= c^{-1} \int_0^\infty \tilde{t}(x', \xi', \mu, c^{-1}y_d)f(y_d) dy_d, \\ g(x', \xi', \mu, cD_d)f &:= c^{-1} \int_0^\infty \tilde{g}(x', \xi', \mu, c^{-1}x_d, c^{-1}y_d)f(y_d) dy_d. \end{aligned}$$

These definitions are motivated by the relations

$$k(., cD_d) = \delta_{c^{-1}}k(., D_d), \quad t(., cD_d) = t(., D_d)\delta_c, \quad g(., cD_d) = \delta_{c^{-1}}g(., D_d)\delta_c,$$

where $\delta_r f(x_d) = f(rx_d)$ for $r > 0$, where we note that

$$\delta_{c^{-1}}p(D_{x_d})\delta_c = \text{OP}_d(p(c\xi_d))$$

for every suitable function $p: \mathbb{R} \rightarrow \mathbb{R}$. Because of the latter relation, the scaling $D_d \mapsto cD_d$ is consistent with composition of operators in the sense that $a_1(., cD_d)a_2(., cD_d) = (a_1 \circ_d a_2)(., cD_d)$ for any Poisson, trace, and singular Green operators a_j , $j = 1, 2$, such that the composition is well-defined. Finally, we note that the choice of the scaling above differs slightly from the one used in [11, Section 5.2].

5.3 The Model Operators of the Reduced Stokes Equations in \mathbb{R}_+^d with unit viscosity

In this section we summarize some results on the boundary symbol operator of the reduced Stokes equation in \mathbb{R}_+^d with unit viscosity as discussed in [11, Section 5].

In the following we use the relation $\lambda = e^{i\theta}\mu^2$ for $\mu > 0, \theta \in (-\delta, \delta)$ respectively $\lambda \in \Sigma_\delta$ for some $\delta \in (0, \pi)$ arbitrary but fixed. Most of the time we will write all symbol-kernels and boundary symbol operators in dependence of $\lambda \in \Sigma_\delta$ instead of μ having in mind that in the estimates for the symbol-kernel classes the latter relation for μ and λ is used.

First of all, let

$$a_{j,\lambda}^r(\xi', D_d) = \begin{pmatrix} \mu^2 e^{i\theta} + |\xi'|^2 + D_d^2 + k_j^r(\xi', D_d) & t_j^r(\xi', D_d) \\ & t_j'(\xi', D_d) \end{pmatrix},$$

$j = 0, 1$, $\theta \in (-\pi, \pi)$, be the model operator of the reduced Stokes equations, where

$$\begin{aligned} k_0^r(\xi', D_d)a &= e^{-[\xi']x_d} \begin{pmatrix} \frac{i\xi'}{[\xi']} \\ -1 \end{pmatrix} a, & k_1^r(\xi', D_d)a &= e^{-[\xi']x_d} \begin{pmatrix} i\xi' \\ -[\xi'] \end{pmatrix} a, \\ t_0^r(\xi', D_d)u &= i\xi'^T \partial_d u'(0), & t_1^r(\xi', D_d)u &= 2\partial_d u_d(0), \\ t'_0(\xi', D_d)u &= u(0), & t'_1(\xi', D_d)u &= \begin{pmatrix} i\xi' u_d(0) + \partial_d u'(0) \\ i\xi' \cdot u'(0) + \partial_d u_n(0) \end{pmatrix} \end{aligned}$$

for $a \in \mathbb{C}^d$ and $u \in \mathcal{S}(\overline{\mathbb{R}_+})^d$.

We note that these model operators are obtained by considering the reduced Stokes system (3.3)-(3.6) with unit viscosity $\nu(x) \equiv 1$ in $\Omega = \mathbb{R}_+^d$ and applying Fourier transformation in tangential direction $x' \in \mathbb{R}^{d-1}$. In that case either only the Dirichlet boundary condition (3.5) is considered, which corresponds to the case $j = 0$ above and the choice $\Gamma_1 = \partial\mathbb{R}_+^d$ and $\Gamma_2 = \emptyset$, or only the Neumann type boundary condition (3.6) is present, which is denoted by $j = 1$ above and is obtained by choosing $\Gamma_1 = \emptyset, \Gamma_2 = \partial\mathbb{R}_+^d$. Here P is replaced by $k_j^r(\xi', D_d)t_j(\xi', D_d)$ since (1.8)-(1.9) is in the case $\nu \equiv 1$ the weak formulation of the Laplace equation $\Delta p_1 = 0$ together with either Neumann ($j = 0$) or Dirichlet boundary condition ($j = 1$). Calculating the solution of (1.8)-(1.9) explicitly in this case $\Omega = \mathbb{R}_+^d, \nu \equiv 1$ after (partial) Fourier transformation, one obtains $k_j^r(\xi', D_d)t_j(\xi', D_d)u$ for given u .

Note that the definition of $t_0^r(\xi', D_d)$ and $k_0^r(\xi', D_d)$ differs from the definitions in [11], but the product $k_0^r(\xi', D_d)t_0^r(\xi', D_d)$ stays the same. – The present decomposition is more suitable for the following. Here $[\cdot]$ denotes a smooth function with $[\xi'] = |\xi'|$ if $|\xi'| \geq 1$ and $[\xi'] \geq \frac{1}{2}$ if $|\xi'| < 1$.

The following theorem summarizes the essential properties of the model operator shown in [11].

THEOREM 5.19 *Let $0 < \delta < \pi$ and let $\theta \in [-\delta, \delta]$. Then there is some $c_0 > 0$ such that*

$$a_{j,\lambda}^r(\xi', \mu, D_d) \equiv a_j^r(\xi', \mu, D_d): H_2^2(\mathbb{R}_+)^d \rightarrow L^2(\mathbb{R}_+)^d \times \mathbb{C}^d$$

is bijective for all $|(\xi', \mu)| \geq c_0$. Moreover, $a_j^r(\xi', \mu, D_d)^{-1}$ is a boundary symbol operator of order -2 , class 0, and regularity $\frac{1}{2}$. Finally,

$$a_j^r(\xi', \mu, D_d)^{-1} \begin{pmatrix} f \\ 0 \end{pmatrix} = p_\lambda(\xi', D_d)_+ f + g_{j,\lambda}^r(\xi', D_d) f \equiv r_{j,\lambda}^r(\xi', D_d) f$$

for $f \in \mathcal{S}(\overline{\mathbb{R}_+})^d$, where $\lambda = e^{i\theta}\mu^2$, $p_\lambda(\xi) = (\lambda + |\xi|^2)^{-1}$ and $g_{j,\lambda}^r(\xi', D_d)$ satisfies

$$\left\| \int_{\Gamma_R} h(-\lambda) D_{\xi'}^{\alpha'} g_{j,\lambda}^r(\xi', D_d) d\lambda \right\|_X \leq C_{\delta, \delta', \alpha'} \langle \xi' \rangle^{-|\alpha'|} \|h\|_\infty \quad (5.17)$$

for $X = \mathcal{L}(L^2(\mathbb{R}_+; x_d^{-\delta'}), H_2^{\delta'}(\mathbb{R}_+))$ and $X = \mathcal{L}(H_2^{-\delta'}(\mathbb{R}_+), L^2(\mathbb{R}_+; x_d^{\delta'}))$ uniformly in $\xi' \in \mathbb{R}^{d-1}$ for all $h \in H(\delta)$, $0 \leq \delta' < \frac{1}{2}$, $\alpha' \in \mathbb{N}_0^{d-1}$. Here $\Gamma_R = \Gamma \setminus B_R$ and $\Gamma = \partial\Sigma_\delta$ for some $R \geq R_0 := c_0^2$.

Proof: The first part is the content of [11, Lemma 5.1]. The validity of (5.17) follows from [11, Theorem 5.13]. More precisely, from [11, Theorem 5.13] we obtain that

$$\left\| \int_{\Gamma_R} h(-\lambda) D_{\xi'}^{\alpha'} \check{g}_{j,\lambda}^r(\xi', D_d) d\lambda \right\|_X \leq C_{\delta, \delta', \alpha'} \langle \xi' \rangle^{-|\alpha'|} \|h\|_\infty$$

for $X = \mathcal{L}(L^2(\mathbb{R}; |x_d|^{-\delta'}), H_2^{\delta'}(\mathbb{R}))$ and $X = \mathcal{L}(H_2^{-\delta'}(\mathbb{R}), L^2(\mathbb{R}; |x_d|^{\delta'}))$ uniformly in $\xi' \in \mathbb{R}^{d-1}$ for all $h \in H(\delta)$, $0 \leq \delta' < \frac{1}{2}$, $\alpha' \in \mathbb{N}_0^{d-1}$, where

$$\check{g}_{j,\lambda}^r(\xi', D_d) f := \int_{\mathbb{R}} \tilde{g}_{j,\lambda}^r(\xi', x_d, y_d) f(y_d) dy_d$$

for $f \in L^2(\mathbb{R}; |x_d|^{-\delta'}) \cup H_2^{-\delta'}(\mathbb{R})$ and $\tilde{g}_{j,\lambda}^r(\xi', x_d, y_d)$ is extended by zero for $x_d < 0$ or $y_d < 0$. Since $g_{j,\lambda}^r(\xi', D_d) = r_+ \check{g}_{j,\lambda}^r(\xi', D_d) e_+$ and $e_+ : H_2^{-\delta'}(\mathbb{R}_+) \rightarrow H_2^{-\delta'}(\mathbb{R})$ is continues for $0 \leq \delta' < \frac{1}{2}$, (5.17) follows. \blacksquare

Furthermore, we note that

$$\text{OP}_d(\lambda + |\xi|^2) g_{j,\lambda}^r(\xi', D_d) f = -k_j^r(\xi', D_d) t_j^r(\xi', D_d) r_{j,\lambda}^r(\xi', D_d) f \quad (5.18)$$

since $\text{OP}_d(\lambda + |\xi|^2) p_\lambda(\xi', D_d) f = f$.

5.4 The Model Operators of the Reduced Stokes Equations in \mathbb{R}_+^d with general viscosity

First of all, we note that, if (v, p) is a solution of the Stokes equation resolvent equation in \mathbb{R}_+^d for $\nu \equiv \text{const.} > 0$, then $(w(x), q(x)) = (v(\nu^{\frac{1}{2}}x), \nu^{-\frac{1}{2}}p(\nu^{\frac{1}{2}}x))$ is a solution of the Stokes equation with unit viscosity. This scaling is also valid on the level of the boundary symbol operators for the reduced Stokes system as follows: After partial Fourier transformation the reduced Stokes equation on \mathbb{R}_+^d with constant viscosity ν becomes

$$\begin{aligned} (\lambda + \nu|\xi'|^2 + \nu D_d^2) \tilde{u}(x_d) + k_j^r(\xi', D_d) \nu t_j^r(\xi', D_d) \tilde{u}(x_d) &= \tilde{f}(x_d), \quad x_d > 0, \\ \nu^{\frac{1}{2}} t_j'(\xi', D_d) \tilde{u} &= \tilde{a} \end{aligned}$$

provided that $|\xi'| \geq 1$ where k_j^r, t_j^r, t_j' are as in the previous section. Now we use that

$$\begin{aligned} k_j^r(\xi', D_d) \nu t_j^r(\xi', D_d) &= k_j^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) t_j^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d), \\ \nu^{\frac{1}{2}} t_j'(\xi', D_d) &= t_j'(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) \end{aligned}$$

Altogether we see that the boundary symbol operator of the reduced Stokes equation in \mathbb{R}_+^d with viscosity $\nu > 0$ is

$$a_{j,\lambda,\nu}^r(\xi', D_d) := \begin{pmatrix} I & 0 \\ 0 & \nu^{\frac{j}{2}} \end{pmatrix} a_{j,\lambda}^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d),$$

where $a_{j,\lambda}^r(\xi', D_d) \equiv a_j^r(\xi', \mu, D_d)$ is the boundary symbol operator of the reduced Stokes equation with unit viscosity as defined above and the factor $\nu^{\frac{j}{2}}$ only acts on the boundary data.

Finally, we note that there is some $\tilde{g}_{j,\lambda} \in C^\tau S_{1,0}^{-2,\frac{1}{2}}(\mathbb{R}^d \times \overline{\mathbb{R}^{d+1}})$ (independent of x) such that

$$\begin{aligned} \left(\frac{i\xi'}{\partial_d} \right) \nu^{\frac{1}{2}} g_{j,\lambda}(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) &\equiv k_j^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) t_j^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) r_{j,\lambda}^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) \\ &= -\text{OP}_d(\lambda + \nu|\xi|^2)_+ g_{j,\lambda}^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) \end{aligned} \quad (5.19)$$

because of (5.18). In particular, this implies

$$\begin{aligned} (-\partial_d)^{1-j} \nu^{\frac{1}{2}} g_{j,\lambda}(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) \Big|_{x_d=0} &= \nu^{\frac{j}{2}} t_j^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) r_{j,\lambda}^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) \\ &= \nu t_j^r(\xi', D_d) r_{j,\lambda}^r(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) \end{aligned} \quad (5.20)$$

and

$$(|\xi'|^2 - \partial_d^2) g_{j,\lambda}(\nu^{\frac{1}{2}} \xi', \nu^{\frac{1}{2}} D_d) = 0 \quad \text{in } (0, \infty). \quad (5.21)$$

5.5 Symbols of the Reduced Stokes Equations in \mathbb{R}_γ^d

As we have seen in Section 4 coordinate transformation acts on the principal symbol as

$$a(\xi) \rightsquigarrow \underline{a}(x', \xi) = a(A(x)\xi)$$

with an additional factor $U^T(x)$ on the left if the range of the operator consists of vector fields and additional factor $U(x)$ on the right if the domain of the operator consists of vector fields. Therefore we define the principal boundary symbol operator for the reduced Stokes equation \mathbb{R}_γ^d by

$$\underline{a}_{j,\lambda}^r(x', \xi', D_d) = U^T(x') \text{diag}(I, \underline{\nu}(x')^{j\frac{1}{2}}) a_{j,\lambda}^r(\underline{\nu}(x')^{\frac{1}{2}} A'(x') \xi', \underline{\nu}(x')^{\frac{1}{2}} D_d) U(x'),$$

where $\underline{\nu} = F^* \nu$ and $\underline{\nu}(x') = \underline{\nu}(x', 0)$. Hence

$$\begin{aligned} \underline{a}_{j,\lambda}^{r,-1}(x', \xi', D_d) &= U^T(x') a_{j,\lambda}^{r,-1}(\underline{\nu}(x')^{\frac{1}{2}} A'(x') \xi', \underline{\nu}(x')^{\frac{1}{2}} D_d) \text{diag}(1, \underline{\nu}(x')^{-\frac{j}{2}}) U(x'). \end{aligned} \quad (5.22)$$

This is the essential formula for the construction of the parametrix.

Moreover, we set

$$\underline{r}_{j,\lambda}^r(x', 0, \xi', D_d) f = \underline{a}_{j,\lambda}^{r,-1}(x', \xi', D_d) \begin{pmatrix} f \\ 0 \end{pmatrix}, \quad f \in \mathcal{S}(\overline{\mathbb{R}}_+).$$

Then

$$\underline{r}_{j,\lambda}^r(x', 0, \xi', D_d) f = \underline{p}_\lambda(x', 0, \xi', D_d)_+ f + \underline{g}_{j,\lambda}^r(x', \xi', D_d) f$$

where $\underline{p}_\lambda(x, \xi) = (\lambda + \underline{\nu}(x)|A(x)\xi|^2)^{-1}$ and

$$\underline{g}_{j,\lambda}^r(x', \xi', D_d)f = U(x')^T \underline{g}_{j,\lambda}^r(\underline{\nu}^{\frac{1}{2}}(x')A'(x')\xi', \underline{\nu}^{\frac{1}{2}}(x')D_d)U(x')f. \quad (5.23)$$

Finally, we set for $x = (x', x_d)$ with $x_d > 0$

$$\underline{r}_{j,\lambda}^r(x, \xi', D_d)f = \underline{p}_\lambda(x, \xi', D_d)_+ f + \underline{g}_{j,\lambda}^r(x', \xi', D_d)f$$

and we define the parametrix of the reduced Stokes system on the transformed \mathbb{R}_γ^d as

$$\underline{r}_{j,\lambda}^r(D_x, x) = \underline{p}_\lambda(D_x, x)_+ + \underline{g}_{j,\lambda}^r(D_x, x') \quad (5.24)$$

For the general construction of a parametrix in the case of non-smooth coefficients we refer to [9, Section 6].

Remark 5.20 We note that $p_\lambda(\xi) = (\lambda + |\xi|^2)^{-1}$ satisfies the transmission condition because of [37, Theorem 2.2.13] and since every polynomial in ξ satisfies the transmission condition. Therefore $\underline{p}_\lambda(x, \xi)$ satisfies the global transmission condition in the sense of [9, Definition 5.2] because of [9, Remark 5.3].

We have to estimate the semi-norms of the transformed symbols. Because of (4.1) and $\nabla'\gamma \in W_{r_2}^{1-\frac{1}{r_2}}(\mathbb{R}^{d-1}) \hookrightarrow C^{\tau_2}(\mathbb{R}^{d-1})$ with $\tau_2 = 1 - \frac{d}{r_2} > 0$, we have $A'(x')$, $A'^{-1}(x')$, $c(x') \in C^{\tau_2}(\mathbb{R}^{d-1})$. Moreover, $\underline{\nu}(x)|_{x_d=0} \in W_{r_1}^{1-\frac{1}{r_1}}(\mathbb{R}^{d-1}) \hookrightarrow C^{\tau_1}(\mathbb{R}^{d-1})$ with $\tau_1 = 1 - \frac{d}{r_1} > 0$. Hence we can apply Lemma 5.8 and Lemma 5.18 to obtain:

Corollary 5.21 *Let $\underline{a}_{j,\lambda}^r(x', \xi', D_d)$, $j = 0, 1$, be the transformed boundary symbol operators of the reduced Stokes equations defined above. Then $\underline{a}_j^r(x', \xi', \mu, D_d) \equiv \underline{a}_{j,\lambda}^r(x', \xi', D_d)$ and $\underline{r}_j^{r,-1}(x, \xi', \mu, D_d)$ are Green symbols of order 2, -2 , respectively, regularity $\frac{1}{2}$, and C^τ -smoothness in x' for $\tau = \min(1 - \frac{d}{r_1}, 1 - \frac{d}{r_2})$. Moreover, the semi-norms of the symbols are uniformly bounded in $\theta \in [-\delta, \delta]$ for any $\delta \in (0, \pi)$.*

THEOREM 5.22 *Let $\delta \in (0, \pi)$, $R_0 = c_0^2 > 0$ be the constant in Theorem 5.19, and $\underline{g}_{j,\lambda}^r(x', \xi', D_d)$ be defined as in (5.23) with $j = 0, 1$. Then*

$$\left\| \int_{\Gamma_R} h(-\lambda) \underline{g}_{j,\lambda}^r(D_x, x') d\lambda \right\|_{\mathcal{L}(L^q(\mathbb{R}_+^d))} \leq C_\delta \|h\|_\infty$$

for every $h \in H(\delta)$ and $R \geq \max\{R_0, 1\}$.

Proof: By (5.23) and (5.17), we obtain

$$\left\| \int_{\Gamma_R} h(-\lambda) D_{\xi'}^{\alpha'} \underline{g}_{j,\lambda}^r(\cdot, \xi', D_d) d\lambda \right\|_{C^\tau(X)} \leq C_{\delta, \delta', \alpha'} \langle \xi' \rangle^{-|\alpha'|} \|h\|_\infty$$

for $X = \mathcal{L}(L^2(\mathbb{R}_+; x_d^{-\delta'}), H_2^{\delta'}(\mathbb{R}_+))$ and $X = \mathcal{L}(H_2^{-\delta'}(\mathbb{R}_+), L^2(\mathbb{R}_+; x_d^{\delta'}))$ uniformly in $\xi' \in \mathbb{R}^{d-1}$ for all $h \in H(\delta)$, $0 \leq \delta' < \frac{1}{2}$, $\alpha' \in \mathbb{N}_0^{d-1}$. Hence Theorem 5.4 implies

$$\left\| \int_{\Gamma_R} h(-\lambda) \underline{g}_{j,\lambda}^r(D_x, x') d\lambda \right\|_{\mathcal{L}(L^q(\mathbb{R}^{d-1}; H_0), L^q(\mathbb{R}^{d-1}; H_1))} \leq C_\delta \|h\|_\infty$$

where $(H_0, H_1) = (L^2(\mathbb{R}_+; x_d^{-\delta'}), H_2^{\delta'}(\mathbb{R}_+))$ or $(H_0, H_1) = (H_2^{-\delta'}(\mathbb{R}_+), L^2(\mathbb{R}_+; x_d^{\delta'}))$. Now, if $1 < q \leq 2$, then one uses the interpolation inclusions

$$(L^2(\mathbb{R}_+, x_n^{\delta'}), L^2(\mathbb{R}_+, x_n^\delta))_{\theta, q} \subseteq L^q(\mathbb{R}_+), \quad (H_2^{-\delta'}(\mathbb{R}_+), H_2^{-\delta}(\mathbb{R}_+))_{\theta, q} \supseteq L^q(\mathbb{R}_+),$$

where $0 \leq \delta' < \frac{1}{q} - \frac{1}{2} < \delta < \frac{1}{2}$, $\theta = (\frac{1}{q} - \frac{1}{2} - \delta')/(\delta - \delta')$, cf. e.g. [11, Lemma 2.1], and $(\cdot, \cdot)_{\theta, q}$ denotes the real interpolation functor. This implies the statement in this case. If $2 \leq q < \infty$, then one uses instead

$$(L^2(\mathbb{R}_+, x_n^{-\delta'}), L^2(\mathbb{R}_+, x_n^{-\delta}))_{\theta, q} \supseteq L^q(\mathbb{R}_+), \quad (H_2^{\delta'}(\mathbb{R}_+), H_2^\delta(\mathbb{R}_+))_{\theta, q} \subseteq L^q(\mathbb{R}_+),$$

where $0 \leq \delta' < \frac{1}{2} - \frac{1}{q} < \delta < \frac{1}{2}$, and $\theta = (\frac{1}{2} - \frac{1}{q} - \delta')/(\delta - \delta')$, cf. e.g. [11, Lemma 2.1] again. This finishes the proof. \blacksquare

For the pseudodifferential operator part $\underline{p}_\lambda(x, D_x)$ we can apply:

Lemma 5.23 *Let $1 < q < \infty$, $R > 0$, and $\delta \in (0, \pi)$. Then $\underline{p}_\lambda(x, \xi) = (\lambda + \underline{\nu}(x)|A(x)\xi|^2)^{-1}$, $x \in \mathbb{R}^d$, $\xi \in \mathbb{R}$, with $A, A^{-1} \in C^\tau(\mathbb{R}^d)^{d \times d}$, $\underline{\nu}, \underline{\nu}^{-1} \in C^\tau(\mathbb{R}^d)$ satisfies*

$$\left\| \int_{\Gamma_R} h(-\lambda) D_\xi^\alpha \underline{p}_\lambda(\cdot, \xi) d\lambda \right\|_{C^\tau} \leq C_{\delta, R, \alpha} \|h\|_\infty \langle \xi \rangle^{-|\alpha|}$$

uniformly in $\xi \in \mathbb{R}^d$, for all $\alpha \in \mathbb{N}_0^d$ and $h \in H(\delta)$.

Proof: The proof is literally the same as in [11, Lemma 5.14] just replacing $C^{0,1}$ -norms by C^τ -norms. \blacksquare

Now we are in the position to prove the following main step in the proof of Theorem 5.1:

THEOREM 5.24 *Let $1 < q < \infty$, $a \in C^\tau(\mathbb{R}^d)$ with $\tau > 0$, $0 < \delta < \pi$, $\lambda \in \Sigma_\delta$, and let $\underline{r}_{j,\lambda}^r(D_x, x)$ be as above. Then $\underline{r}_{j,\lambda}^r(D_x, x)$ extends to a bounded operator $\underline{r}_{j,\lambda}^r(D_x, x): L^q(\mathbb{R}_+^d)^d \rightarrow W_q^2(\mathbb{R}_+^d)^d$ and*

$$(\lambda - \underline{\nu}\Delta)\underline{r}_{j,\lambda}^r(D_x, x)f + \nabla \underline{g}_{j,\lambda}(D_x, x')f = f + S_{j,\lambda}f \quad \text{in } \mathbb{R}_+^d, \quad (5.25)$$

$$\underline{t}'_j(x', D_x)\underline{r}_{j,\lambda}^r(D_x, x)f = S'_{j,\lambda}f \quad \text{on } \partial\mathbb{R}_+^d \quad (5.26)$$

for every $f \in L^q(\mathbb{R}_+^d)^d$ where $\underline{g}_{j,\lambda}(D_x, x')$ is a singular Green operator of order -1 , class 0, and regularity $\frac{1}{2}$. Moreover,

$$\begin{aligned} & \left(\underline{\nabla} \underline{g}_{j,\lambda}(D_x, x') f, a \underline{\nabla} \varphi \right)_{\mathbb{R}_+^d} \\ &= (\nu(\underline{\Delta} - \underline{\nabla} \operatorname{div}) \underline{r}_{j,\lambda}^r(D_x, x) f, a \underline{\nabla} \varphi)_{\mathbb{R}_+^d} + \langle S_{j,\lambda}'' f, \varphi \rangle_{W_{q,0}^{-1}, W_q^1} \end{aligned} \quad (5.27)$$

for all $\varphi \in W_q^1(\mathbb{R}_+^d)$ with $\varphi|_{x_d=0} = 0$ if $j = 1$,

$$\underline{g}_{1,\lambda}(D_x, x') f|_{\partial \mathbb{R}_+^d} = \underline{r}_1^r(x', D_x) \underline{r}_{1,\lambda}^r(D_x, x) f + S_\lambda''' f \quad \text{on } \partial \mathbb{R}_+^d, \quad (5.28)$$

and

$$\|S_{j,\lambda} f\|_{L^q(\mathbb{R}_+^d)} + \|S_{j,\lambda}' f\|_{W_q^{2-j-\frac{1}{q}}(\mathbb{R}^{d-1})} \leq C_{q,\delta} \langle \lambda \rangle^{-\varepsilon} \|f\|_{L^q(\mathbb{R}_+^d)}, \quad (5.29)$$

$$\|S_{j,\lambda}'' f\|_{W_{q,0}^{-1}(\mathbb{R}_+^d)} + \|S_\lambda''' f\|_{W_q^{1-\frac{1}{q}}(\mathbb{R}^{d-1})} \leq C_{q,\delta} \langle \lambda \rangle^{-\varepsilon} \|f\|_{L^q(\mathbb{R}_+^d)}, \quad (5.30)$$

$$\langle \lambda \rangle^{\frac{1}{2}(2-j-\frac{1}{q})} \|S_{j,\lambda}' f\|_{L^q(\mathbb{R}^{d-1})} \leq C_{q,\delta} \langle \lambda \rangle^{-\varepsilon} \|f\|_{L^q(\mathbb{R}_+^d)} \quad (5.31)$$

uniformly in $\lambda \in \Sigma_\delta$, $f \in L^q(\mathbb{R}_+^d)^d$ for some $\varepsilon > 0$. Finally,

$$\langle \lambda \rangle \|\underline{r}_{j,\lambda}^r(D_x, x)\|_{\mathcal{L}(L^q(\mathbb{R}_+^d))} + \|\nabla^2 \underline{r}_{j,\lambda}^r(D_x, x)\|_{\mathcal{L}(L^q(\mathbb{R}_+^d))} \leq C_{q,\delta}, \quad (5.32)$$

$$\langle \lambda \rangle^{\frac{1}{2}} \|\underline{g}_{j,\lambda}^r(D_x, x')\|_{\mathcal{L}(L^q(\mathbb{R}_+^d))} + \|\nabla \underline{g}_{j,\lambda}^r(D_x, x')\|_{\mathcal{L}(L^q(\mathbb{R}_+^d))} \leq C_{q,\delta} \quad (5.33)$$

uniformly in $\lambda \in \Sigma_\delta$, $|\lambda| \geq R_0$, where R_0 is as in Theorem 5.19.

Proof: First of all, because of Corollary 5.21, Theorem 5.4, Theorem 5.15.2, and Remarks 5.7 and 5.13,

$$\underline{r}_{j,\lambda}^r(D_x, x): L^q(\mathbb{R}_+^d)^d \rightarrow W_q^2(\mathbb{R}_+^d)^d$$

with operator norm uniformly bounded in $\lambda \in \Sigma_\delta$, $|\lambda| \geq R_0$, $\delta \in (0, \pi)$. Considering $\underline{p}_\lambda(x, \xi)$, $\tilde{g}_{j,\lambda}^r(x', \xi', x_n, y_n)$ as symbol(-kernels) of order 0 with symbol seminorms bounded by $C_\delta(1 + |\lambda|)^{-1}$, cf. Remark 5.7 and Remark 5.13.1, we conclude $\|R_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_+^d))} \leq C_\delta(1 + |\lambda|)^{-1}$. Hence (5.32) holds.

In order to show (5.25), we calculate

$$\begin{aligned} & (\lambda - \nu \underline{\Delta} \underline{r}_{j,\lambda}^r(D_x, x) f = (\lambda - \nu \underline{\Delta}) \underline{p}_\lambda(D_x, x) f + (\lambda - \nu \underline{\Delta}) \underline{g}_{j,\lambda}^r(D_x, x') f \\ &= \operatorname{OP}(\underline{q}_\lambda(y, \xi) \underline{p}_\lambda(y, \xi)) + \operatorname{OP}'(\operatorname{OP}_d(\underline{q}_\lambda(y', 0, \xi)) + \underline{g}_{j,\lambda}^r(y', \xi', D_d)) + \tilde{S}_{j,\lambda} f \\ &= f + \operatorname{OP}'(\underline{q}_\lambda(y', 0, \xi', D_d) + \underline{g}_{j,\lambda}^r(y', \xi', D_d)) f + \tilde{S}_{j,\lambda} f \end{aligned}$$

where $\underline{q}_\lambda(x, \xi) = \lambda + \nu(x)|A(x)\xi|^2$ and

$$\|\tilde{S}_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_+^d))} \leq C \left(\left| \underline{p}_\lambda \right|_k^{(-2+\varepsilon)} + \left| \underline{g}_{j,\lambda}^r \right|_k^{(-3+\varepsilon)} \right) \leq C \langle \lambda \rangle^{-\frac{\varepsilon}{2}} \left(\left| \underline{p}_\lambda \right|_k^{(-2,0)} + \left| \underline{g}_{j,\lambda}^r \right|_k^{(-3,0)} \right)$$

uniformly in $\lambda \in \Sigma_\delta$, $|\lambda| \geq R_0$, for some $\varepsilon > 0$ and $k \in \mathbb{N}$ because of Lemma 5.16 with $d_1 = 2$, Remark 5.7, and Remark 5.13.1. Next

$$\underline{q}_\lambda(y', \xi', D_d) + \underline{g}_{j,\lambda}^r(y', \xi', D_d) = -U(y')^T \left(\frac{A'(y')\xi'}{\partial_d} \right) \underline{g}_{j,\lambda}(y', \xi', D_d),$$

where

$$\underline{g}_{j,\lambda}(y', \xi', D_d) = \underline{\nu}^{\frac{1}{2}}(y') g_{j,\lambda}(\underline{\nu}^{\frac{1}{2}}(y') A'(y') \xi', \underline{\nu}^{\frac{1}{2}}(y') D_d) U(y') \quad (5.34)$$

and $g_{j,\lambda}(\xi', D_d)$ is as in (5.19). Hence

$$\text{OP}' \left(\underline{q}_\lambda(y', \xi', D_d) + \underline{g}_{j,\lambda}^r(y', \xi', D_d) \right) f = -\underline{\nabla} \underline{g}_{j,\lambda}(D_x, x') f + \tilde{S}'_{j,\lambda} f,$$

where $\|\tilde{S}'_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_+^d))} \leq C\langle \lambda \rangle^{-\varepsilon}$ uniformly in $\lambda \in \Sigma_\delta$, $|\lambda| \geq R_0$ for some $\varepsilon > 0$ because of Lemma 5.16 and Remark 5.13 as before. Thus (5.25) holds true with $S_{j,\lambda} = \tilde{S}_{j,\lambda} + \tilde{S}'_{j,\lambda}$.

Since $\underline{g}_{j,\lambda}(D_x, x')$ is a parameter-dependent singular Green operator of order -1 , class 0, and regularity $\frac{1}{2}$, we obtain (5.33) by the same arguments as for (5.32). In order to prove (5.27), we derive for all $\varphi \in W_q^1(\mathbb{R}_+^d)$ with $\varphi|_{x_d=0} = 0$ if $j = 1$ that

$$\begin{aligned} (\underline{\nabla} \underline{g}_{j,\lambda}(D_x, x') f, a \underline{\nabla} \varphi)_{\mathbb{R}_+^d} &= \left(a A^T A \text{OP}(i\xi \underline{g}_{j,\lambda}(\xi, y')) f, \nabla \varphi \right)_{\mathbb{R}_+^d} \\ &= \left(\text{OP}'(a(y') A(y')^T A(y') \text{OP}_d(i\xi) \underline{g}_{j,\lambda}(\xi', y', D_d)) f, \nabla \varphi \right)_{\mathbb{R}_+^d} + (\tilde{S}_{j,\lambda} f, \nabla \varphi)_{\mathbb{R}_+^d} \\ &= - \left(\text{OP}'(a(y') \partial_d \underline{g}_{j,\lambda}(\xi', y', D_d)) f|_{x_d=0}, \varphi|_{x_d=0} \right)_{\mathbb{R}^{d-1}} \\ &\quad - \left(\text{div OP}'(a(y') A(y')^T A(y') \text{OP}_d(i\xi) \underline{g}_{j,\lambda}(\xi', y', D_d)) f, \varphi \right)_{\mathbb{R}_+^d} + (\tilde{S}_{j,\lambda} f, \nabla \varphi)_{\mathbb{R}_+^d} \end{aligned}$$

where $\|\tilde{S}_{j,\lambda} f\|_{L^q(\mathbb{R}_+^d)} \leq C\langle \lambda \rangle^{-\varepsilon} \|f\|_{L^q(\mathbb{R}_+^d)}$ for some $\varepsilon > 0$ because of Lemma 5.16 with $d_1 = 0$. Moreover,

$$\begin{aligned} & - \text{div OP}'(a(y') A(y')^T A(y') \text{OP}_d(i\xi) \underline{g}_{j,\lambda}(\xi', y', D_d)) f \\ &= \text{OP}'(a(y') (|A'(y') \xi'|^2 - \partial_d^2) \underline{g}_{j,\lambda}(\xi', y', D_d)) = 0 \end{aligned}$$

due to (5.21) and (5.34). Furthermore, if $j = 0$, then

$$\begin{aligned} & \text{OP}'(a(y') \partial_d \underline{g}_{0,\lambda}(\xi', y', D_d)) f|_{x_d=0} \\ &= \text{OP}'(a(y') \underline{t}_{0,\lambda}'(\xi', y', D_d) \underline{r}_{0,\lambda}'(\xi', y', D_d)) f \\ &= e_d \cdot \gamma_0 \text{OP}(a(y) (|A(y) \xi|^2 - (A(y) \xi)(A(y) \xi)^T) \underline{p}_\lambda(\xi', y) U(y))_+ f + S'_{0,\lambda} f \\ &\quad + e_d \cdot \gamma_0 \text{OP}'(a(y') \text{OP}_d(|A(y') \xi|^2 - (A(y') \xi)(A(y') \xi)^T) U(y') \underline{g}_{0,\lambda}^r(\xi', y', D_d)) f \end{aligned}$$

due to (5.20) and (5.34), where

$$\begin{aligned} \text{OP}'(t(y, \xi', D_d)) f &\equiv e_d \cdot \gamma_0 \text{OP}(a(y) (|A(y) \xi|^2 - (A(y) \xi) A(y) \xi^T) \underline{p}_\lambda(\xi, y) U(y))_+ f \\ &= \text{OP}'(t(y', 0, \xi', D_d)) f + S'_{j,\lambda} f. \end{aligned}$$

Here $\text{OP}'(t(y, \xi', D_d))$ is a trace operator of order 0 and class 0 since $e_d \cdot (|A(y)\xi|^2 - (A(y)\xi)A(y)\xi^T)p_\lambda(\xi, y) = O(\langle \xi_d \rangle^{-1})$ w.r.t. ξ_d , cf. [37, Proposition 2.2.2]. Therefore Lemma 5.17 implies $\|S'_{j,\lambda}f\|_{B_{q,q}^{-\frac{1}{q}}(\mathbb{R}^{d-1})} \leq C\langle \lambda \rangle^{-\varepsilon}\|f\|_{L^q(\mathbb{R}_+^d)}$ for some $\varepsilon > 0$. Finally,

$$\begin{aligned} & \left(e_d \cdot \gamma_0 \text{OP}(a(y)(|A(y)\xi|^2 - (A(y)\xi)(A(y)\xi)^T U(y))p_\lambda(\xi', y))_+ f, \varphi|_{x_d=0} \right)_{\mathbb{R}^{d-1}} \\ &= - \left(\text{OP}(a(y)(|A(y)\xi|^2 - (A(y)\xi)(A(y)\xi)^T U(y))p_\lambda(\xi', y))_+ f, \nabla \varphi \right)_{\mathbb{R}_+^d} \\ &= - \left(a(\underline{\Delta} - \underline{\nabla} \text{div})p_\lambda(D_x, x)f, \underline{\nabla} \varphi \right)_{\mathbb{R}_+^d} + (\tilde{S}''_{j,\lambda}f, \nabla \varphi)_{\mathbb{R}_+^d} \end{aligned}$$

and

$$\begin{aligned} & \left(e_d \cdot \gamma_0 \text{OP}'(a(y') \text{OP}_d(|A(y')\xi|^2 - (A(y')\xi)(A(y')\xi)^T U(y'))g_{j,\lambda}^r(\xi', y', D_d))f, \varphi|_{x_d=0} \right)_{\mathbb{R}^{d-1}} \\ &= - \left(\text{OP}'(a(y') \text{OP}_d(|A(y')\xi|^2 - (A(y')\xi)(A(y')\xi)^T U(y'))g_{j,\lambda}^r(\xi', y', D_d))f, \nabla \varphi \right)_{\mathbb{R}_+^d} \\ &= - \left(a(\underline{\Delta} - \underline{\nabla} \text{div})g_{j,\lambda}^r(D_x, x')f, \underline{\nabla} \varphi \right)_{\mathbb{R}_+^d} + (\hat{S}''_{j,\lambda}f, \nabla \varphi)_{\mathbb{R}_+^d} \end{aligned}$$

since

$$\begin{aligned} & \text{div OP}(a(y)(|A(y)\xi|^2 - (A(y)\xi)(A(y)\xi)^T U(y))p_\lambda(\xi', y)) \\ &= \text{OP}(a(y)i\xi \cdot (|A(y)\xi|^2 - (A(y)\xi)(A(y)\xi)^T U(y))p_\lambda(\xi', y)) = 0 \quad \text{and} \\ & \text{div OP}'(a(y') \text{OP}_d(|A(y')\xi|^2 - (A(y')\xi)(A(y')\xi)^T U(y'))g_{j,\lambda}^r(\xi', y', D_d)) \\ &= \text{OP}'(a(y') \text{OP}_d(i\xi \cdot (|A(y')\xi|^2 - (A(y')\xi)(A(y')\xi)^T U(y'))g_{j,\lambda}^r(\xi', y', D_d)) = 0. \end{aligned}$$

Here $\|S''_{j,\lambda}f\|_{L^q(\mathbb{R}_+^d)} \leq C\langle \lambda \rangle^{-\varepsilon}\|f\|_{L^q(\mathbb{R}_+^d)}$ because of Lemma 5.16 and Remark 5.13 again. Furthermore, if $j = 1$,

$$\begin{aligned} & \underline{g}_{1,\lambda}^r(D_x, x')|_{x_d=0} = \text{OP}'(\underline{t}_1^r(y', \xi', D_d)\underline{r}_{j,\lambda}^r(y', \xi', D_d)) \\ &= \text{OP}'\left(\underline{t}_1^r(y', \xi', D_d)\underline{p}_\lambda(y', 0, \xi', D_d)_+\right) + \text{OP}'\left(\underline{t}_1^r(y', \xi', D_d)\underline{g}_{j,\lambda}^r(y', \xi', D_d)\right) \\ &= \underline{t}_1^r(x', D_x)(p_\lambda(D_x, x)_+ + g_{1,\lambda}^r(D_x, x')) + S_\lambda''' \end{aligned}$$

due to (5.20), where S_λ''' satisfies (5.30) because of Lemma 5.16 and Remark 5.13 again.

Finally,

$$\begin{aligned} & \gamma_0 \underline{r}_{0,\lambda}^r(D_x, x) = \text{OP}'(\gamma_0 \underline{r}_{1,\lambda}^r(y', \xi', D_d)) + S'_{0,\lambda} = S'_{0,\lambda} \\ & \underline{t}'_1(x', D_x)\underline{r}_{1,\lambda}^r(D_x, x) = \text{OP}'(\underline{t}'_1(y', \xi', D_d)\underline{r}_{1,\lambda}^r(y', \xi', D_d)) + S'_{1,\lambda} = S'_{1,\lambda} \end{aligned}$$

where $S'_{j,\lambda}$ satisfies the estimate in (5.29) because of Lemma 5.16 and Remark 5.13 once more. Using the $L^q(\mathbb{R}^{d-1})$ -estimates stated in Lemma 5.16, one derives (5.31), where we note that

$$\left| \underline{p}_\lambda \right|_k^{(-j-\frac{1}{q}+\varepsilon)} + \left| \underline{g}_{j,\lambda}^r \right|_k^{(-1-j-\frac{1}{q}+\varepsilon)} \leq C(1+|\lambda|)^{-\frac{1}{2}(2-j+\frac{1}{q}+\varepsilon)} \left(\left| \underline{q} \right|_k^{(-2,0)} + \left| \underline{g}_j^r \right|_k^{(-3,0)} \right).$$

This finishes the proof. ■

5.6 Proof of Theorem 5.1

Let \mathbb{R}_γ^d be a bent half-space as in the assumptions of Theorem 5.1. Then we define

$$R_{j,\lambda} := R'_{j,\lambda} - E_j T'_j R'_{j,\lambda}, \quad \text{where} \quad R'_{j,\lambda} := F^{*, -1} \text{OP}'(\underline{r}_{j,\lambda}^r(\underline{y}, \underline{\xi}', D_d)) F^*$$

as parametrix for the reduced Stokes equations in \mathbb{R}_γ^d , where $\underline{r}_{j,\lambda}^r$ is defined in (5.24) (extended for $|\lambda| \leq R_0$ suitably) and E_j is the extension operator due to Lemma 4.7. Then (5.2)-(5.3) hold. Because of (5.32) and Corollary 4.3, $R'_{j,\lambda}: L^q(\mathbb{R}_\gamma^d)^d \rightarrow W_q^2(\mathbb{R}_\gamma^d)^d$ with operator norm uniformly bounded in $\lambda \in \Sigma_\delta \cup \{0\}$ for every $\delta \in (0, \pi)$ and $\|R'_{j,\lambda}\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d))} \leq C_\delta(1 + |\lambda|)^{-1}$, $\lambda \in \Sigma_\delta$. Therefore Lemma 4.7, (5.26), (5.29), (5.30), and Lemma 4.6 imply

$$\langle \lambda \rangle \|E_j T'_j R'_{j,\lambda} f\|_{L^q(\mathbb{R}_\gamma^d)} + \|\nabla^2 E_j T'_j R'_{j,\lambda} f\|_{L^q(\mathbb{R}_\gamma^d)} \leq C \langle \lambda \rangle^{-\varepsilon} \|f\|_{L^q(\mathbb{R}_\gamma^d)}. \quad (5.35)$$

Hence (5.8) holds. Moreover, because of Theorem 5.22 and Lemma 5.23 together with Theorem 5.4, (5.10) holds, where we note that

$$\left\| \int_{\Gamma_R} h(-\lambda) E_j T'_j R'_{j,\lambda} d\lambda \right\|_{\mathcal{L}(L^q(\mathbb{R}_\gamma^d))} \leq C_\delta \|h\|_\infty \quad \text{for all } h \in H(\delta)$$

since $\|E_j T'_j R'_{j,\lambda} f\|_{L^q(\mathbb{R}_\gamma^d)} \leq C \langle \lambda \rangle^{-1-\varepsilon} \|f\|_{L^q(\mathbb{R}_\gamma^d)}$ for some $\varepsilon > 0$.

Due to Lemma 4.6 and (5.8),

$$(\lambda - \text{div}(\nu \nabla \cdot)) R_{j,\lambda} = F^{*, -1} \underline{q}_\lambda(x, D_x) \text{OP}'(\underline{r}_{j,\lambda}^r(y, \xi', D_d)) F^* + \tilde{S}'_\lambda$$

where $\underline{q}_\lambda(x, \xi) = \lambda + \underline{\nu}(x)|A(x)\xi|^2$ and $\tilde{S}'_\lambda = O((1 + |\lambda|)^{-\varepsilon})$ in $\mathcal{L}(L^q(\mathbb{R}_\gamma^d))$. Because of (5.25) and Lemma 4.6 again, we conclude further that

$$\begin{aligned} (\lambda - \text{div}(\nu \nabla \cdot)) R'_{j,\lambda} &= I - F^{*, -1} \underline{\nabla} \underline{g}_{j,\lambda}(D_x, x') F^* + \tilde{S}_\lambda \\ &= I - \nabla G_{j,\lambda} + \tilde{S}_\lambda \end{aligned}$$

for some $\tilde{S}_\lambda = O((1 + |\lambda|)^{-\varepsilon})$ in $\mathcal{L}(L^q(\mathbb{R}_\gamma^d))$ where $G_{j,\lambda} = F^{*, -1} \underline{g}_{j,\lambda}(D_x, x') F^*$. Combining this with (5.35), we obtain (5.1) together with the estimate of $S_{j,\lambda}$.

It remains to show (5.4)-(5.5). Using Lemma 4.6 and (5.27) with $a = \det \nabla F(x)$, we obtain

$$\begin{aligned} (\nabla G_{j,\lambda} f, \nabla \varphi)_{\mathbb{R}_\gamma^d} &= (\underline{\nabla} \underline{g}_{j,\lambda}(D_x, x') F^* f, \det \nabla F(x) \underline{\nabla} F^* \varphi)_{\mathbb{R}_+^d} \\ &= (\underline{\nu}(\underline{\Delta} - \underline{\nabla} \text{div}) \underline{r}_{j,\lambda}(D_x, x) F^* f, a \underline{\nabla} F^* \varphi)_{\mathbb{R}_+^d} + \langle S''_{j,\lambda} F^* f, F^* \varphi \rangle_{W_{q,0}^{-1}, W_{q'}^1} \\ &= (\nu(\Delta - \nabla \text{div}) R_{j,\lambda} f, \varphi)_{\mathbb{R}_\gamma^d} + (\underline{\nu} R_{1j,\lambda}(D_x, x) F^* f, a \underline{\nabla} F^* \varphi)_{\mathbb{R}_+^d} + \langle S'_{j,\lambda} F^* f, F^* \varphi \rangle \\ &\equiv (\nu(\Delta - \nabla \text{div}) R_{j,\lambda} f, \varphi)_{\mathbb{R}_\gamma^d} + \langle S'_{j,\lambda} f, \varphi \rangle_{W_{q,0}^{-1}, W_{q'}^1} \end{aligned}$$

for all $\varphi \in W_{q'}^1(\mathbb{R}_\gamma^d)$ with $\varphi|_{\partial\mathbb{R}_\gamma^d} = 0$ if $j = 0$, where R_1 is a differential operator of order 1 with L^{r_2} -coefficients, $r_2 > d$. Hence

$$\begin{aligned} \left| (\nu R_1 \underline{r}_{j,\lambda}(D_x, x) F^* f, a \nabla F^* \varphi)_{\mathbb{R}_+^d} \right| &\leq C \|\underline{r}_{j,\lambda}(D_x, x) F^* f\|_{W_s^1} \|\nabla \varphi\|_{L^{q'}} \\ &\leq C \|\underline{r}_{j,\lambda}(D_x, x) F^* f\|_{W_q^{2-2\varepsilon}} \|\nabla \varphi\|_{L^{q'}} \leq C(1 + |\lambda|)^{-\varepsilon} \|f\|_{L^q} \|\nabla \varphi\|_{L^{q'}} \end{aligned}$$

for all $f \in L^q(\mathbb{R}_\gamma^d)$, $\varphi \in \dot{W}_{q'}^1(\mathbb{R}_\gamma^d)$, and some $\varepsilon > 0$, where $\frac{1}{s} = \frac{1}{q} - \frac{1}{r_2} > \frac{1}{q} - \frac{1}{d}$. Combining this with (5.30), we have shown the estimates of $S'_{j,\lambda}$ stated in (5.6)-(5.7). The identity (5.5) and the estimate of S''_λ follows easily from (5.28), (5.30), and Lemma 4.6 again. This finishes the proof of Theorem 5.1.

6 Estimates of the Parametrix

Now we define the parametrix R_λ on Ω by

$$R_\lambda f = \sum_{k=1}^N \psi_k R_{\gamma_k, \lambda} \varphi_k f,$$

where $R_{\gamma_k, \lambda}$ denotes the approximate resolvent on $\mathbb{R}_{\gamma_k}^d$ according to Theorem 5.1, where the boundary conditions ($j = 0, 1$) are chosen to fit to the boundary conditions on $\partial\Omega \cap U_k$. Moreover, we order $\mathbb{R}_{\gamma_k}^d$, $k = 1, \dots, N$, such that $U_k \cap \Gamma_1 \neq \emptyset$ and $U_k \cap \Gamma_2 = \emptyset$ for $k = 1, \dots, N_1$ as well as $U_k \cap \Gamma_1 = \emptyset$ and $U_k \cap \Gamma_2 \neq \emptyset$ for $k = N_1 + 1, \dots, N$.

We show that

$$(\lambda - \operatorname{div}(\nu \nabla \cdot) + \nabla P) R_\lambda f = f + S_\lambda f, \quad (6.1)$$

$$R_\lambda f|_{\Gamma_1} = 0, \quad (6.2)$$

$$T'_1 R_\lambda f|_{\Gamma_2} = 0 + S'_\lambda f, \quad (6.3)$$

where Pv is defined as solution of (1.8)-(1.9) and

$$\|S_\lambda f\|_{L^q(\Omega)} + \|S'_\lambda f\|_{W_q^{1-\frac{1}{q}}(\Gamma_2)} + \langle \lambda \rangle^{\frac{1}{2}-\frac{1}{2q}} \|S'_\lambda f\|_{L^q(\Gamma_2)} \leq C_{\delta, q} \langle \lambda \rangle^{-\varepsilon} \|f\|_{L^q(\Omega)} \quad (6.4)$$

uniformly in $\lambda \in \Sigma_\delta$, $f \in L^q(\Omega)^d$. First of all, using Theorem 5.1, it is easy to check that

$$(\lambda - \operatorname{div}(\nu \nabla \cdot)) R_\lambda f + \nabla G_\lambda f = f + S_\lambda f$$

for some S_λ satisfying the same estimate as in (6.4) and

$$G_\lambda f = \sum_{j=1}^N \psi_j G_{\gamma_j, \lambda} \varphi_j f.$$

Here we note that all perturbation terms due to differentiation of the cut-off functions φ_j, ψ_j decay of order at least $\langle \lambda \rangle^{-\frac{1}{2}}$ due to (5.8)-(5.9). Moreover, (6.2)-(6.3) together

with the corresponding estimate in (6.4) are proved in a straight forward manner using Theorem 5.1 again. As mentioned in Remark 5.2 above, each $G_{\gamma_j, \lambda}$ represents the principal of $PR_{\gamma_j, \lambda}$ on $\mathbb{R}_{\gamma_j}^d$. In the same way G_λ represents the principal part of PR_λ on Ω . More precisely, we will show that

$$\|\nabla PR_\lambda f - \nabla G_\lambda f\|_{L^q(\Omega)} \leq C_{q, \delta}(1 + |\lambda|)^{-\varepsilon} \|f\|_{L^q(\Omega)}$$

for all $f \in L^q(\Omega)^d$, $\lambda \in \Sigma_\delta$ and some $\varepsilon > 0$. This is the most important step in the proof of Theorem 1.3. By duality, it is enough to show that for any $f \in L^q(\Omega)^d$ and any $u \in L^{q'}(\Omega)^d$, we have

$$|(\nabla PR_\lambda f - \nabla G_\lambda f, u)_\Omega| \leq C_{q, \delta}(1 + |\lambda|)^{-\varepsilon} \|f\|_q \|u\|_{q'}. \quad (6.5)$$

To show this, we use the Helmholtz decomposition for any $u \in L^{q'}(\Omega)^d$ according to (A2), i.e., $u = u_0 + \nabla p$ where $u_0 \in J_{q'}(\Omega)$ and $p \in \dot{W}_{q', \Gamma_2}^1(\Omega)$. Here p can be decomposed by the assumption (A3) as $p = p_1 + p_2$ where $p_1 \in W_{q', \Gamma_2}^1(\Omega)$, $p_2 \in \dot{W}_{q', \Gamma_2}^1(\Omega)$ with $\nabla p_2 \in W_{q'}^1(\Omega)$. Thus we have a decomposition of any $u \in L^{q'}(\Omega)^d$ such that $u = u_0 + \nabla p_1 + \nabla p_2$ where u_0, p_1, p_2 satisfy the conditions above. We estimate the left-hand side of (6.5) using this decomposition and estimating each term separately, which will be called first, second and third part below.

For the first part, we have

$$\begin{aligned} & (\nabla P(\sum_{j=1}^N \psi_j R_{\gamma_j, \lambda} \varphi_j f) - \nabla(\sum_{j=1}^N \psi_j G_{\gamma_j, \lambda} \varphi_j f), u_0)_\Omega \\ &= (P(\sum_{j=1}^N \psi_j R_{\gamma_j, \lambda} \varphi_j f) - \sum_{j=1}^N \psi_j G_{\gamma_j, \lambda} \varphi_j f, \gamma_n u_0)_{\Gamma_2} \\ &= (2\nu \partial_n(\sum_{j=N_1+1}^N \psi_j R_{\gamma_j, \lambda} \varphi_j f)_n|_{\Gamma_2} - 2 \sum_{j=1}^N \psi_j \nu (\partial_n R_{\gamma_j, \lambda} \varphi_j f)_n|_{\Gamma_2} - S''_\lambda f, \gamma_n u_0)_{\Gamma_2} \\ &= (2\nu \sum_{j=N_1+1}^N ((\partial_n \psi_j) R_{\gamma_j, \lambda} \varphi_j f)_n|_{\partial \mathbb{R}_{\gamma_j}^d} - S''_\lambda f, \gamma_\nu u_0)_{\Gamma_2}, \end{aligned} \quad (6.6)$$

where

$$\begin{aligned} \|2\nu (R_{\gamma_j, \lambda} \varphi_j f)_n\|_{W_q^{1-\frac{1}{q}}(\partial \mathbb{R}_{\gamma_j}^d)} &\leq C_{q, \delta} \langle \lambda \rangle^{-\frac{1}{2}} \|f\|_q \quad \text{and} \\ |(S''_\lambda f, \gamma_\nu u_0)_{\Gamma_2}| &\leq C_{q, \delta} \langle \lambda \rangle^{-\varepsilon} \|f\|_q \|u\|_{q'} \end{aligned}$$

because of Theorem 5.1. Hence the absolute value of (6.6) is estimated from above by $C_{q, \delta}(1 + |\lambda|)^{-\varepsilon} \|f\|_q \|u\|_{q'}$ for some $\varepsilon > 0$.

For the second part, we split it further into the Dirichlet and Neumann parts. Here Dirichlet part means that the boundary condition (3.5) is present on that part

of the boundary and Neumann part refers to (3.6). For the Dirichlet part, we have

$$\begin{aligned}
& (\nabla P(\sum_{j=1}^{N_1} \psi_j R_{\gamma_j, \lambda} \varphi_j f) - \nabla(\sum_{j=1}^{N_1} \psi_j G_{\gamma_j, \lambda} \varphi_j f), \nabla p_1)_\Omega \\
&= (\nu(\Delta - \nabla \operatorname{div})(\sum_{j=1}^{N_1} \psi_j R_{\gamma_j, \lambda} \varphi_j f), \nabla p_1)_\Omega - \sum_{j=1}^{N_1} (G_{\gamma_j, \lambda} \varphi_j f, \nabla \psi_j \cdot \nabla p_1)_{\mathbb{R}_{\gamma_j}^d} \\
&\quad - \sum_{j=1}^{N_1} (\nabla G_{\gamma_j, \lambda} \varphi_j f, \nabla(\psi_j p_1))_{\mathbb{R}_{\gamma_j}^d} + \sum_{j=1}^{N_1} (\nabla G_{\gamma_j, \lambda} \varphi_j f, \nabla(\psi_j) p_1)_{\mathbb{R}_{\gamma_j}^d} \\
&= (\nu(\Delta - \nabla \operatorname{div})(\sum_{j=1}^{N_1} \psi_j R_{\gamma_j, \lambda} \varphi_j f), \nabla p_1)_\Omega \\
&\quad - \sum_{j=1}^{N_1} (\nu(\Delta - \nabla \operatorname{div}) R_{\gamma_j, \lambda} \varphi_j f, \nabla(\psi_j p_1))_{\mathbb{R}_{\gamma_j}^d} - \sum_{j=1}^{N_1} \langle S'_{0, \lambda} \varphi_j f, \psi_j p_1 \rangle_{W_{q, 0}^{-1}, W_{q'}^1} \\
&\quad - \sum_{j=1}^{N_1} (G_{\gamma_j, \lambda} \varphi_j f, \nabla \psi_j \cdot \nabla p_1)_{\mathbb{R}_{\gamma_j}^d} + \sum_{j=1}^{N_1} (\nabla G_{\gamma_j, \lambda} \varphi_j f, (\nabla \psi_j) p_1)_{\mathbb{R}_{\gamma_j}^d} \tag{6.7}
\end{aligned}$$

For the first term of (6.7), we use

$$\begin{aligned}
& \sum_{j=1}^{N_1} (\nu(\Delta - \nabla \operatorname{div}) \psi_j R_{\gamma_j, \lambda} \varphi_j f, \nabla p_1)_\Omega \\
&= \sum_{j=1}^{N_1} (\nu \psi_j (\Delta - \nabla \operatorname{div}) R_{\gamma_j, \lambda} \varphi_j f, \nabla p_1)_{\mathbb{R}_{\gamma_j}^d} + \sum_{j=1}^{N_1} (\nu [\Delta - \nabla \operatorname{div}, \psi_j] R_{\gamma_j, \lambda} \varphi_j f, \nabla p_1)_{\mathbb{R}_{\gamma_j}^d} \\
&= \sum_{j=1}^{N_1} (\nu(\Delta - \nabla \operatorname{div}) R_{\gamma_j, \lambda} \varphi_j f, \nabla(\psi_j p_1))_{\mathbb{R}_{\gamma_j}^d} \\
&\quad - \sum_{j=1}^{N_1} (\nu(\Delta - \nabla \operatorname{div}) \psi_j R_{\gamma_j, \lambda} \varphi_j f, (\nabla \psi_j) p_1)_{\mathbb{R}_{\gamma_j}^d} + \sum_{j=1}^{N_1} (S_j R_{\gamma_j, \lambda} \varphi_j f, \nabla p_1)_{\mathbb{R}_{\gamma_j}^d} \tag{6.8}
\end{aligned}$$

where $S_j = \nu[\Delta - \nabla \operatorname{div}, \psi_j]$. If we put (6.8) into (6.7), the first term of (6.8) cancels with the second term of (6.7).

For the estimate of the second term of (6.8), one uses the following estimate,

$$\begin{aligned}
& \|\nu(\Delta - \nabla \operatorname{div}) R_{\gamma_j, \lambda} \varphi_j f\|_{W_q^{-\varepsilon}(\Omega)} \leq C_{q, \delta} \|R_{\gamma_j, \lambda} \varphi_j f\|_{W_q^{2-\varepsilon}(\mathbb{R}_{\gamma_j}^d)} \\
& \leq C_{q, \delta} (1 + |\lambda|)^{-\frac{\varepsilon}{2}} \|\varphi_j f\|_{L^q(\mathbb{R}_{\gamma_j}^d)} \leq C_{q, \delta} (1 + |\lambda|)^{-\frac{\varepsilon}{2}} \|f\|_{L^q(\Omega)},
\end{aligned}$$

where $0 < \varepsilon < 1$, together with the embedding $W_q^\varepsilon(\Omega) \hookrightarrow W_q^1(\Omega)$ for $0 < \varepsilon < 1$ and the fact that the dual of $W_q^s(\Omega)$ is $W_{q'}^{-s}(\Omega)$ for all $s \in (-\frac{1}{q'}, \frac{1}{q})$.

Since the commutator $S_j = [\Delta - \nabla \operatorname{div}, \psi_j]$ is the differential operator of order 1, we have for the third term in (6.8) $\|S_j R_{\gamma_j, \lambda} \varphi_j f\|_{L^q(\mathbb{R}_{\gamma_j}^d)} \leq C_{q, \delta} (1 + |\lambda|)^{-\frac{1}{2}} \|f\|_q$.

The remaining terms, which contain the operator $G_{\gamma_j, \lambda}$, can be estimated using similar arguments. Hence the absolute value of (6.7) is estimated from above by $C_{q, \delta} (1 + |\lambda|)^{-\varepsilon} \|f\|_q \|u\|_{q'}$ for some $\varepsilon > 0$.

For the Neumann part, we have

$$\begin{aligned}
& (\nabla P(\sum_{j=N_1+1}^N \psi_j R_{\gamma_j, \lambda} \varphi_j f) - \nabla(\sum_{j=N_1+1}^N \psi_j G_{\gamma_j, \lambda} \phi_j f), \nabla p_1)_\Omega \\
&= (\nu(\Delta - \nabla \operatorname{div})(\sum_{j=N_1+1}^N \psi_j R_{\gamma_j, \lambda} \varphi_j f), \nabla p_1)_\Omega - \sum_{j=N_1+1}^N (G_{\gamma_j, \lambda} \varphi_j f, \nabla \psi_j \cdot \nabla p_1)_{\mathbb{R}_{\gamma_j}^d} \\
&\quad - \sum_{j=N_1+1}^N (\nabla G_{\gamma_j, \lambda} \varphi_j f, \nabla(\psi_j p_1))_{\mathbb{R}_{\gamma_j}^d} + \sum_{j=N_1+1}^N (\nabla G_{\gamma_j, \lambda} \varphi_j f, (\nabla \psi_j) p_1)_{\mathbb{R}_{\gamma_j}^d} \\
&= (\nu(\Delta - \nabla \operatorname{div})(\sum_{j=N_1+1}^N \psi_j R_{\gamma_j, \lambda} \varphi_j f), \nabla p_1)_\Omega - \sum_{j=N_1+1}^N (G_{\gamma_j, \lambda} \varphi_j f, \nabla \psi_j \cdot \nabla p_1)_{\mathbb{R}_{\gamma_j}^d} \\
&\quad - \sum_{j=N_1+1}^N (\nu(\Delta - \nabla \operatorname{div}) R_{\gamma_j, \lambda} \varphi_j f + S'_{1, \lambda} \varphi_j f, \nabla(\psi_j p_1))_{\mathbb{R}_{\gamma_j}^d} \\
&\quad + \sum_{j=N_1+1}^N (\nabla G_{\gamma_j, \lambda} \varphi_j f, (\nabla \psi_j) p_1)_{\mathbb{R}_{\gamma_j}^d}. \tag{6.9}
\end{aligned}$$

The sum of the first and the third term of (6.9) can be treated as in the Dirichlet case and yields the lower order term. The estimate of the other terms are also as similar as the Dirichlet case.

Hence the absolute value of (6.9) is estimated from above by $C_{q, \delta} (1 + |\lambda|)^{-\varepsilon} \|f\|_q \|u\|_{q'}$ for some $\varepsilon > 0$.

For the third part, we can treat the Dirichlet and Neumann parts in the same way. We have

$$\begin{aligned}
& (\nabla P(\sum_{j=1}^N \psi_j R_{\gamma_j, \lambda} \varphi_j f) - \nabla(\sum_{j=1}^N \psi_j G_{\gamma_j, \lambda} \phi_j f), \nabla p_2)_\Omega \\
&= (\nu(\Delta - \nabla \operatorname{div})(\sum_{j=1}^N \psi_j R_{\gamma_j, \lambda} \varphi_j f), \nabla p_2)_\Omega - (\nabla(\sum_{j=1}^N \psi_j G_{\gamma_j, \lambda} \phi_j f), \nabla p_2)_\Omega
\end{aligned} \tag{6.10}$$

For the estimate of the first term of the right-hand side of (6.10), one uses the following estimate

$$\begin{aligned}
& \|(\Delta - \nabla \operatorname{div}) \psi_j R_{\gamma_j, \lambda} \varphi_j f\|_{W_q^{-\varepsilon}(\Omega)} \leq C_{q, \delta} \|\psi_j R_{\gamma_j, \lambda} \varphi_j f\|_{W_q^{2-\varepsilon}(\Omega)} \\
& \leq C_{q, \delta} \|R_{\gamma_j, \lambda} \varphi_j f\|_{W_q^{2-\varepsilon}(\mathbb{R}_{\gamma_j}^d)} \leq C_{q, \delta} \langle \lambda \rangle^{-\frac{\varepsilon}{2}} \|\varphi_j f\|_{L^q(\mathbb{R}_{\gamma_j}^d)} \leq C_{q, \delta} \langle \lambda \rangle^{-\frac{\varepsilon}{2}} \|f\|_{L^q(\Omega)},
\end{aligned}$$

where $0 < \varepsilon < 1$, together with the embedding $W_q^\varepsilon(\Omega) \hookrightarrow W_q^1(\Omega)$ for $0 < \varepsilon < 1$ and the fact that the dual of $W_q^s(\Omega)$ is $W_{q'}^{-s}(\Omega)$ for all $s \in (-\frac{1}{q'}, \frac{1}{q})$. The second term of the right-hand side of (6.10) can be estimated in the same way as the first term. Thus, combining the previous estimates, we have shown (6.5).

Next let $E: W_q^{1-\frac{1}{q}}(\Gamma_2)^d \rightarrow W_q^2(\Omega)^d$ be a bounded operator such that $Ea|_{\Gamma_1} = 0$ and $T_1' Ea|_{\Gamma_2} = a$ as well as

$$\langle \lambda \rangle \|Ea\|_{L^q(\Omega)} + \|\nabla^2 Ea\|_{L^q(\Omega)} \leq C \left(\|a\|_{W_q^{1-\frac{1}{q}}(\Gamma_2)} + \langle \lambda \rangle^{\frac{1}{2}-\frac{1}{2q}} \|a\|_{L^q(\Gamma_2)} \right).$$

We note that the existence of such an operator follows from Lemma 4.7. Hence

$$\tilde{R}_\lambda f = R_\lambda f - ES'_\lambda f$$

satisfies

$$(\lambda - \operatorname{div}(\nu \nabla \cdot) + \nabla P) \tilde{R}_\lambda f = f + S_\lambda f,$$

as well as $\tilde{R}_\lambda f|_{\Gamma_1} = T_1' \tilde{R}_\lambda f|_{\Gamma_2} = 0$, where S_λ satisfies the estimate as in (6.4).

Since $S_\lambda \rightarrow 0$ in $\mathcal{L}(L^q(\Omega)^d)$ as $|\lambda| \rightarrow \infty$, $\lambda \in \Sigma_\delta$, there is some $R > 0$ such that $(I + S_\lambda)^{-1}$ exists for all $\lambda \in \Sigma_\delta$ with $|\lambda| \geq R$. Moreover,

$$(I + S_\lambda)^{-1} = I + S'_\lambda \quad \text{with } \|S'_\lambda\|_{\mathcal{L}(L^q(\Omega))} \leq C(1 + |\lambda|)^{-\varepsilon} \quad (6.11)$$

by a standard Neumann series argument. If we substitute f by $(I + S_\lambda)^{-1}f$ in the equation, we have $(\lambda + A_q) \tilde{R}_\lambda (I + S_\lambda)^{-1}f = f$ with $\tilde{R}_\lambda (I + S_\lambda)^{-1}f|_{\Gamma_1} = 0$ and $T_1' R_\lambda (I + S_\lambda)^{-1}f|_{\Gamma_2} = 0$. Hence there exists $R > 0$ such that $(\lambda + A_q)$ is surjective for all $\lambda \in \Sigma_\delta$ with $|\lambda| \geq R$. Hence, if we show that there exists R' such that $\mathcal{N}(\lambda + A_q) = 0$ for $\lambda \in \Sigma_\delta$ with $|\lambda| \geq R'$, we know that $\lambda + A_q$ is bijective for $\lambda \in \Sigma_\delta$ with $|\lambda| \geq \max(R, R')$. We need the following lemma.

Lemma 6.1 *Let $\Omega \subseteq \mathbb{R}^d$, $d \geq 2$ and $1 < q < \infty$ be as in Assumption 1.1. If $\lambda + A_{q'}$ is surjective for a certain range of $\lambda \in \mathbb{C} \setminus (-\infty, 0]$, then there is no non-trivial solution of (1.5) for the same range of λ .*

Proof: Let $f \in L^{q'}(\Omega)^d$ be arbitrary and let $u \in \mathcal{D}(A_{q'})$ such that $(\lambda + A_{q'})u = f$. Then, multiplying f with ∇g , we observe that $\operatorname{div} u \in W_{q'}^1(\Omega)$, $\operatorname{div} u|_{\Gamma_2} = 0$ solves

$$-\lambda(\operatorname{div} u, g) - (\nu \nabla \operatorname{div} u, \nabla g) = (f, \nabla g)$$

for all $g \in W_{q, \Gamma_2}^1(\Omega)$. Hence, if $g \in W_{q, \Gamma_2}^1(\Omega)$ solves (1.5), then $(f, \nabla g) = 0$ for all $f \in L^{q'}(\Omega)^d$ and therefore $\nabla g = 0$. Since $\lambda \neq 0$, we get from (1.5) that $g = 0$. ■

Proof of Theorem 1.3: From the arguments above we know that $\lambda + A_s$ for $s = q, q'$ is surjective for $|\lambda| \geq R'$ with $\lambda \in \Sigma_\delta$ for some $R' > 0$.

In order to show existence of $\lambda + A_q$ for large λ , it remains to prove $\mathcal{N}(\lambda + A_q) = 0$. Using the above lemma, we can conclude that there is no non-trivial solution of (1.5)

for the same range of λ as before. Now let $u \in \mathcal{N}(\lambda + A_q)$ where $|\lambda| \geq R'$ and $\lambda \in \Sigma_\delta$. Then we can apply Lemma 3.2 with $f = g = a = \tilde{p} = 0$ to conclude that u solves (1.1)-(1.4) with right-hand side zero. In particular, this implies $\operatorname{div} u = 0$. In order to show $u = 0$, let $f \in L^{q'}(\Omega)^d$ be arbitrary and let $|\lambda| \geq R'$ with $\lambda \in \Sigma_\delta$. Let $v \in \mathcal{D}(A_{q'})$ with $(\lambda + A_{q'})v = f$. Then

$$(u, f)_\Omega = (u, (\lambda + A_{q'})v)_\Omega = \lambda(u, v)_\Omega + (2\nu Du, Dv)_\Omega = ((\lambda + A_q)u, v)_\Omega = 0$$

because of (1.10). Since $f \in L^{q'}(\Omega)^d$ is arbitrary, we get $u = 0$. This shows the existence of $(\lambda + A_q)^{-1}$ for $|\lambda| \geq R$, $\lambda \in \Sigma_\delta$. Moreover, because of (6.11),

$$(\lambda + A_q)^{-1} = R_\lambda + S''_\lambda,$$

where $\|S''_\lambda\|_{\mathcal{L}(L^q(\Omega))} \leq C\langle\lambda\rangle^{-1-\varepsilon}$ for some $\varepsilon > 0$. Therefore (1.11) follows from (5.8) and (1.12) follows from (5.10).

Finally, the existence of $h(c + A_q)$ if $c + \Sigma_{\delta'} \subset \rho(-A_q)$ and the corresponding estimate (1.14) follows easily from (1.11) and (1.12) using that $(\lambda + A_q)^{-1}$ is uniformly bounded on compact subsets of $\rho(-A_q)$ and a simple shift of the contour. This completes the proof. \blacksquare

7 Proof of Theorem 1.4

Let us assume that $\Omega \subset \mathbb{R}^d$ is bounded. Then we know that there exists $(\lambda + A_q)^{-1}$ for any $\lambda \in \Sigma_\delta$ such that $|\lambda| \geq R$, where R is a sufficiently large number. Let $\lambda_0 \in \Sigma_\delta$ be such that $(\lambda_0 + A_q)^{-1}$ exists. Then we have

$$\begin{aligned} & (\lambda + A_q)(\lambda_0 + A_q)^{-1}f \\ &= \{(\lambda - \lambda_0) + (\lambda_0 + A_q)\}(\lambda_0 + A_q)^{-1}f = (\lambda - \lambda_0)(\lambda_0 + A_q)^{-1}f + f \end{aligned}$$

for any $\lambda \in \mathbb{C}$. By Rellich's compactness theorem, we know that the operator $(\lambda - \lambda_0)(\lambda_0 + A_q)^{-1}$ is compact. Hence we know that $\mathcal{R}(\lambda + A_q)$ has finite co-dimensions for any $\lambda \in \mathbb{C}$. Thus $\lambda + A_q$ is a semi-Fredholm operator for any $\lambda \in \mathbb{C}$. We know also that $(\lambda + A_q)^{-1}$ exists for a certain range of $\lambda \in \mathbb{C}$ as mentioned above. So, using the local invariance of the index of a family of the semi-Fredholm operators, we have $\operatorname{ind}(\lambda + A_q) = 0$ for any $\lambda \in \mathbb{C}$. To show the existence of the inverse of $\lambda + A_q$ for any $\lambda \in \mathbb{C} \setminus (-\infty, 0]$, we only have to show that $\mathcal{N}(\lambda + A_q) = \{0\}$ for the same range of λ . Moreover, we show that 0 is in the resolvent of A_q if $\Gamma_1 \neq \emptyset$.

First let $q = 2$. Then (A4) is satisfied for any $\lambda \in \mathbb{C} \setminus (-\infty, 0]$. Hence we can apply Lemma 3.2 with $f = g = a = \tilde{p} = 0$ to conclude $\operatorname{div} v = 0$ for any $v \in \mathcal{N}(\lambda + A_2)$ and $\lambda \in \mathbb{C} \setminus (-\infty, 0]$. Moreover, if $\lambda = 0$, then (1.5) for $g \in W_2^1(\Omega)$ implies $g \equiv \text{const}$. Therefore $\operatorname{div} v \equiv \text{const}$ for all $v \in \mathcal{N}(A_2)$. Moreover, if $\Gamma_2 \neq \emptyset$, then $\operatorname{div} v|_{\Gamma_2} = 0$ implies $\operatorname{div} v = 0$. Finally, if $\Gamma_2 = \emptyset$, then $\int_\Omega \operatorname{div} v \, dx = \int_{\partial\Omega} v \, d\sigma = 0$, which implies $\operatorname{div} v = 0$ again.

Using $\operatorname{div} v = 0$ for all $v \in \mathcal{N}(\lambda + A_2)$, we conclude further

$$0 = (\lambda v + A_2 v, v)_\Omega = \lambda(v, v)_\Omega + (2\nu Dv, Dv)_\Omega$$

because of (1.10). If $\lambda \in \mathbb{C} \setminus (-\infty, 0]$, then one derives $v = 0$ directly. If $\lambda = 0$ and $\Gamma_1 \neq \emptyset$, one also gets $v = 0$ by Korn's inequality.

Next we consider the case $q > 2$. Since $W_q^2(\Omega) \hookrightarrow H^2(\Omega)$, it follows that $\mathcal{N}(\lambda + A_q) \subseteq \mathcal{N}(\lambda + A_2) = \{0\}$ for all $\lambda \in \mathbb{C} \setminus (-\infty, 0]$ and $\lambda = 0$ if $\Gamma_1 \neq \emptyset$.

Finally, let $1 < q < 2$ and let $u \in \mathcal{N}(\lambda + A_q)$. Then we have

$$\begin{aligned} 0 &= (\lambda v - \operatorname{div}(\nu \nabla v^T) + \nabla \nu \cdot \nabla v^T + \nabla P v, \nabla g) \\ &= -(\lambda \operatorname{div} v, g) - (\nabla v, \nabla v \otimes \nabla g) - (\nu \Delta v, \nabla g) + (\nu(\Delta - \nabla \operatorname{div})v, \nabla g) \\ &\quad + (Dv, 2\nabla \nu \otimes \nabla g) - (\nabla \nu \cdot \nabla v^T, \nabla g) \\ &= -(\lambda \operatorname{div} v, g) - (\nu \nabla \operatorname{div} v, \nabla g) \end{aligned}$$

for any $g \in W_{q'}^1(\Omega)$, $g|_{\Gamma_2} = 0$. Because of $\mathcal{R}(\lambda + A_{q'}) = L^{q'}(\Omega)^d$ if $\lambda \in \mathbb{C} \setminus (-\infty, 0]$, we can apply Lemma 6.1 to derive $\operatorname{div} v = 0$. If $\lambda = 0$ and $\Gamma_1 \neq \emptyset$, then the arguments in the proof of Lemma 6.1 show $\nabla \operatorname{div} v = 0$. From this one derives $\operatorname{div} v = 0$ in the same way as in the case $q = 2$. Now let $f \in L^{q'}(\Omega)^d$ and let $v := (\lambda + A_{q'})^{-1}f$, where $\lambda \in \mathbb{C} \setminus (-\infty, 0]$ or $\lambda = 0$ if $\Gamma_1 \neq \emptyset$. – Here we use that the theorem is already proved for the case $q \geq 2$. – Then

$$(u, f)_\Omega = (u, (\lambda + A_{q'})v)_\Omega = \lambda(u, v)_\Omega + (2\nu Du, Dv)_\Omega = ((\lambda + A_q)u, v)_\Omega = 0$$

due to (1.10). Since $f \in L^{q'}(\Omega)^d$ is arbitrary, we get $u = 0$ if $\lambda \in \mathbb{C} \setminus (-\infty, 0]$ or if $\lambda = 0$ and $\Gamma_1 \neq \emptyset$. This completes the proof.

References

- [1] T. Abe. On a resolvent estimate of the Stokes equation with Neumann-Dirichlet-type boundary condition on an infinite layer. *Math. Methods Appl. Sci.*, 27(9):1007–1048, 2004.
- [2] T. Abe and Y. Shibata. On a resolvent estimate of the Stokes equation on an infinite layer. *J. Math. Soc. Japan* 55, No. 2, 469–497, 2003.
- [3] T. Abe and Y. Shibata. On a resolvent estimate of the Stokes equation on an infinite layer, part 2, $\lambda = 0$ case. *J. Math. Fluid Mech.* 5, 245–274, 2003.
- [4] H. Abels. On a diffuse interface model for two-phase flows of viscous, incompressible fluids with matched densities. *Arch. Rat. Mech. Anal.*, DOI 10.1007/s00205-008-0160-2.
- [5] H. Abels. Bounded imaginary powers of the Stokes operator in an infinite layer. *J. Evol. Eq.*, 2:439–457, 2002.

- [6] H. Abels. *Stokes Equations in Asymptotically Flat Domains and the Motion of a Free Surface*. PhD thesis, TU Darmstadt, Shaker Verlag, Aachen, 2003.
- [7] H. Abels. Bounded imaginary powers and H_∞ -calculus of the Stokes operator in two-dimensional exterior domains. *Math. Z.*, 251(3):589–605, 2005.
- [8] H. Abels. Bounded imaginary powers and H_∞ -calculus of the Stokes operator in unbounded domains. In *Nonlinear elliptic and parabolic problems*, volume 64 of *Progr. Nonlinear Differential Equations Appl.*, pages 1–15. Birkhäuser, Basel, 2005.
- [9] H. Abels. Pseudodifferential boundary value problems with non-smooth coefficients. *Comm. Part. Diff. Eq.*, 30:1463–1503, 2005.
- [10] H. Abels. Reduced and generalized Stokes resolvent equations in asymptotically flat layers, part I: unique solvability. *J. Math. Fluid. Mech.* 7, 201-222, 2005.
- [11] H. Abels. Reduced and generalized Stokes resolvent equations in asymptotically flat layers, part II: H_∞ -calculus. *J. Math. Fluid. Mech.* 7, 223-260, 2005.
- [12] H. Abels. Generalized Stokes resolvent equations in an infinite layer with mixed boundary conditions. *Math. Nachr.* 279, No. 4, 1-17, 2006.
- [13] H. Abels. Diffuse interface models for two-phase flows of viscous incompressible fluids. *Lecture Notes, Max Planck Institute for Mathematics in the Sciences*, No. 36/2007, 2007.
- [14] H. Abels and M. Wiegner. *Resolvent estimates for the Stokes operator on an infinite layer*. *Diff. Int. Eq.* 18 No. 10, 1081-1110, 2005.
- [15] R. A. Adams. *Sobolev Spaces*. Academic Press, New York, San Francisco, London, 1975.
- [16] H. Amann. Operator-valued fourier multipliers, vector-valued besov spaces, and applications. *Math. Nachr.*, 186:5–56, 1997.
- [17] J. Bergh and J. Löfström. *Interpolation Spaces*. Springer, Berlin - Heidelberg - New York, 1976.
- [18] W. Borchers and H. Sohr. *On the semigroup of the Stokes operator for exterior domains in L^q -spaces*. *Math. Z.* 196, 415-425, 1987.
- [19] W. Borchers and W. Varnhorn. *On the boundedness of the Stokes semigroup in two-dimensional exterior domains*. *Math. Z.* 213, 275-299, 1993.
- [20] D. Bothe and J. Prüss. L_P -theory for a class of non-Newtonian fluids. *SIAM J. Math. Anal.*, 39(2):379–421 (electronic), 2007.

- [21] S.K. Chua. *Extension theorems on weighted Sobolev space*. Indiana Univ. Math. J., 41, 1027-1076, 1992.
- [22] R. Danchin. Density-dependent incompressible fluids in bounded domains. *J. Math. Fluid Mech.*, 8(3):333–381, 2006.
- [23] L. Boutet de Monvel. *Boundary problems for pseudo-differential operators*. Acta Math. 126, 11-51, 1971.
- [24] R. Denk, M. Hieber, and J. Prüss. \mathcal{R} -boundedness, Fourier multipliers and problems of elliptic and parabolic type. *Mem. Amer. Math. Soc.*, 166(788):viii+114, 2003.
- [25] G. Dore and A. Venni. On the closedness of the sum of two closed operators. *Math. Z.*, 196:189–201, 1987.
- [26] R. Farwig. *Weighted L^q -Helmholtz decompositions in infinite cylinders and in infinite layers*. Adv. Diff. Eq. 8, 357-384, 2003.
- [27] R. Farwig, H. Kozono, and H. Sohr. An L^q -approach to Stokes and Navier-Stokes equations in general domains. *Acta Math.*, 195:21–53, 2005.
- [28] R. Farwig and M.-H. Ri. The resolvent problem and H^∞ -calculus of the Stokes operator in unbounded cylinders with several exits to infinity. *J. Evol. Equ.*, 7(3):497–528, 2007.
- [29] R. Farwig and M.-H. Ri. Stokes resolvent systems in an infinite cylinder. *Math. Nachr.*, 280(9-10):1061–1082, 2007.
- [30] R. Farwig and H. Sohr. *Generalized resolvent estimates for the Stokes system in bounded and unbounded domains*. J. Math. Soc. Japan 46, No. 4, 607-643, 1994.
- [31] R. Farwig and H. Sohr. *Helmholtz Decomposition and Stokes Resolvent System for Aperture Domains in L^q -Spaces*. Analysis 16, 1-26, 1996.
- [32] Y. Giga. *Analyticity of the semigroup generated by the Stokes operator in L_r spaces*. Math. Z. 178, 297-329, 1981.
- [33] Y. Giga. *Domains of fractional powers of the Stokes operator in L_r Spaces*. Arch. Rat. Mech. Anal. 89, 251-265, 1985.
- [34] Y. Giga and H. Sohr. On the Stokes operator in exterior domains. *J. Fac. Sci. Univ. Tokyo Sect. IA Math.*, 36(1):103–130, 1989.
- [35] Y. Giga and H. Sohr. *Abstract L^p estimates for the Cauchy problem with applications to the Navier-Stokes equations in exterior domains*. J. Funct. Anal. 102, 72-94, 1991.

- [36] G. Grubb. *Pseudo-differential boundary problems in L_p spaces*. Comm. Part. Diff. Eq. 15, 289-340, 1990.
- [37] G. Grubb. *Functional Calculus of Pseudodifferential Boundary Problems, 2nd Edition*. Birkhäuser, Basel - Boston - Berlin, 1996.
- [38] G. Grubb and N. J. Kokholm. *A global calculus of parameter-dependent pseudodifferential boundary problems in L_p Sobolev spaces*. Acta Math., Vol. 171, No. 2, 165-229, 1993.
- [39] G. Grubb and V. A. Solonnikov. Boundary value problems for the nonstationary navier-stokes equations treated by pseudo-differential methods. *Math. Scand.*, 69:217-290, 1991.
- [40] J. Málek, J. Nečas, M. Rokyta and M. Ružička. *Weak and measure-valued solutions to evolutionary PDEs*. Applied Mathematics and Mathematical Computation. 13. London: Chapman & Hall. vii, 317 p., 1996.
- [41] H. Kumano-Go and M. Nagase. *Pseudo-differential operators with non-regular symbols and applications*. Funkcial Ekvac. 21, 151-192, 1978.
- [42] O. A. Ladyženskaja and V. A. Solonnikov. The unique solvability of an initial-boundary value problem for viscous incompressible inhomogeneous fluids. *Zap. Naučn. Sem. Leningrad. Otdel. Mat. Inst. Steklov. (LOMI)*, 52:52-109, 218-219, 1975. Boundary value problems of mathematical physics, and related questions of the theory of functions, 8.
- [43] J. Marschall. Pseudodifferential operators with coefficients in Sobolev spaces. *Trans. Amer. Math. Soc.*, 307(1):335-361, 1988.
- [44] A. McIntosh. *Operators which have an H_∞ -calculus*. In "Miniconference on Operator Theory and Partial Differential Equations", B. Jefferies, A. McIntosh, W. Ricker, editors Proc. Center Math. Anal. A.N.U., 14, 210-231, 1986.
- [45] T. Miyakawa. *The Helmholtz decomposition of vector fields in some unbounded domains*. Math. J. Toyama Univ. 17, 115-149, 1994.
- [46] A. Noll and J. Saal. *H^∞ -calculus for the Stokes operator on L_q -spaces*. Math. Z. 244, 651-688, 2003.
- [47] K. Schumacher. A chart preserving the normal vector and extensions of normal derivatives in weighted function. *Preprint, TU Darmstadt, No. 2510*, 2007.
- [48] C. G. Simader and H. Sohr. A new approach to the Helmholtz decomposition and the Neumann problem in L^q -spaces for bounded and exterior domains. In *Mathematical problems relating to the Navier-Stokes equation*, volume 11 of *Ser. Adv. Math. Appl. Sci.*, pages 1-35. World Sci. Publ., River Edge, NJ, 1992.

- [49] V. A. Solonnikov. L_p -estimates for solutions to the initial boundary-value problem for the generalized Stokes system in a bounded domain. *J. Math. Sci. (New York)*, 105(5):2448–2484, 2001. Function theory and partial differential equations.
- [50] V. A. Solonnikov. Estimates of the solution of model evolution generalized Stokes problem in weighted Hölder spaces. *Zap. Nauchn. Sem. S.-Peterburg. Otdel. Mat. Inst. Steklov. (POMI)*, 336(Kraev. Zadachi Mat. Fiz. i Smezh. Vopr. Teor. Funkts. 37):211–238, 277, 2006.
- [51] H. Triebel. *Interpolation Theory, Function Spaces, Differential Operators*. North-Holland Publishing Company, Amsterdam, New York, Oxford, 1978.

Helmut Abels

Max Planck Institute for Mathematics in the Sciences
Inselstr. 22
04103 Leipzig
Germany
abels@mis.mpg.de

Yutaka Terasawa

Department of Mathematics
Hokkaido University
Kita, Sapporo, Hokkaido 060 Japan
yutaka@math.sci.hokudai.ac.jp